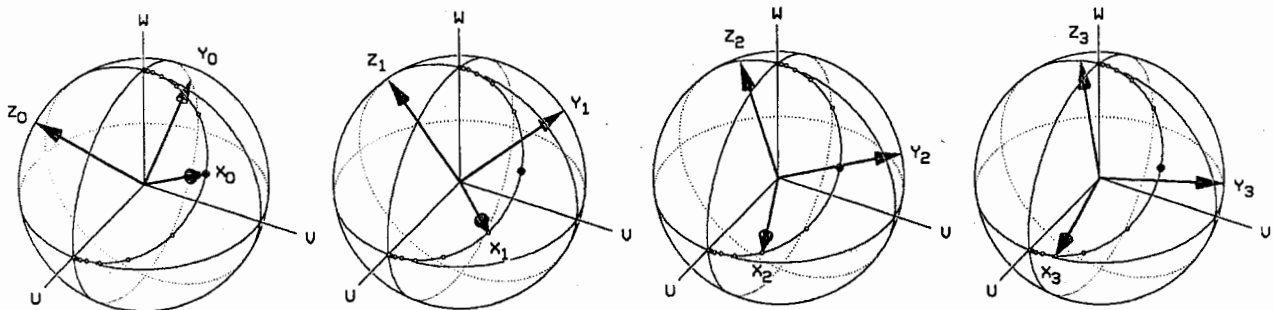


Preamble:

As shown in class (and again hinted on a handout) the basic QR algorithm $Q_k R_k = A_k$, $A_{k+1} = R_k Q_k = Q_k^T A_k Q_k$ applied to any symmetric 3×3 matrix $A = A_0$ is logically equivalent either to the simultaneous iteration of the three vectors $x_k = A x_{k-1}$, $y_k = A y_{k-1}$, $z_k = A z_{k-1}$ after starting from the humble trio $x_0 = [1, 0, 0]^T$, $y_0 = [0, 1, 0]^T$, $z_0 = [0, 0, 1]^T$, or else just to raising the given matrix A to the k-th power and then reading out its column vectors.

The only catch is that one must convert this evolving trio into a mutually orthogonal triplet $X_k = \text{const} \cdot x_k$, $Y_k = \text{portion of } y_k \text{ orthogonal to } x_k$, and $Z_k = \text{orthogonal to both } x_k \text{ and } y_k$, before using the same to estimate the eigenvalues of A via Rayleigh quotients like $RQ_Y(k) = (Y_k^T A Y_k) / (Y_k^T Y_k)$.



To repeat, for this purpose it does not matter whether these "refined" X_k, Y_k, Z_k remain of unit length, but their orthogonality is essential. The QR algorithm very sensibly re-orthogonalizes at every step, but in principle (as here) we could do it only when actually needed at the end of the iteration.

Now please explore these ideas via the following single long problem devoted to just the matrix

$$A = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 3 & -1 \\ 0 & -1 & 2 \end{bmatrix}, \text{ with eigenvectors } U = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}, \quad V = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \quad W = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

and eigenvalues 4, 2, 1 for our mutual convenience.

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- (a) Supply and check explicit formulas for x_k, y_k, z_k , and thence also for X_k, Y_k, Z_k ($= x_k \times y_k$ here, I do believe!).
- (b) Confirm analytically that $RQ_X(k) = (2^{2k+1}+1)/(2^{2k-1}+1)$.
- (c) Derive a similarly compact formula for $RQ_Z(k)$... and check it, too, against the output of your QR algorithm.
- (d) Show from first principles that the sum of the Rayleigh quotients referring to any three mutually orthogonal trial vectors must always equal 7 for the present matrix.
- (e) Then derive (and check) a fairly tidy formula even for $RQ_Y(k)$.
- (f) Show that on the direction sphere anchored on the U, V, W triplet of eigenvectors, our "middle" vector Y_k hops exactly along the arc of a great circle ... and travels 90° altogether.
- (g) Check analogously whether even the landing spots of our main iterated vector X_k lie on a small circle on that direction sphere. If not, could it have been moved onto one via a change of starting vector?
- (h) What precise sense, if any, can you make of these iterated vectors for negative values of k ?

And last but not least,

- (i) LIGHTLY REPEAT these main themes for the closely related matrix

$$B = \begin{bmatrix} 0 & -1 & 2 \\ -1 & 3 & -1 \\ 2 & -1 & 0 \end{bmatrix},$$

which happens to have exactly the same eigenvectors as above, but eigenvalues 4, -2, 1 to make life a little more interesting.