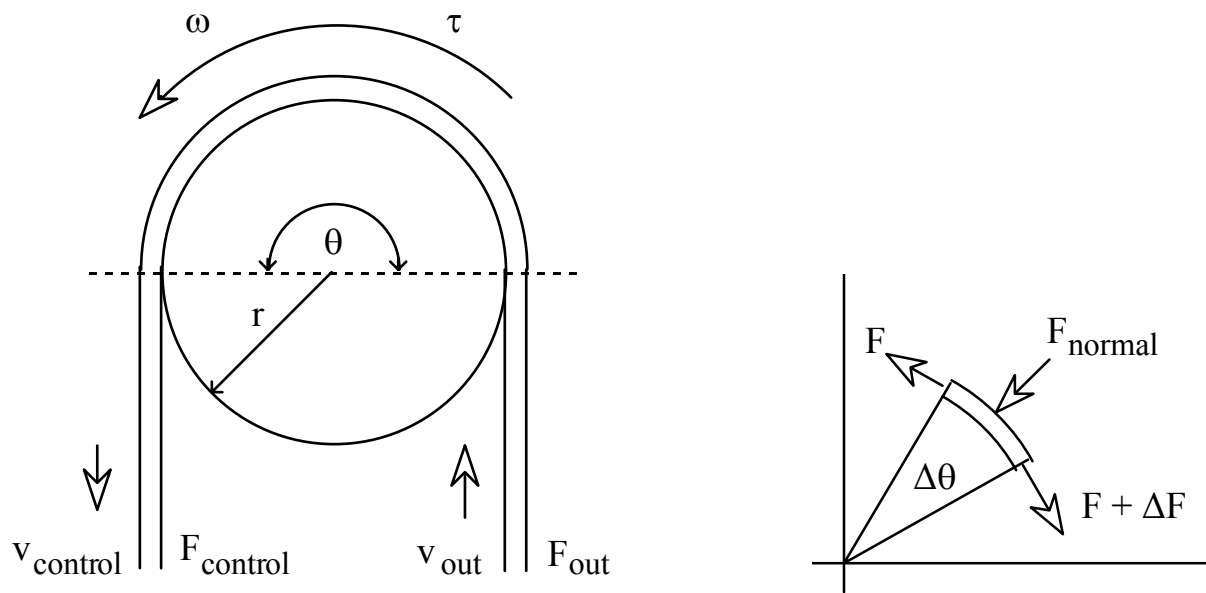


Capstan—a mechanical amplifier

Photograph removed due to copyright restrictions.



A schematic diagram of a basic capstan and a force diagram for a small segment of the rope are shown in the figures.

$$F_{\text{normal}} = F \sin \Delta\theta/2 + (F + \Delta F) \sin \Delta\theta/2$$

In the limit of small angles

$$F_{\text{normal}} = F d\theta/2 + (F + dF) d\theta/2$$

Assuming continuous slip and Coulomb friction between rope and drum,

$$dF = \mu F_{\text{normal}} = \mu \frac{2F+dF}{2} d\theta$$

$$dF = F d\theta \text{ or } d \ln F = \mu d\theta$$

Integrating from 0 to θ

$$F_{\text{out}} = e^{\mu\theta} F_{\text{control}}$$

Note that this relation is only valid if $\omega r \geq v_{\text{control}}$

From continuity: $v_{\text{control}} = v_{\text{out}}$

Torque required of capstan drive:

$$\tau = (F_{\text{out}} - F_{\text{control}}) r = (e^{\mu\theta} - 1) r F_{\text{control}}$$

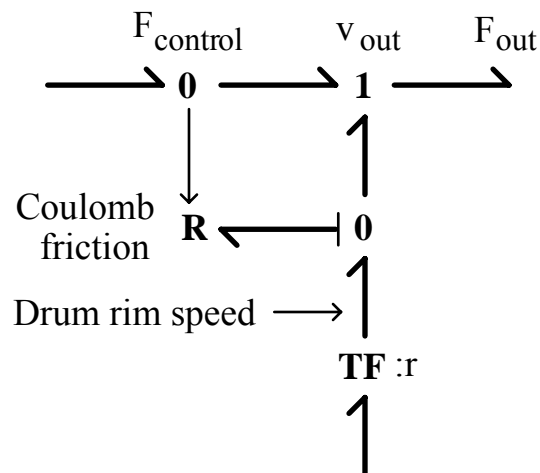
Power dissipated:

$$P_{\text{dissipated}} = \tau \omega + F_{\text{control}} v_{\text{control}} - F_{\text{out}} v_{\text{out}}$$

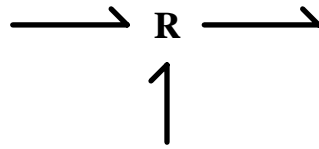
$$P_{\text{dissipated}} = (e^{\mu\theta} - 1) r F_{\text{control}} \omega - (e^{\mu\theta} - 1) F_{\text{control}} v_{\text{control}}$$

Note that $P_{\text{dissipated}} \geq 0$ with $P_{\text{dissipated}} = 0$ if $\omega r = v_{\text{control}}$

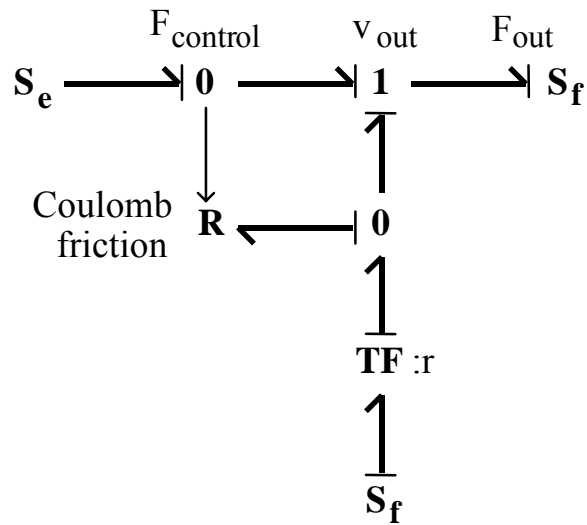
A bond graph follows:



This is a three-port resistor.



Typical boundary conditions result in the following causality.



Constitutive equations are

$$\begin{bmatrix} F_{out} \\ \tau \\ v_{control} \end{bmatrix} = \begin{bmatrix} 0 & 0 & e\mu\theta \\ 0 & 0 & (e\mu\theta-1)r \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_{out} \\ \omega \\ F_{control} \end{bmatrix}$$