

18.03 Class 34, April 30, 2010

Complex or repeated eigenvalues

1. Eigenvalues and coefficients
2. Complex eigenvalues
3. Repeated eigenvalues
4. Defective and complete

[1] We were solving $u' = Au$, with $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$:
 $A = \begin{bmatrix} -2 & 1 \\ -4 & 3 \end{bmatrix}$ for example. Or u could be a 3D vector,
and A a 3x3 matrix.

(1) Find the eigenvalues = roots λ_1, λ_2
of the characteristic polynomial

$$p_A(\lambda) = \det(A - \lambda I)$$

(2) For each eigenvalue, find a nonzero eigenvector:

$$(A - \lambda_1 I) v_1 = 0 \quad (A - \lambda_2 I) v_2 = 0$$

Normal modes: $u_1 = e^{\lambda_1 t} v_1$, $u_2 = e^{\lambda_2 t} v_2$.

(3) General solution is linear combination of these: $u = c_1 u_1 + c_2 u_2$.

There are a few problems with this, but before pointing them out let me make three comments:

(a) Any multiple of an eigenvector is another eigenvector for the same eigenvalue; they form a line, an "eigenline."

(b) The zero vector is an eigenvector for every value λ , whether λ is an eigenvalue or not. Most of the time 0 is the ONLY eigenvector for value λ ; λ is an eigenvalue exactly when there is a *nonzero* eigenvector for that value.

$$\begin{aligned} (c) \quad p_A(\lambda) &= \det(A - \lambda I) \\ &= \lambda^2 - (a+d)\lambda - (ad-bc) \end{aligned}$$

The sum of the diagonal terms of a square matrix is the "trace" of A , $\text{tr } A$, so

$$p_A(\lambda) = \lambda^2 - (\text{tr } A)\lambda + (\det A)$$

In our example, $\text{tr } A = 1$ and $\det A = -2$, and

$$p_A(\lambda) = \lambda^2 - \lambda - 2.$$

[2] There may be no ray solutions. Romeo and Juliet provided one example.
Or, what about

$$A = \begin{bmatrix} 1 & 2 \\ -2 & 1 \end{bmatrix}.$$

Let's apply the method and see what happens. $\text{tr}(A) = 2$, $\text{det}(A) = 5$, so

$$p_A(\lambda) = \lambda^2 - 2\lambda + 5 = (\lambda - 1)^2 + 4$$

which has roots $\lambda_1 = 1 + 2i$, $\lambda_2 = 1 - 2i$.

We could abandon the effort at this point, but we had so much fun and success with complex numbers earlier that it seems we should carry on.

Find an eigenvector for $\lambda_1 = 1 + 2i$:

$$A - (1+2i)I : \begin{bmatrix} -2i & 2 \\ -2 & -2i \end{bmatrix} \begin{bmatrix} ? \\ ? \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Standard method: use the entries in the top row in reverse order with one sign changed: $\begin{bmatrix} 2 \\ 2i \end{bmatrix}$ or, easier, in this case,

$$v_1 = \begin{bmatrix} 1 \\ i \end{bmatrix}.$$

This is set up so the top entry in the product is 0 . We have a chance to check our work (mainly the calculation of the eigenvalues) by seeing that the bottom entry in the product is 0 too:

$$-2 \cdot 1 - 2i \cdot i = 0$$

$\begin{bmatrix} 1 \\ i \end{bmatrix}$ is a vector with complex entries. OK, so be it. It's hard to visualize, perhaps, and doesn't represent a point on the plane, but we can still compute with it just fine.

Since $\lambda_2 = \text{conjugate of } \lambda_1$, an eigenvector for λ_2 is given by the conjugate of v_1 :

$$v_2 = \begin{bmatrix} 1 \\ -i \end{bmatrix}$$

So the normal modes

$$v(t) = e^{\{(1+2i)t\}} \begin{bmatrix} 1 \\ i \end{bmatrix} , \quad \bar{v}(t) = e^{\{(1-2i)t\}} \begin{bmatrix} 1 \\ -i \end{bmatrix} .$$

As in the case of second order equations, the real and imaginary parts of solutions are again solutions,

$$u_1 = (v + \bar{v})/2 = \text{Re}(v) , \quad u_2 = (v - \bar{v})/(2i)$$

and we really only need to write down one of the normal modes.

So these are real solutions:

$$\begin{aligned} u &= e^{\{(1+2i)t\}} \begin{bmatrix} 1 \\ i \end{bmatrix} \\ &= e^t (\cos(2t) + i \sin(2t)) (\begin{bmatrix} 1;0 \end{bmatrix} + i \begin{bmatrix} 0;1 \end{bmatrix}) \quad \text{so} \end{aligned}$$

$$u_1 = \text{Re}(u) = e^t (\cos(2t) \begin{bmatrix} 1;0 \end{bmatrix} - \sin(2t) \begin{bmatrix} 0;1 \end{bmatrix})$$

$$= e^t [\cos(2t) ; -\sin(2t)] \quad \text{and}$$

$$u_2 = \text{Im}(u) = e^t (\cos(2t) \begin{bmatrix} 0;1 \end{bmatrix} + \sin(2t) \begin{bmatrix} 1;0 \end{bmatrix})$$

$$= e^t [\sin(2t) ; \cos(2t)]$$

These are two independent real solutions. Both spiral around the origin, clockwise, while fleeing away from it exponentially. They satisfy

$$u_1(0) = [1;0] \quad , \quad u_2(0) = [0;1] .$$

I showed their trajectories on the Mathlet Linear Phase Portraits: Matrix Entry.

The general real solution is

$$a u_1 + b u_2 \quad , \quad a, \quad b \text{ real} .$$

It is very hard for me to visualize the fact that all those spirals are linear combinations of any two of them.

Summary: Nonreal eigenvalues lead to spiral solutions.
 Positive real parts lead to solutions going to infinity with t ("unstable")
 Negative real parts lead to solutions going to zero with t ("stable")
 Zero real parts lead to solutions parametrizing ellipses.

So we discover that the possibility of complex eigenvalues really isn't a failure of the method at all. There are in fact ray solutions, but they are complex and don't show up on our real phase plane.

[3] Second problem with our method: Illustrated by

$$A = [-2 \ 1 ; -1 \ 0]$$

$$p_A(\lambda) = \lambda^2 + 2\lambda + 1 = (\lambda + 1)^2$$

which has only one root, "repeated": $\lambda_1 = \lambda_2 = -1$.

Still, find an eigenvector:

$$A - (-1)I = [-1 \ 1 ; -1 \ 1] [? ; ?] = [0 ; 0] : \quad v = [1 ; 1]$$

or any nonzero multiple. ALL eigenvectors for A lie on the line containing 0 and $[1 ; 1]$. I showed a picture of the phase portrait, which shows only one pair of opposed ray trajectories.

So there is (up to multiples) only one normal mode:

$$u_1 = e^{-t} [1 ; 1]$$

But we need another solution. Here is how to find one; I won't go into details, just give you the method.

Write down the same matrix $A - \lambda_1 I$ but now find a vector w such that

$$(A - \lambda_1 I) w = v .$$

Then

$$u_2 = e^{\lambda_1 t} (t v + w)$$

is a second solution.

In our case:

$$\begin{bmatrix} -1 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} ? \\ ? \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

has solution $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$, so

$$\begin{aligned} u_2 &= e^{-t} (t \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix}) \\ &= e^{-t} \begin{bmatrix} t \\ t+1 \end{bmatrix} \end{aligned}$$

$\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ isn't the only vector that works here; $\begin{bmatrix} 0 \\ 1 \end{bmatrix} + c v$ does too for any constant c . It doesn't matter which one you pick.

With this choice, $u_1(0) = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$, $u_2(0) = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$.

The general solution is

$$u = a u_1 + b u_2.$$

To learn more about all this you should take 18.06.

Didn't get to talk about this on Friday:

[4] A matrix with a repeated eigenvalue but only one lineful of eigenvectors is called "defective." A matrix can have a repeated eigenvalue and not be defective:

$$A = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$

for example has characteristic polynomial

$$p(\lambda) = \lambda^2 - 4\lambda + 4 = (\lambda - 2)^2$$

so $\lambda_1 = \lambda_2 = 2$. To find an eigenvector consider

$$A - \lambda_1 I : \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} ? \\ ? \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now ANY vector is an eigenvector! Instead of only one line you get the entire plane. For any vector v ,

$$e^{2t} v$$

is a solution, and every solution is a normal mode. This is called the "complete" case.

In the 2×2 case, if the eigenvalue is repeated you are in the defective case unless the matrix is precisely $\begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_1 \end{bmatrix}$

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18.03 Differential Equations
Spring 2010

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