

1.021, 3.021, 10.333, 22.00 Introduction to Modeling and Simulation
Spring 2011

Part I – Continuum and particle methods

Applications to biophysics and bionanomechanics

Lecture 10

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Massachusetts Institute of Technology**



Content overview

I. Particle and continuum methods

Lectures 1-13

1. Atoms, molecules, chemistry
2. Continuum modeling approaches and solution approaches
3. Statistical mechanics
4. Molecular dynamics, Monte Carlo
5. Visualization and data analysis
6. Mechanical properties – application: how things fail (and how to prevent it)
7. Multi-scale modeling paradigm
8. Biological systems (simulation in biophysics) – how proteins work and how to model them

II. Quantum mechanical methods

Lectures 14-26

1. It's A Quantum World: The Theory of Quantum Mechanics
2. Quantum Mechanics: Practice Makes Perfect
3. The Many-Body Problem: From Many-Body to Single-Particle
4. Quantum modeling of materials
5. From Atoms to Solids
6. Basic properties of materials
7. Advanced properties of materials
8. What else can we do?

Overview: Material covered so far...

- **Lecture 1: Broad introduction to IM/S**
- **Lecture 2: Introduction to atomistic and continuum modeling** (multi-scale modeling paradigm, difference between continuum and atomistic approach, case study: diffusion)
- **Lecture 3: Basic statistical mechanics – property calculation I** (property calculation: microscopic states vs. macroscopic properties, ensembles, probability density and partition function)
- **Lecture 4: Property calculation II** (Monte Carlo, advanced property calculation, introduction to chemical interactions)
- **Lecture 5: How to model chemical interactions I** (example: movie of copper deformation/dislocations, etc.)
- **Lecture 6: How to model chemical interactions II** (EAM, a bit of ReaxFF—chemical reactions)
- **Lecture 7: Application to modeling brittle materials I**
- **Lecture 8: Application to modeling brittle materials II**
- **Lecture 9: Application – Applications to materials failure**
- **Lecture 10: Applications to biophysics and bionanomechanics**

Lecture 10: Applications to biophysics and bionanomechanics

Outline:

1. Protein force fields
2. Single molecule mechanics
3. Fracture of protein domains – Bell model

Goal of today's lecture:

- Force fields for organic materials, and specifically proteins
- Basic introduction into modeling of biological materials
- Fracture model for protein domains

1. Force fields for organic chemistry - how to model proteins

Significance of proteins

- Proteins are **basic building blocks of life**
- **Define tissues, organs, cells**
- Provide a **variety of functions and properties**, such as mechanical stability (strength), elasticity, catalytic activity (enzyme), electrochemical properties, optical properties, energy conversion
- Molecular simulation is an **important tool in the analysis of protein structures and protein materials**

***Goal here:** To train you in the fundamentals of modeling techniques for proteins, to enable you to carry out protein simulations*

Explain the significance of proteins (application)

Human body: Composed of diverse array of protein materials

Eye's cornea
(collagen material)

Skin (complex composite of collagen, elastin)

Cells (complex material/system based on proteins)

Image removed due to copyright restrictions.

[Human Body 3D View™](#) image of whole bodies.



Image courtesy of NIH.

Muscle tissue
(motor proteins)

Nerve cells

Blood vessels

Tendon
(links bone, muscles)

Cartilage (reduce friction in joints)

Bone (structural stability)

Cellular structure: Protein networks

Cell nucleus

Actin network

Microtubulus
(e.g. cargo)

Vimentin
(extensible,
flexible, provide
strength)

= cytoskeleton



Image courtesy of NIH.

Protein structures define the cellular architecture

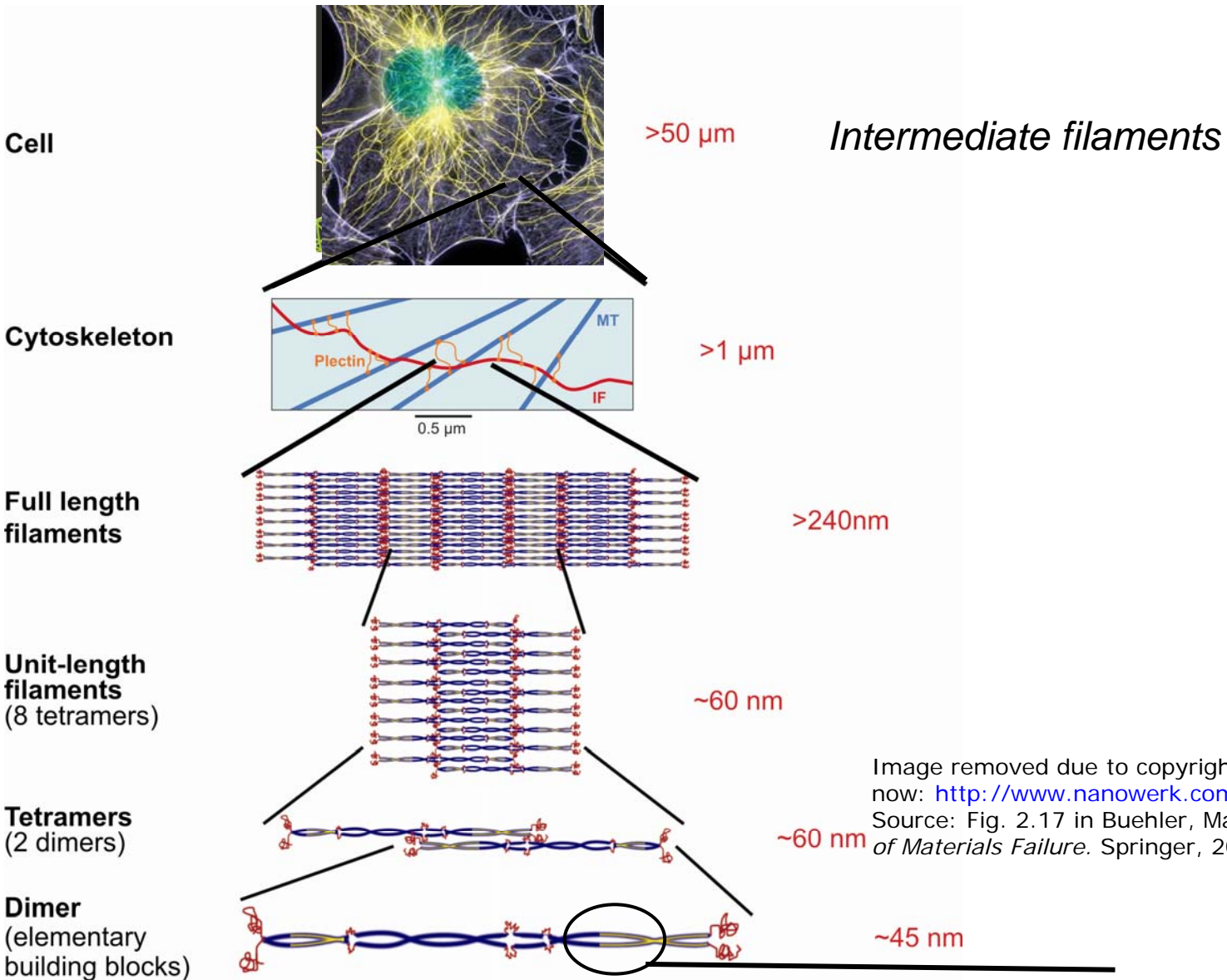
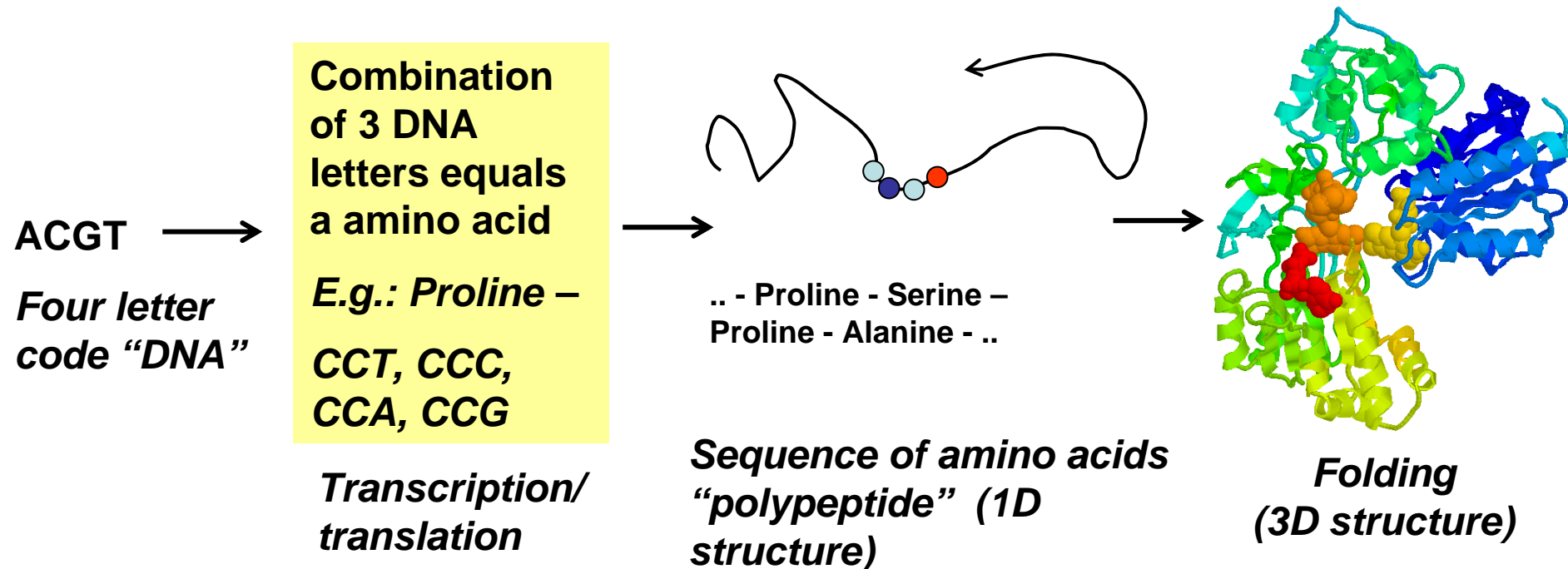


Image removed due to copyright restrictions; see image now: http://www.nanowerk.com/spotlight/id2878_1.jpg. Source: Fig. 2.17 in Buehler, Markus J. *Atomistic Modeling of Materials Failure*. Springer, 2008.

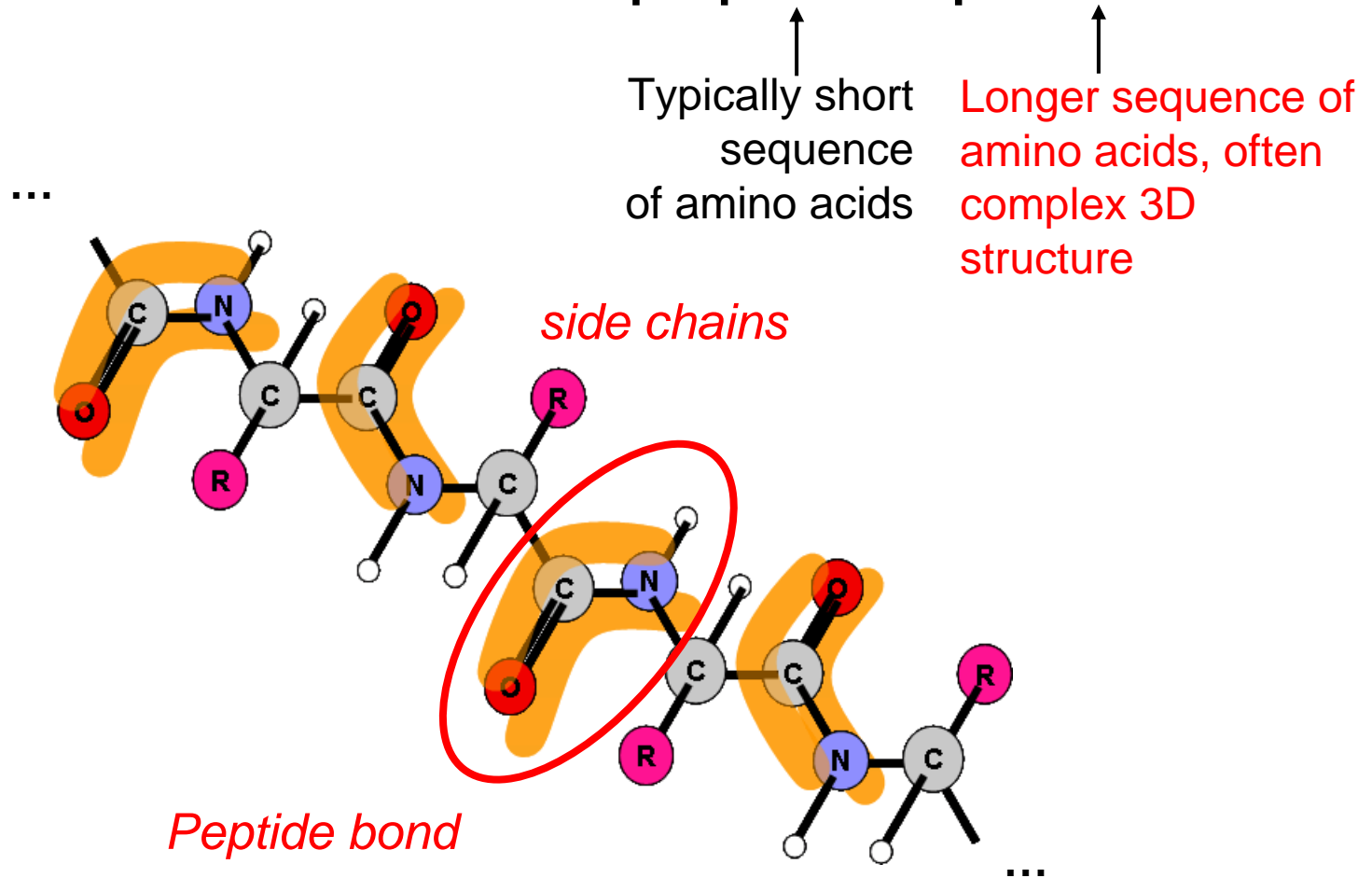
How protein materials are made – the genetic code

- Proteins: Encoded by DNA (three “letters”), utilize 20 basic building blocks (amino acids) to form polypeptides
- Polypeptides arrange in complex folded 3D structures with specific properties

1D structure transforms into complex 3D folded configuration



Chemical structure of peptides/proteins



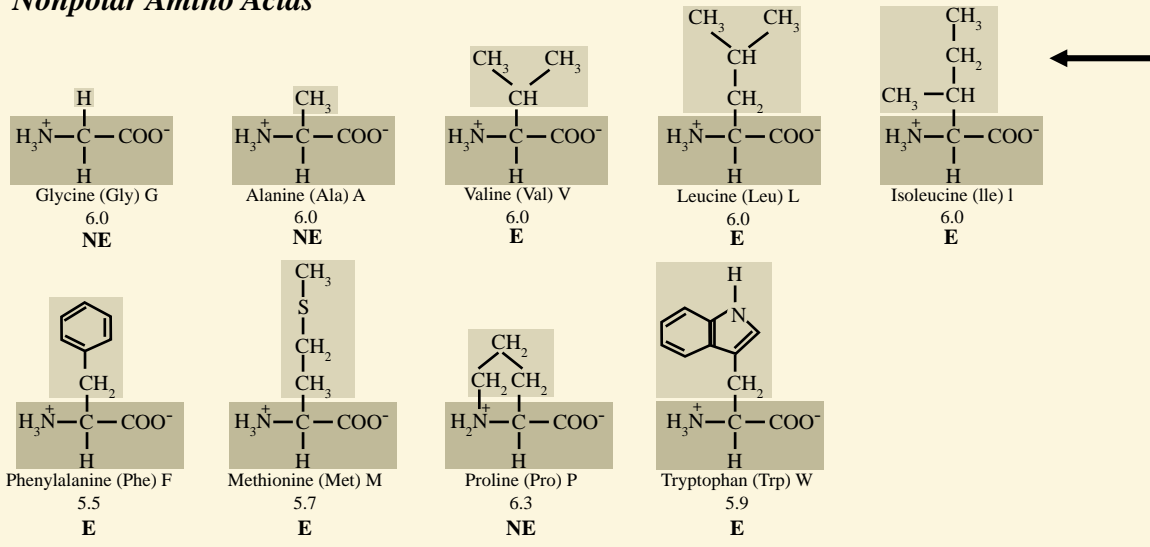
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R = side chain, one of the 20 natural amino acids

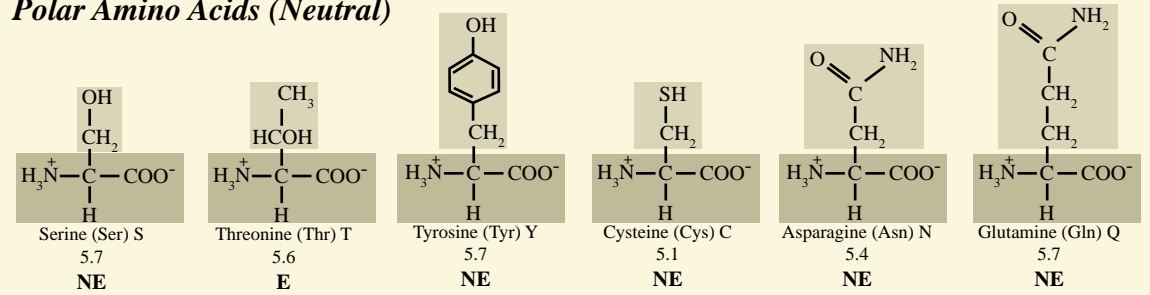
20 natural amino acids differ in their side chain chemistry

R

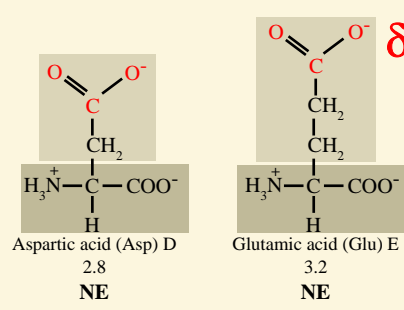
Nonpolar Amino Acids



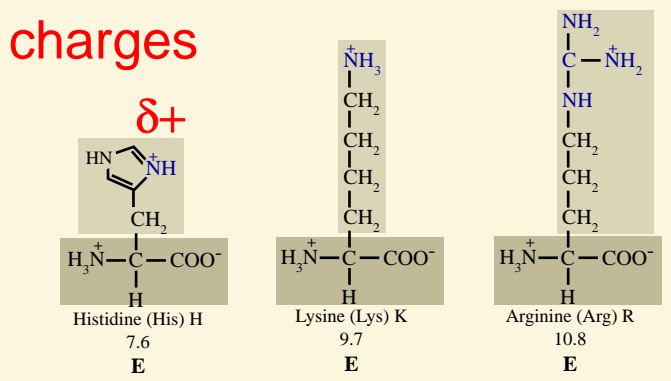
Polar Amino Acids (Neutral)



Acidic Amino Acids



Basic Amino Acids



δ- charges

δ+ charges

Forms peptide bond →

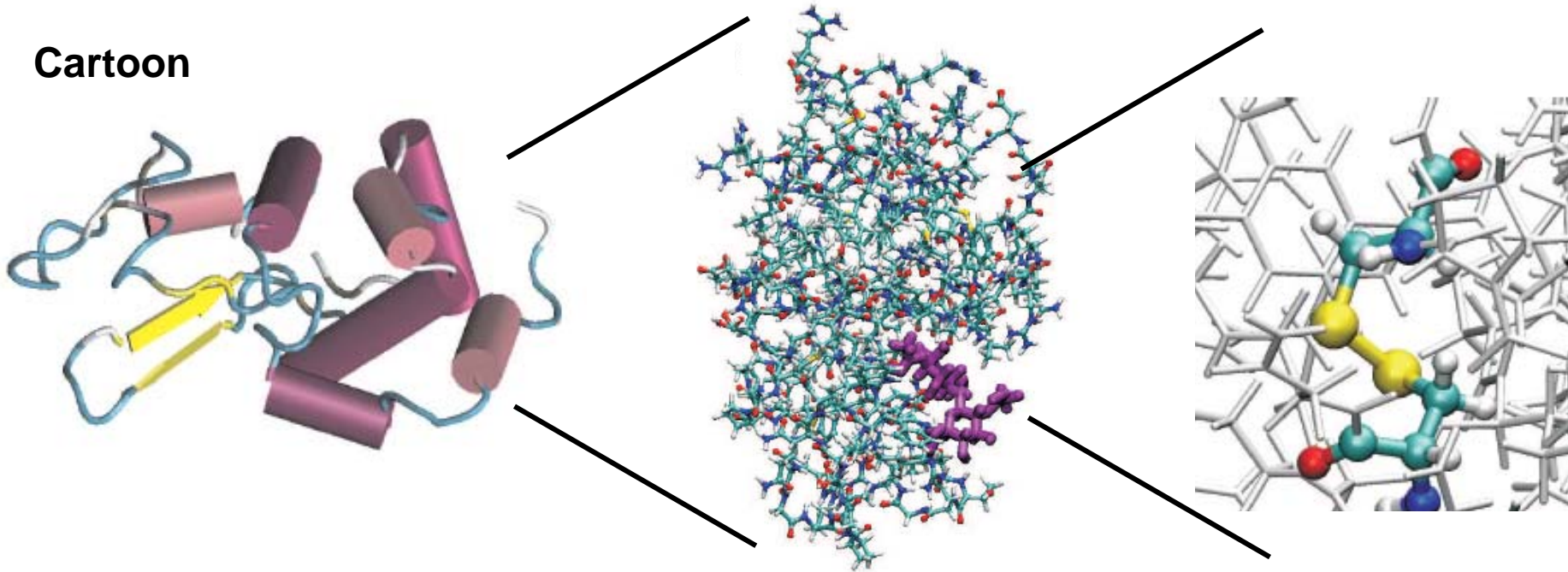
There are 20 natural amino acids

Difference in side chain, R

Chemistry, structure and properties are linked

Chemical structure

Cartoon



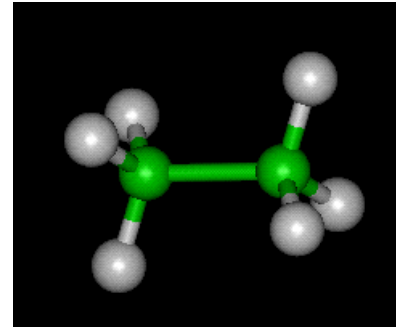
Presence of various chemical bonds:

- Covalent bonds (C-C, C-O, C-H, C-N..)
- Electrostatic interactions (charged amino acid side chains)
- H-bonds (e.g. between H and O)
- vdW interactions (uncharged parts of molecules)

Concept: split energy contributions

$$U_{total} = U_{Elec} + U_{Covalent} + U_{Metallic} + U_{vdW} + U_{H-bond}$$

(Note: $U_{Covalent}$ is circled in red in the original image. An arrow points from the circle to the text "=0 for proteins". Another arrow points from the text "=0 for proteins" to the $U_{Metallic}$ term.)



Ethane
 C_2H_6

Covalent bond described as

1. Bond stretching part (energy penalty for bond stretching)
2. Bending part (energy penalty for bending three atoms)
3. Rotation part (energy penalty for bond rotation, $N \geq 4$)

Consider ethane molecule as “**elastic structure**”

$$U_{Covalent} = U_{stretch} + U_{bend} + U_{rotate}$$

Force fields for organics: Basic approach

$$U_{total} = U_{Elec} + U_{Covalent} + U_{Metallic} + U_{vdW} + U_{H-bond}$$

=0 for proteins

$$U_{Covalent} = U_{stretch} + U_{bend} + U_{rot}$$

$$\left\{ \begin{array}{l} \phi_{stretch} = \frac{1}{2} k_{stretch} (r - r_0)^2 \\ U_{stretch} = \sum_{\text{pairs}} \phi_{stretch} \end{array} \right.$$

$$\left\{ \begin{array}{l} \phi_{bend} = \frac{1}{2} k_{bend} (\theta - \theta_0)^2 \\ U_{bend} = \sum_{\text{triplets}} \phi_{bend} \end{array} \right.$$

$$\left\{ \begin{array}{l} \phi_{rot} = \frac{1}{2} k_{rot} (1 - \cos(\mathcal{G})) \\ U_{rot} = \sum_{\text{quadruplets}} \phi_{rot} \end{array} \right.$$

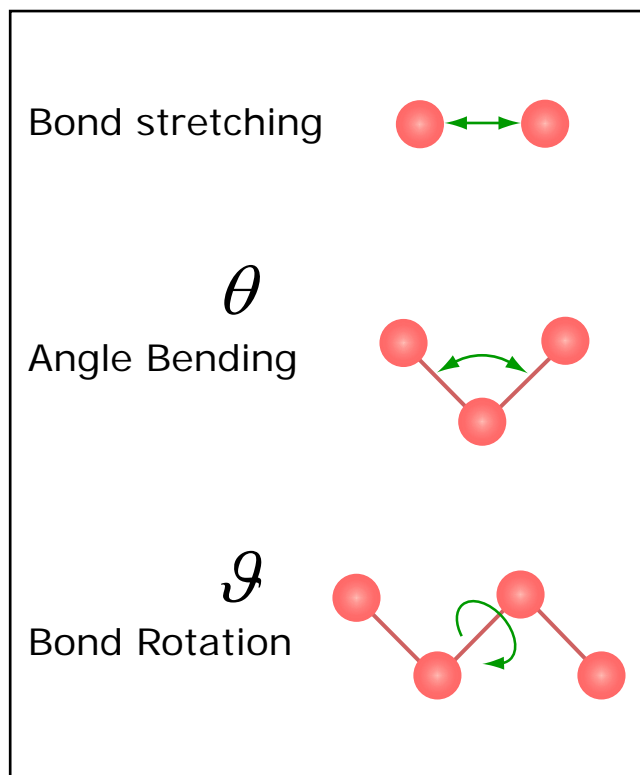
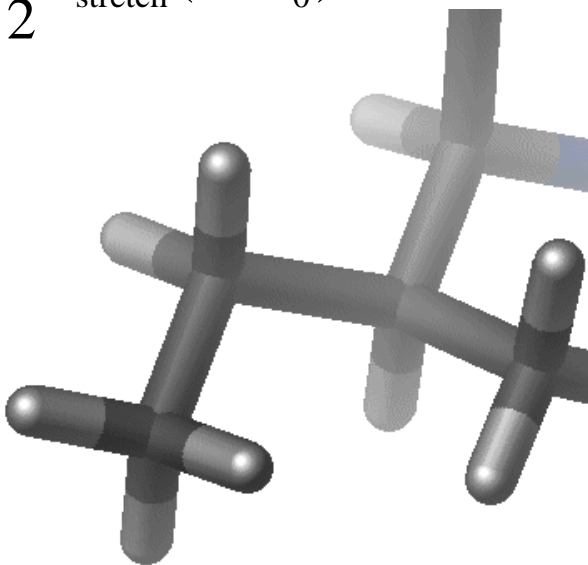


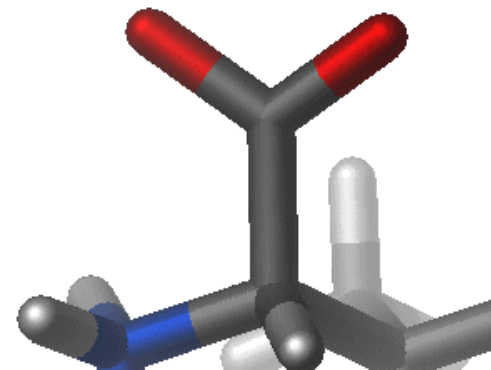
Image by MIT OpenCourseWare.

Model for covalent bonds

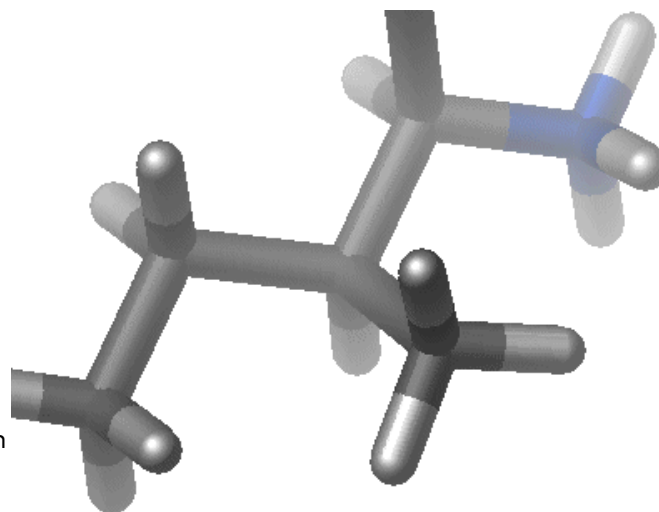
$$\phi_{\text{stretch}} = \frac{1}{2} k_{\text{stretch}} (r - r_0)^2$$



$$\phi_{\text{bend}} = \frac{1}{2} k_{\text{bend}} (\theta - \theta_0)^2$$



$$\phi_{\text{rot}} = \frac{1}{2} k_{\text{rot}} (1 - \cos(\mathcal{G}))$$



Courtesy of the EMBnet Education & Training Committee. Used with permission.

Images created for the CHARMM tutorial by Dr. Dmitry Kuznetsov (Swiss Institute of Bioinformatics) for the EMBnet Education & Training committee (<http://www.embnet.org>)

http://www.ch.embnet.org/MD_tutorial/pages/MD.Part2.html

Force fields for organics: Basic approach

$$U_{total} = U_{Elec} + U_{Covalent} + U_{Metallic} + U_{vdW} + U_{H-bond}$$

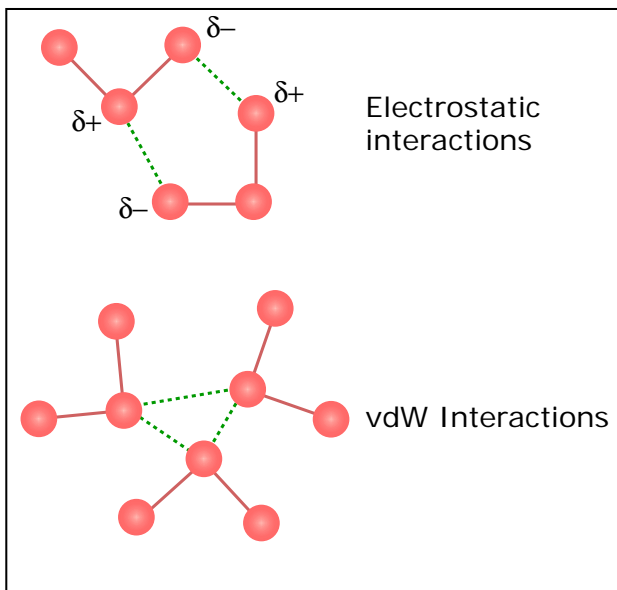
U_{Elec} (circled in red)
 $U_{Covalent}$ (checked with a blue checkmark)
 $U_{Metallic}$ (crossed out with a red slash and labeled "=0 for proteins")

q_i
 q_j

partial charges
↓

U_{Elec} :Coulomb potential $\phi(r_{ij}) = \frac{q_i q_j}{\epsilon_1 r_{ij}}$

electrostatic constant ϵ_1 distance r_{ij}



Coulomb forces $F(r_{ij}) = -\frac{q_i q_j}{\epsilon_1 r_{ij}^2}$

$\epsilon_1 = 4\pi\epsilon_0$ $\epsilon_0 = 1.602 \times 10^{-19} \text{ C}$

Force fields for organics: Basic approach

$$U_{total} = U_{Elec} + U_{Covalent} + U_{Metallic} + U_{vdW} + U_{H-bond}$$

(Note: Blue checkmarks are above U_{Elec} and U_{Covalent}. A red arrow points from the text "=0 for proteins" to U_{Metallic}. The term U_{vdW} is circled in red.)

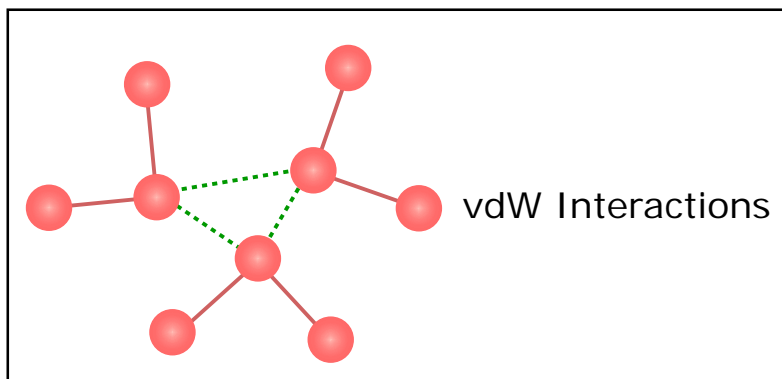


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U_{vdW}

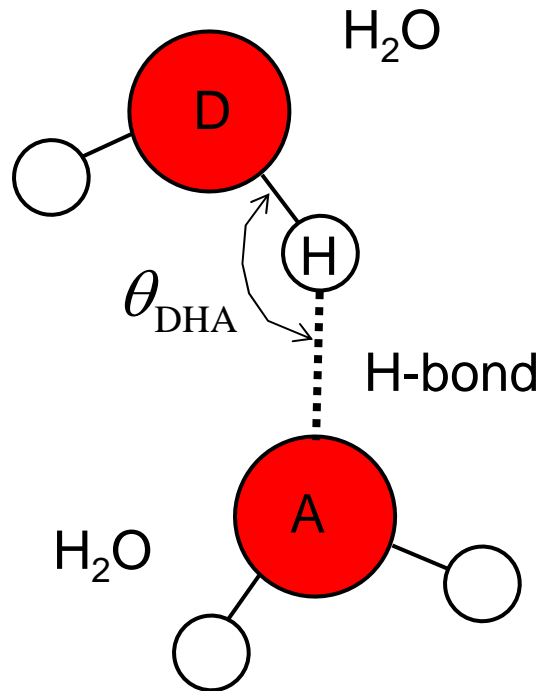
$$U_{vdW} : \quad \text{LJ potential} \quad \phi(r_{ij}) = 4\epsilon \left[\left(\frac{\sigma}{r_{ij}} \right)^{12} - \left(\frac{\sigma}{r_{ij}} \right)^6 \right]$$

LJ potential is particularly good model for vdW interactions (Argon)

H-bond model

$$U_{total} = U_{Elec} + U_{Covalent} + U_{Metallic} + U_{vdW} + U_{H-bond}$$

✓ ✓ =0 for proteins ✓



U_{H-bond}

Evaluated between acceptor (A) /donor(D) pairs

Between electronegative atom and a H- atom that is bonded to another electronegative atom

Slightly modified LJ, different parameters

$$U_{H-bond} : \phi(r_{ij}) = D_{H-bond} \left[5 \left(\frac{R_{H-bond}}{r_{ij}} \right)^{12} - 6 \left(\frac{R_{H-bond}}{r_{ij}} \right)^{10} \right] \cos^4(\theta_{DHA})$$

r_{ij} = distance between D-A

Summary

$$U_{total} = U_{\text{Elec}} + U_{\text{Covalent}} + U_{\text{Metallic}} + U_{\text{vdW}} + U_{\text{H-bond}}$$

=0 for proteins

$$U_{\text{Elec}} : \quad \text{Coulomb potential} \quad \phi(r_{ij}) = \frac{q_i q_j}{\epsilon_1 r_{ij}}$$

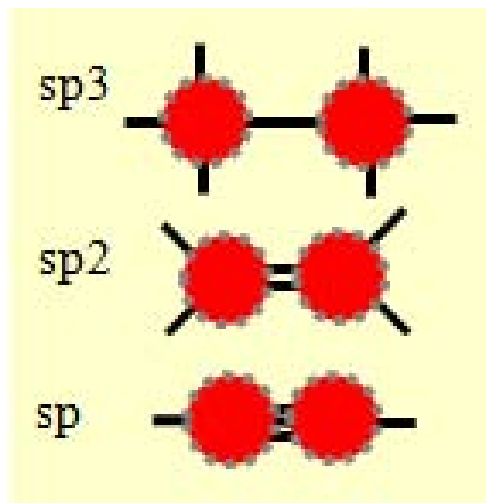
$$U_{\text{Covalent}} = U_{\text{stretch}} + U_{\text{bend}} + U_{\text{rot}} \quad \left\{ \begin{array}{l} \phi_{\text{stretch}} = \frac{1}{2} k_{\text{stretch}} (r - r_0)^2 \\ \phi_{\text{bend}} = \frac{1}{2} k_{\text{bend}} (\theta - \theta_0)^2 \\ \phi_{\text{rot}} = \frac{1}{2} k_{\text{rot}} (1 - \cos(\vartheta)) \end{array} \right.$$

$$U_{\text{vdW}} : \quad \text{LJ potential} \quad \phi(r_{ij}) = 4\epsilon \left[\left(\frac{\sigma}{r_{ij}} \right)^{12} - \left(\frac{\sigma}{r_{ij}} \right)^6 \right]$$

$$U_{\text{H-bond}} : \quad \phi(r_{ij}) = D_{\text{H-bond}} \left[5 \left(\frac{R_{\text{H-bond}}}{r_{ij}} \right)^{12} - 6 \left(\frac{R_{\text{H-bond}}}{r_{ij}} \right)^{10} \right] \cos^4(\theta_{\text{DHA}})$$

The need for atom typing

- **Limited transferability** of potential expressions: Must use different potential for different chemistry
- Different chemistry is captured in **different “tags”** for atoms: **Element type** is expanded by **additional information** on particular chemical state
- Tags specify if a C-atom is in **sp³**, **sp²**, **sp** or in aromatic state (that is, to capture resonance effects)
- **Example atom tags:** CA, C_1, C_2, C_3, C..., HN, HO, HC, ...

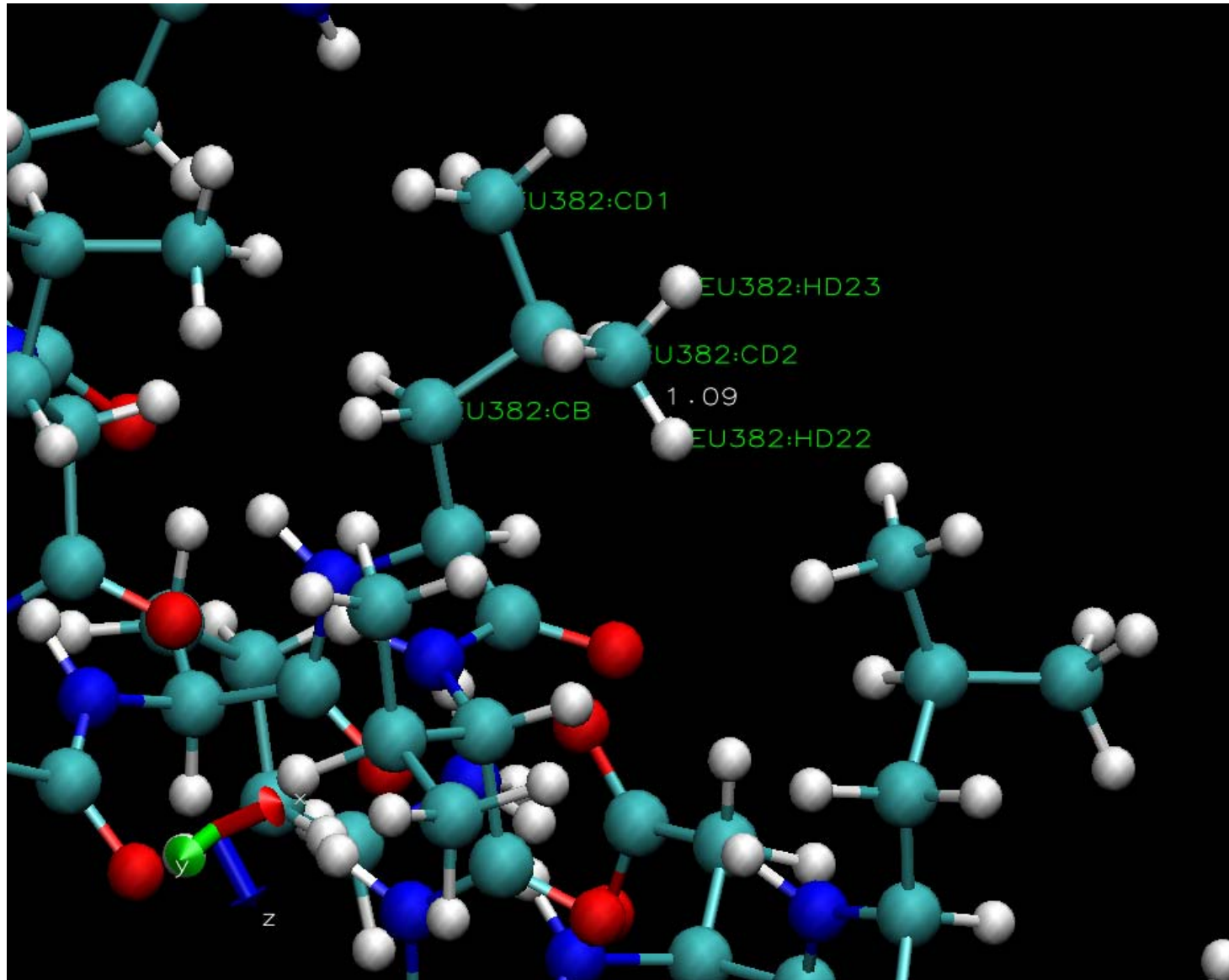


Atom typing in CHARMM

Example of the RTF for the Alanine residue:

```
RESI ALA0.00
GROUP
ATOM NNH1-0.47 !      |
ATOM HNH 0.31  !  HN-N
ATOM CACT1 0.07 !      |      HB1
ATOM HAHB 0.09 !      |      /
GROUP          !HA-CA--CB-HB2
ATOM CBCT3-0.27 !      |      \
ATOM HB1HA 0.09 !      |      HB3
ATOM HB2HA 0.09 !      O=C
ATOM HB3HA 0.09 !      |
GROUP          !
ATOM CC 0.51
ATOM OO-0.51
BONDCB CA N HN N CA
BOND C CA C +N CA HA CB HB1 CB HB2 CB HB3
DOUBLE O C
IMPR N -C CA HN C CA +N O
DONOR HN N
ACCEPTOR O C
IC -C CA *N HN      1.3551 126.4900 180.0000 115.4200 0.9996
IC -C N CA C        1.3551 126.4900 180.0000 114.4400 1.5390
IC N CA C +N        1.4592 114.4400 180.0000 116.8400 1.3558
IC +N CA *C O       1.3558 116.8400 180.0000 122.5200 1.2297
IC CA C +N +CA      1.5390 116.8400 180.0000 126.7700 1.4613
IC N C *CA CB       1.4592 114.4400 123.2300 111.0900 1.5461
IC N C *CA HA       1.4592 114.4400 -120.4500 106.3900 1.0840
IC C CA CB HB1      1.5390 111.0900 177.2500 109.6000 1.1109
IC HB1 CA *CB HB2   1.1109 109.6000 119.1300 111.0500 1.1119
IC HB1 CA *CB HB3   1.1109 109.6000 -119.5800 111.6100 1.1114
```

VMD analysis of protein structure



Common empirical force fields for organics and proteins

Class I (experiment derived, simple form)

- CHARMM **pset #3**
- CHARMM (Accelrys)
- AMBER
- OPLS/AMBER/Schrödinger
- ECEPP (free energy force field)
- GROMOS

*Harmonic terms;
Derived from
vibrational
spectroscopy, gas-
phase molecular
structures
Very system-
specific*

Class II (more complex, derived from QM)

- CFF95 (Biosym/Accelrys)
- MM3
- MMFF94 (CHARMM, Macromodel...)
- UFF, DREIDING

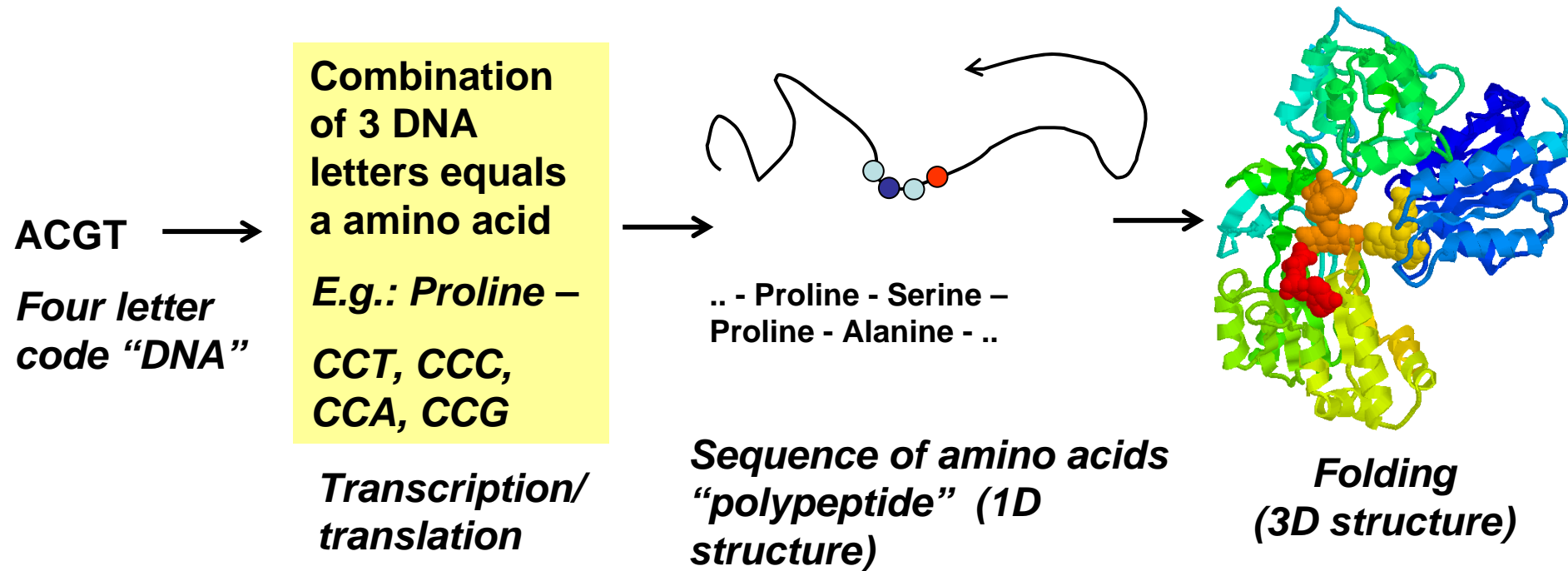
*Include anharmonic
terms
Derived from QM,
more general*

CHARMM force field

- Widely used and accepted model for protein structures
- Programs such as NAMD have implemented the CHARMM force field

Problem set #3, nanoHUB stretchmol module, study of a protein domain that is part of **human vimentin intermediate filaments**

Application – protein folding



Goal of protein folding simulations:
Predict folded 3D structure based on polypeptide sequence

Movie: protein folding with CHARMM

- *de novo* Folding of a *Transmembrane fd Coat Protein*
<http://www.charmm-gui.org/?doc=gallery&id=23>

Polypeptide chain

Images removed due to copyright restrictions.

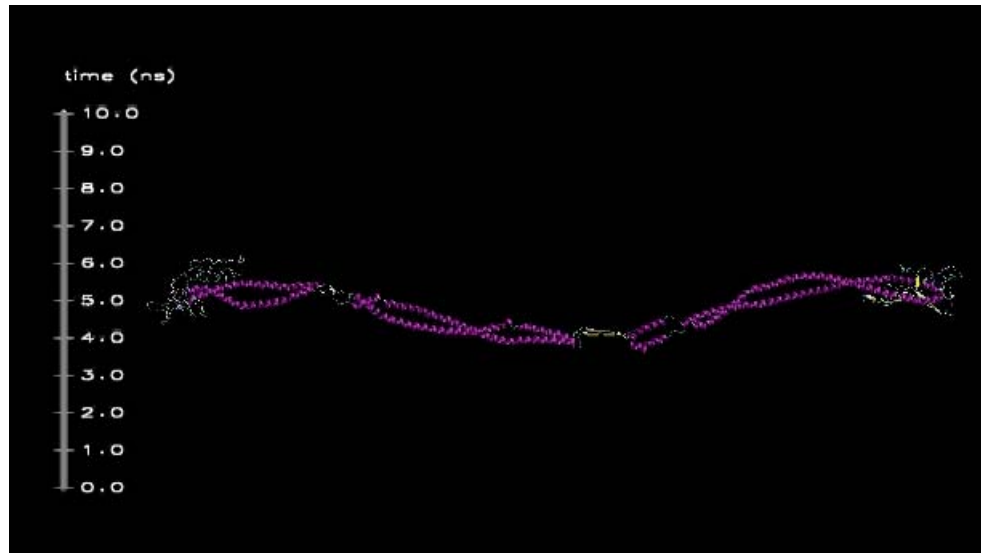
Screenshots from protein folding video, which can be found here:

<http://www.charmm-gui.org/?doc=gallery&id=23>.

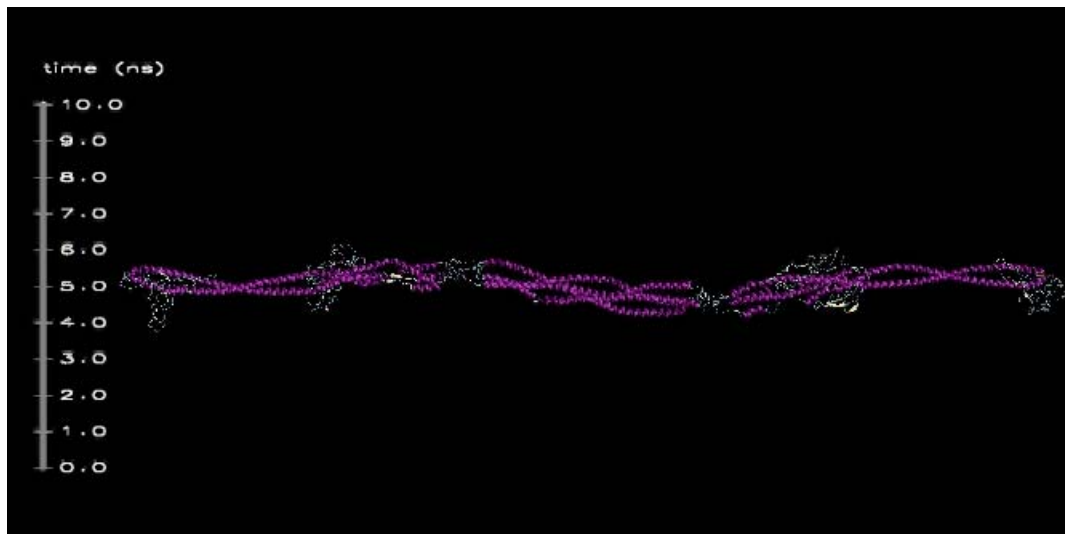
Quality of predicted structures quite good

Confirmed by comparison of the **MSD deviations** of a room temperature ensemble of conformations from the replica-exchange simulations and **experimental structures** from both **solid-state NMR** in lipid bilayers and solution-phase NMR on the protein in micelles)

Movies in equilibrium (temperature 300 K)



Dimer



Tetramer
(increased effective
bending stiffness,
interaction via overlap
& head/tail domain)

2. Single molecule mechanics

*Structure and mechanics of
protein, DNA, etc. molecules*

Cooking spaghetti



Photo courtesy of [HatM](#) on Flickr.

stiff rods



Public domain image.

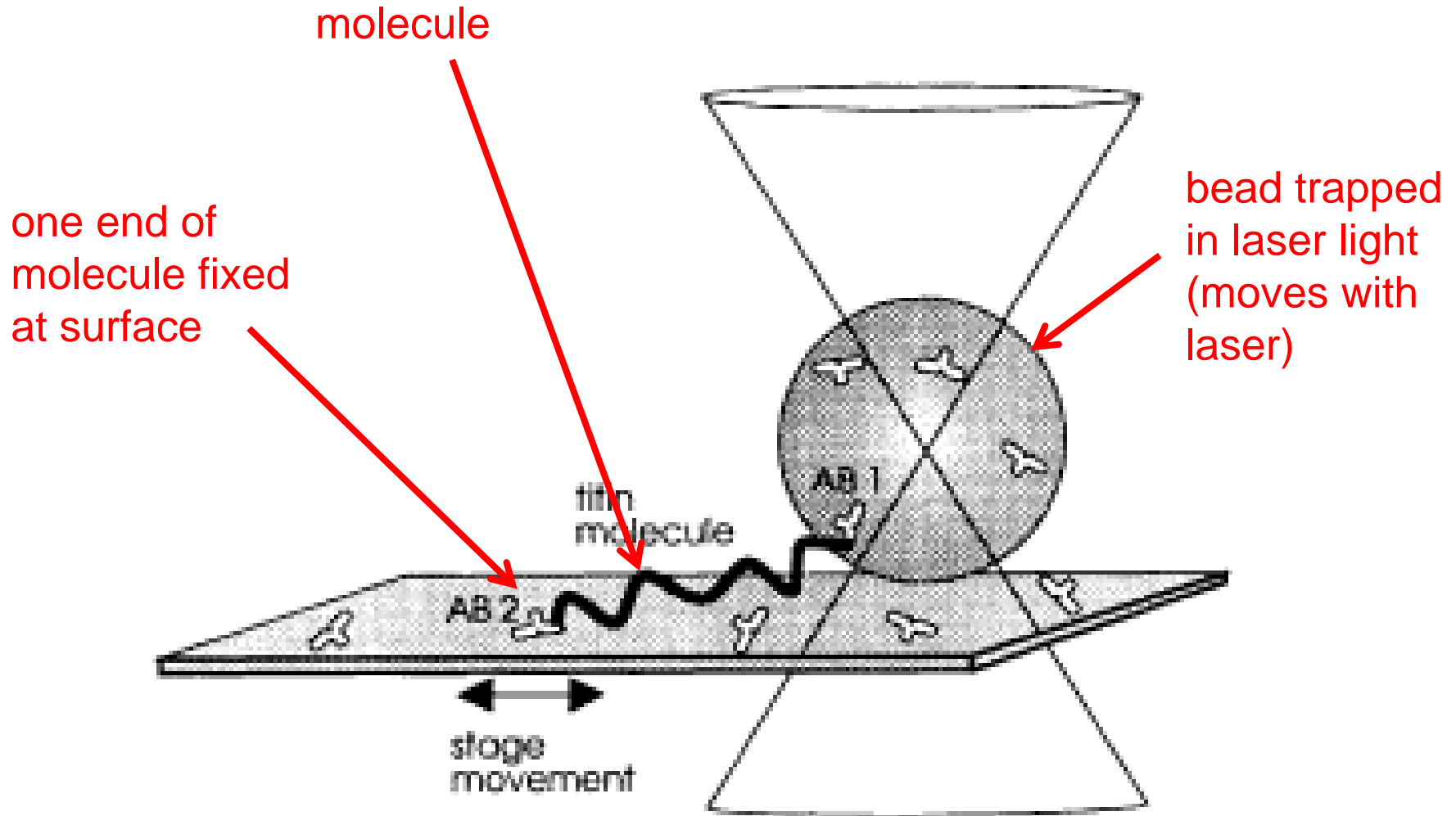
cooking



Photo courtesy of [HatM](#) on Flickr.

*soft, flexible rods
(like many protein
molecules)*

Single molecule tensile test – “optical tweezer”



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Source: Tskhovrebova, L., J. Trinick, et al. "Elasticity and Unfolding of Single Molecules of the Giant Muscle Protein Titin." *Nature* 387, no. 6630 (1997): 308- 12. © 1997.

Example 1: Elasticity of tropocollagen molecules

300 nm length



Entropic elasticity leads to strongly nonlinear elasticity



Photo courtesy of [HatM](#) on Flickr.

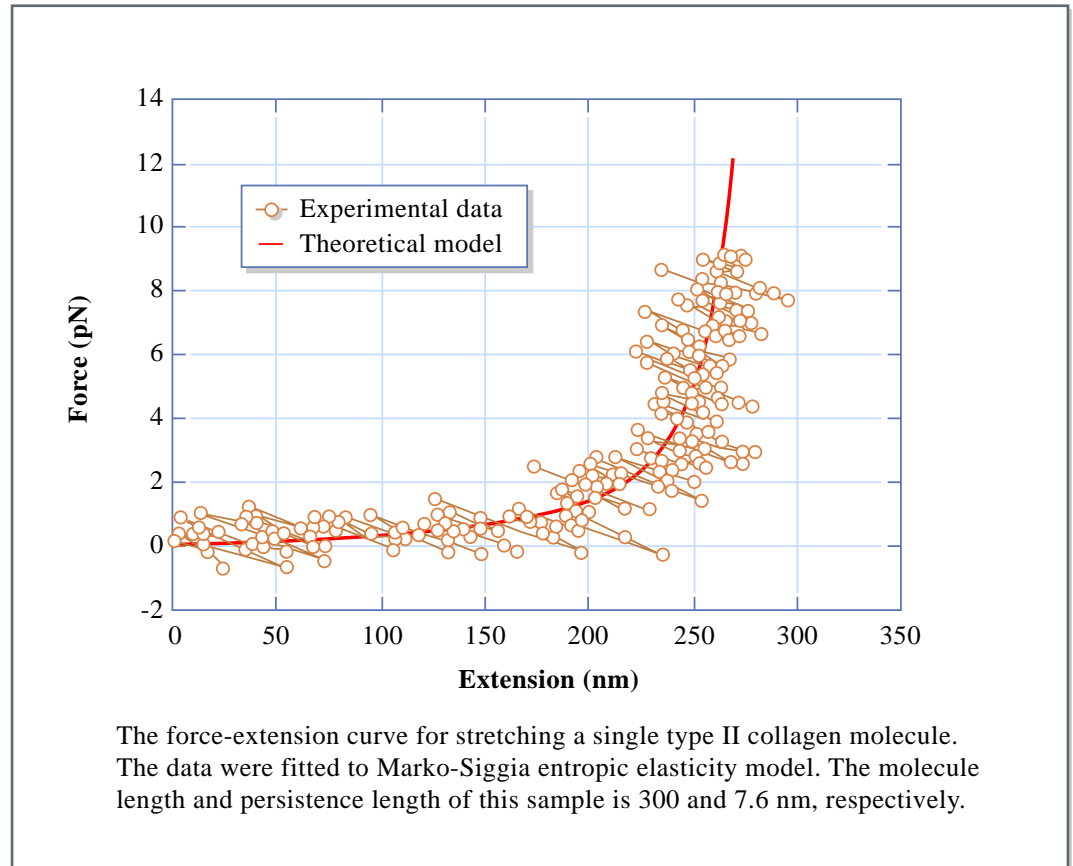
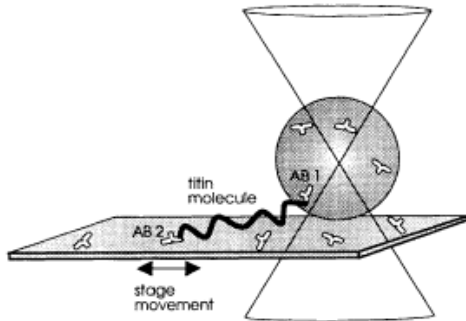


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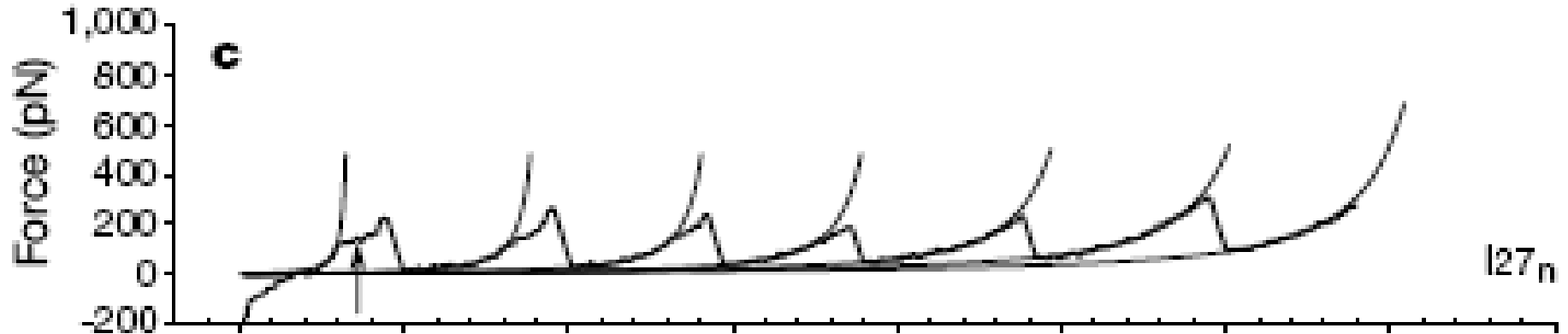
Example 2: Single protein molecule mechanics

Optical tweezers experiment

Protein structure (I27 multidomain titin in muscle)



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Source: Tskhovrebova, L., J. Trinick, et al. "Elasticity and Unfolding of Single Molecules of the Giant Muscle Protein Titin." *Nature* 387, no. 6630 (1997): 308-12. © 1997.



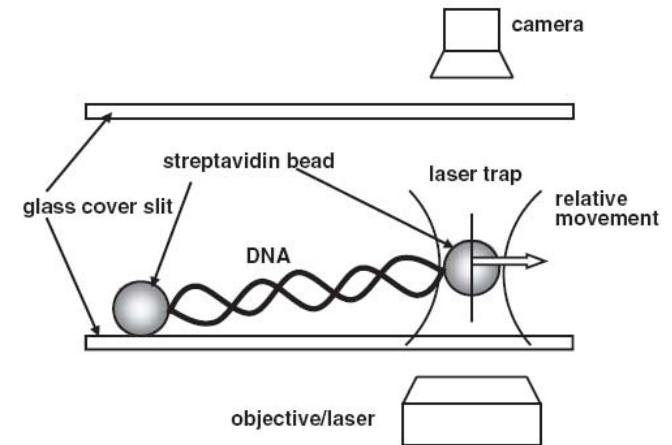
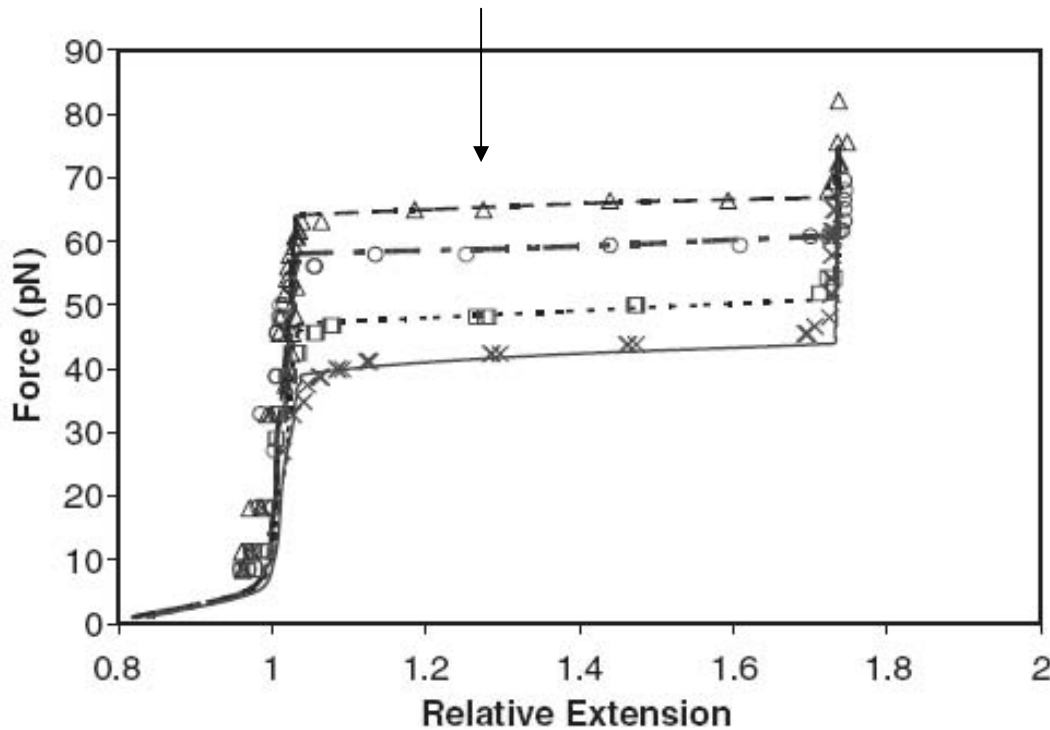
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Source: Marszalek, P., H. Lu, et al. "Mechanical Unfolding Intermediates in Titin Modules." *Nature* 402, no. 6757 (1999): 100-3. © 1999.

<http://www.nature.com/nature/journal/v387/n6630/pdf/387308a0.pdf>

<http://www.nature.com/nature/journal/v402/n6757/pdf/402100a0.pdf>

Example 3: Single DNA molecule mechanics

plateau regime (breaking of bonds)



Courtesy of Elsevier, Inc., <http://www.sciencedirect.com>. Used with permission.

Plots of stretching force against relative extension of the single DNA molecule (experimental results)

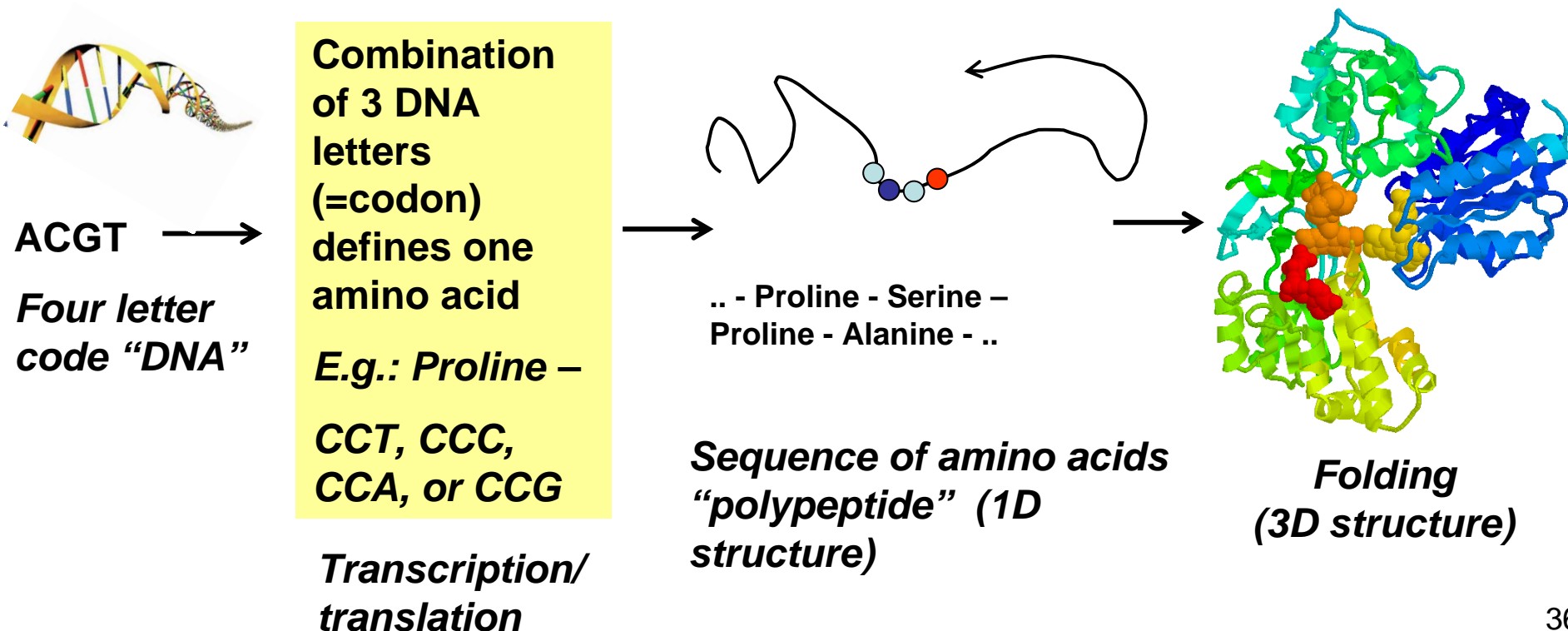
Structural makeup of protein materials

*Although very **diverse**, all protein materials have **universal** “protocols” of how they are made*

How protein materials are made—the genetic code

- Proteins: Encoded by DNA (three “letters”), utilize 20 basic building blocks (amino acids) to form polypeptides
- Polypeptides arrange in complex folded 3D structures with specific properties

1D structure transforms into complex 3D folded configuration



Alpha-helix (abbreviated as AH)

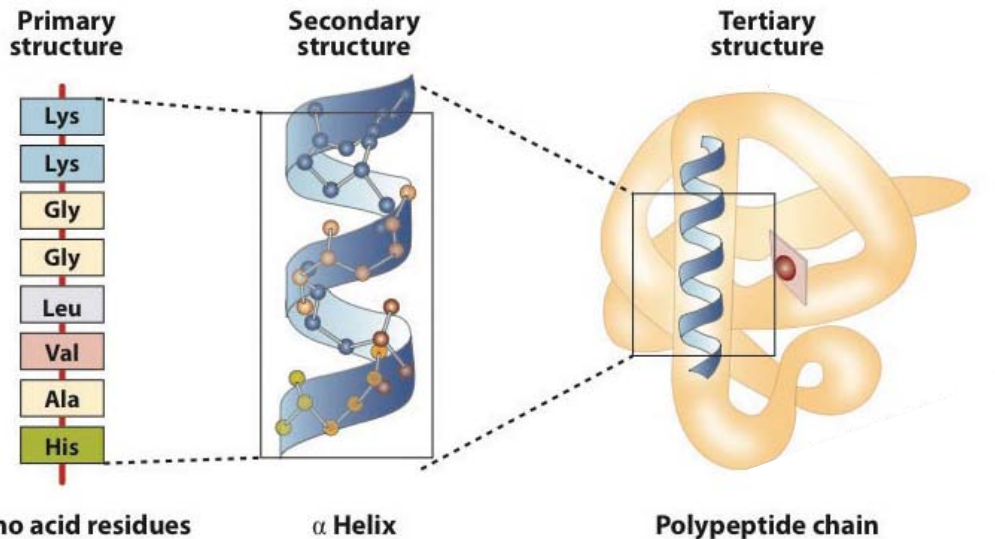
Concept: hydrogen bonding (H-bonding)

e.g. between O and H in H₂O

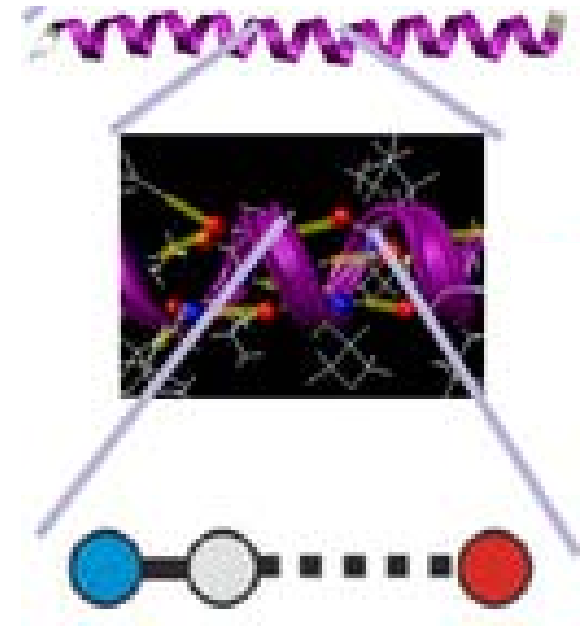
Between N and O in proteins

Drives formation of helical structures

AHs found in: **hair, cells, wool, skin, etc.**

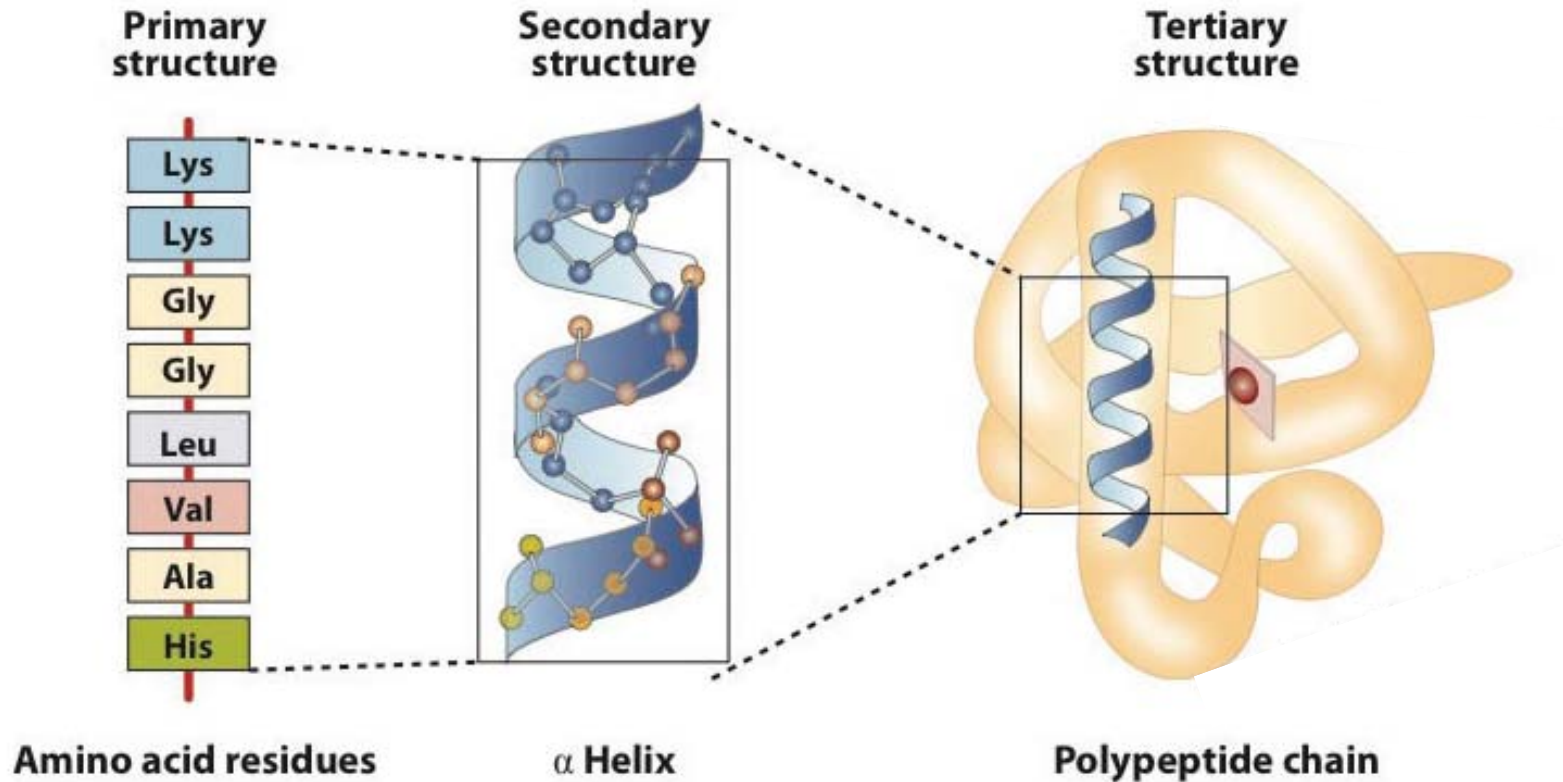


Adapted from Ball, D., Hill, J., et al. *The Basics of General, Organic, and Biological Chemistry*. Flatworld Knowledge, 2011. Courtesy of Flatworld Knowledge.



Source: Qin, Z., L. Kreplak, and M. Buehler. "Hierarchical structure controls nanomechanical properties of vimentin intermediate filaments." *PLoS ONE* (2009). License CC BY.

Primary, secondary, tertiary structure



Adapted from Ball, D., Hill, J., and R. Scott. *The Basics of General, Organic, and Biological Chemistry*. Flatworld Knowledge, 2011. Courtesy of Flatworld Knowledge.

Beta-sheets (abbreviated as BS)

Beta-sheet

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Found in many mechanically relevant proteins

Spider silk

Fibronectin

Titin (muscle tissue)

Amyloids (Alzheimer's disease)

Amyloid proteins (Alzheimer's disease)

Please see Fig. 8 from http://web.mit.edu/mbuehler/www/papers/final_JCTN_preprint.pdf.

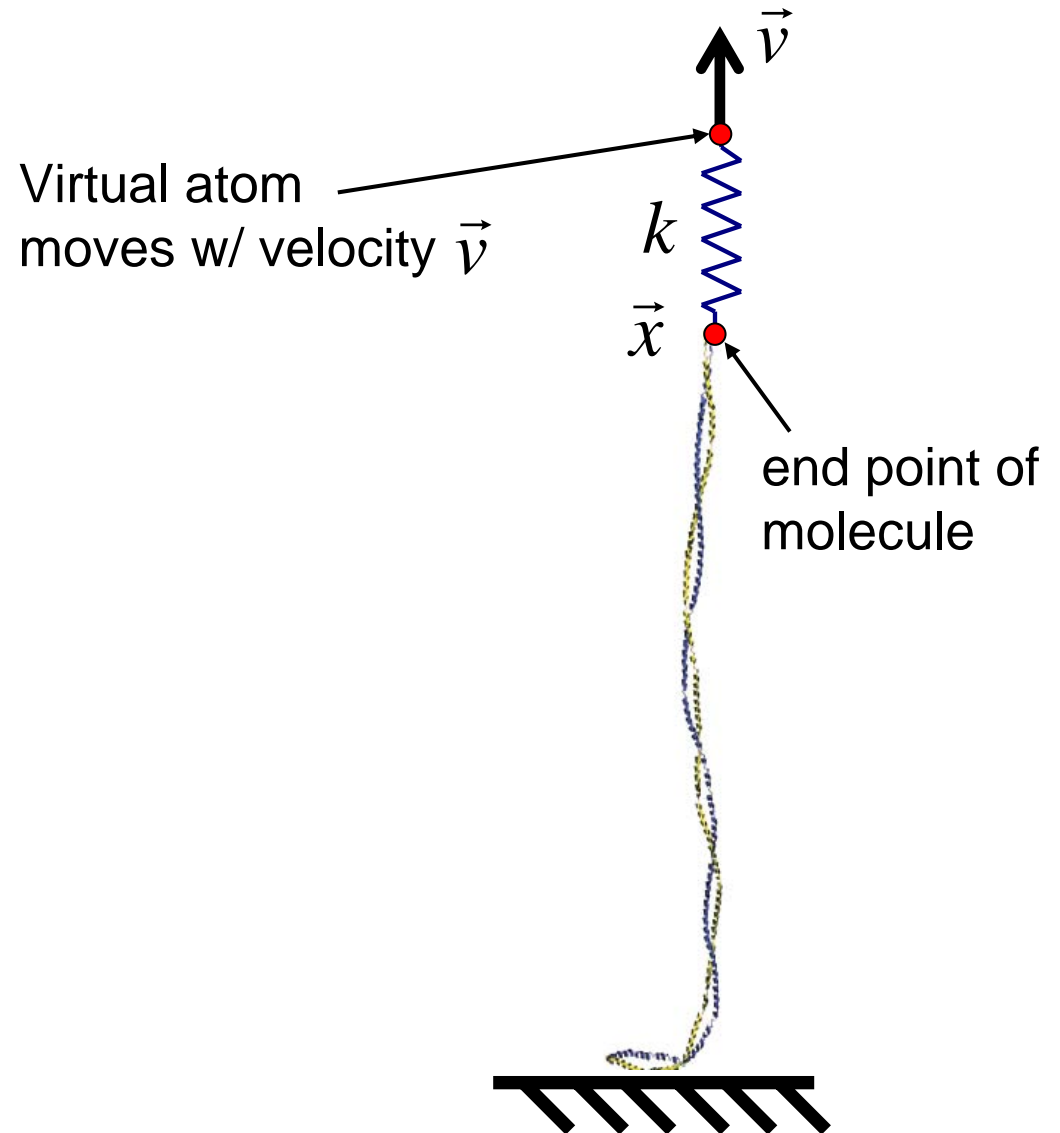
3. Fracture of protein domains – Bell model

How to apply load to a molecule

*(in molecular dynamics
simulations)*

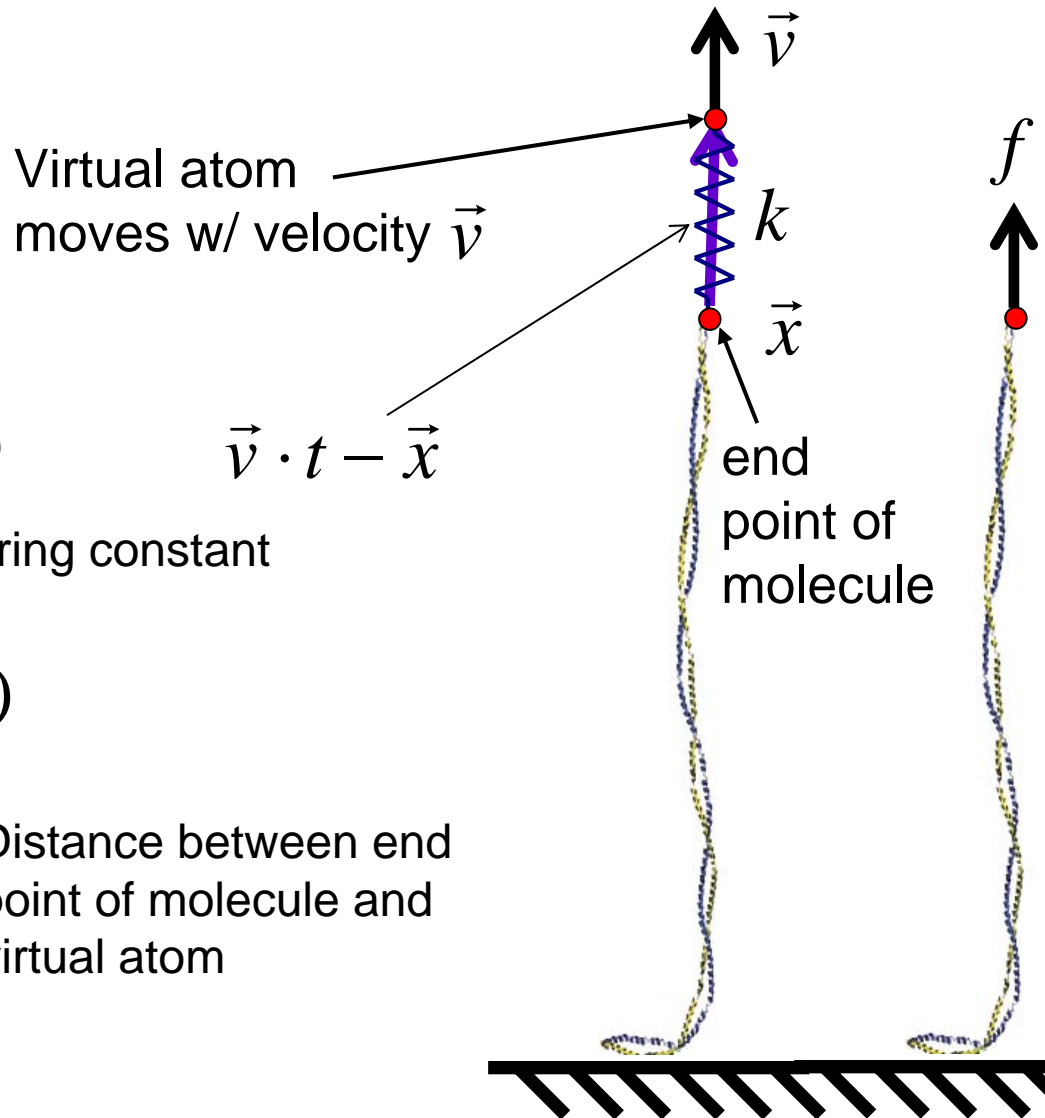
Steered molecular dynamics (SMD)

Steered molecular dynamics used to apply forces to protein structures



Steered molecular dynamics (SMD)

Steered molecular dynamics used to apply forces to protein structures



$$f = k(v \cdot t - x)$$

$$\vec{v} \cdot t - \vec{x}$$

SMD spring constant

$$\vec{f} = k(\vec{v} \cdot t - \vec{x})$$

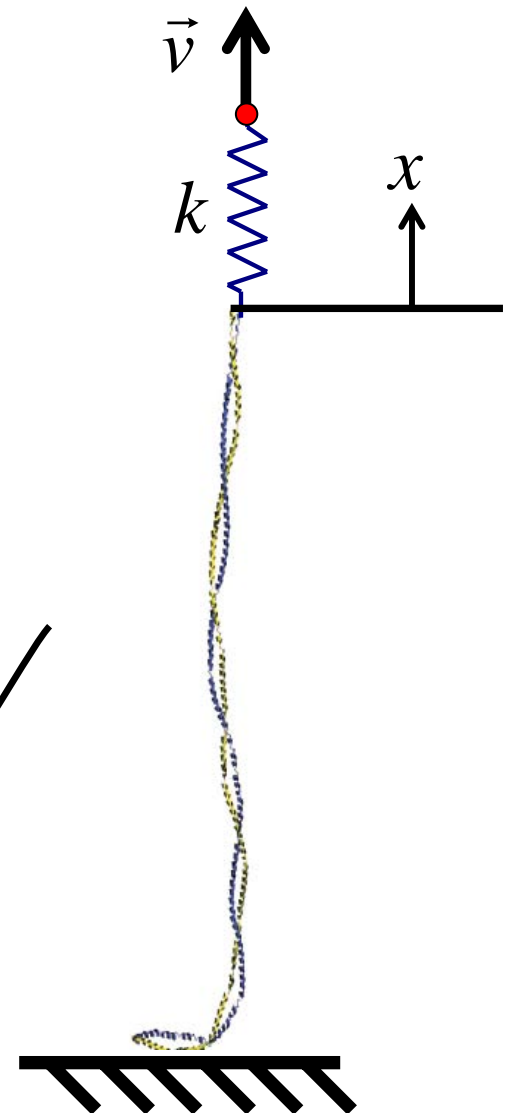
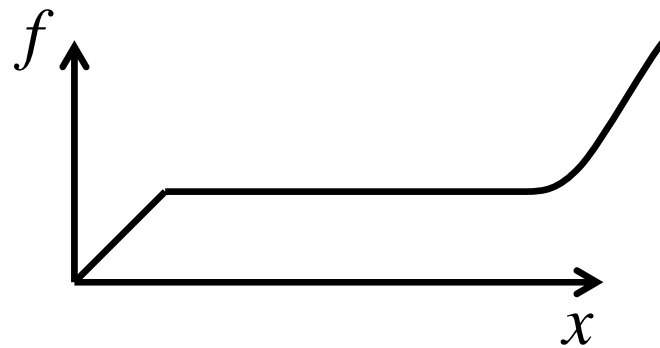
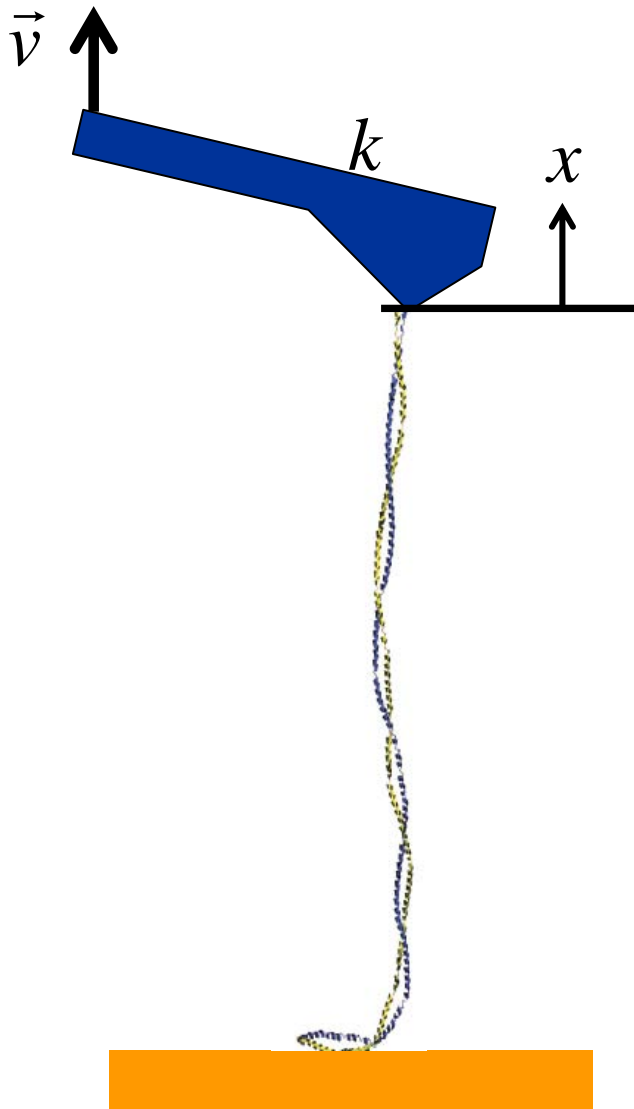
Distance between end point of molecule and virtual atom

time

SMD deformation speed vector

SMD mimics AFM single molecule experiments

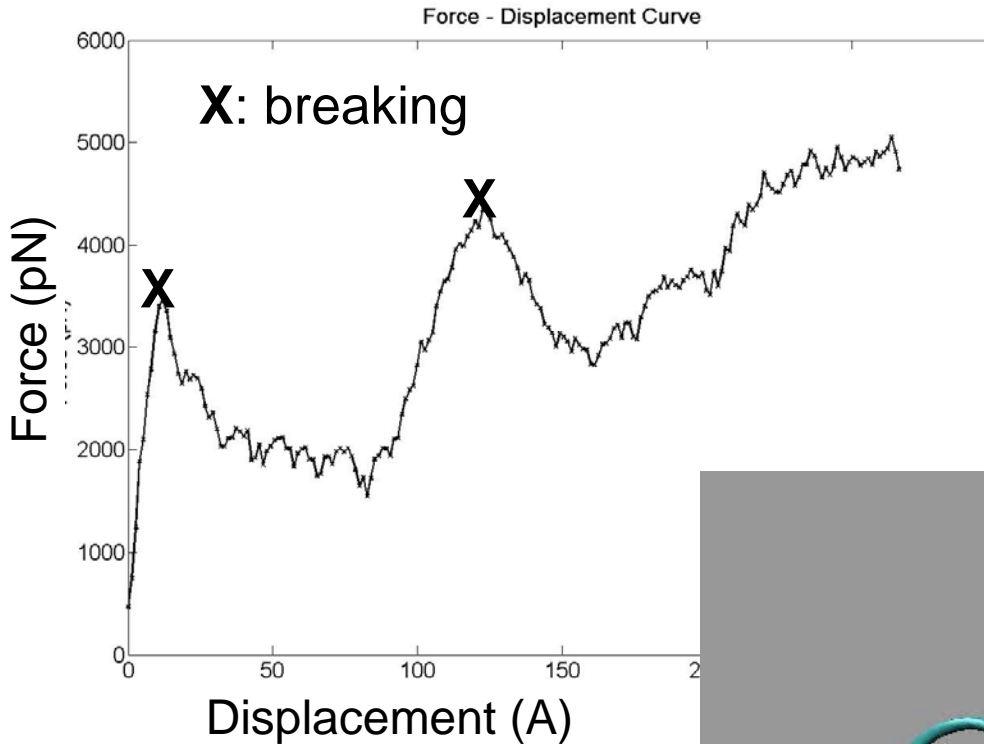
Atomic force microscope



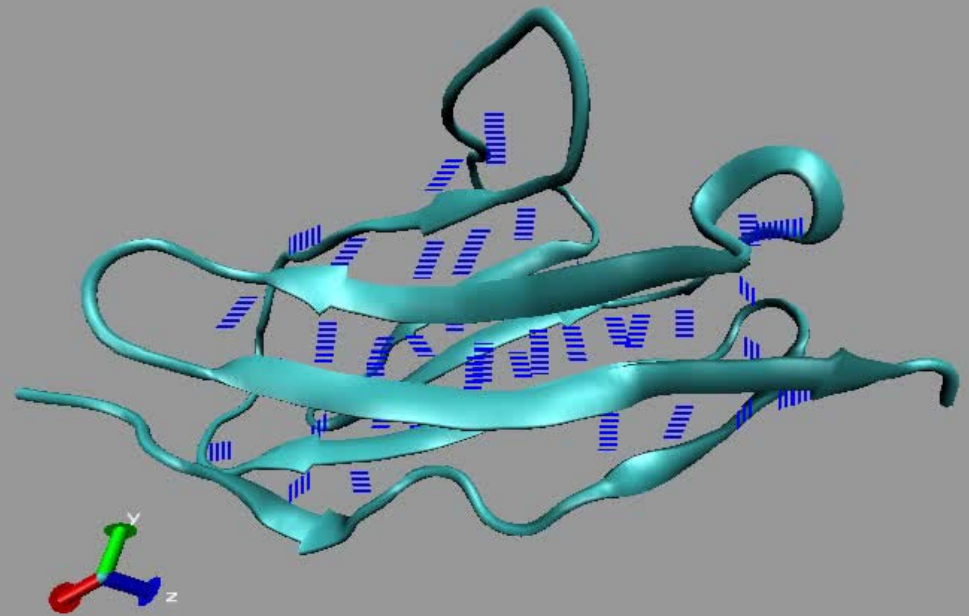
SMD is a useful approach to probe the nanomechanics of proteins (elastic deformation, “plastic” – permanent deformation, etc.)

Example: titin unfolding (CHARMM force field)

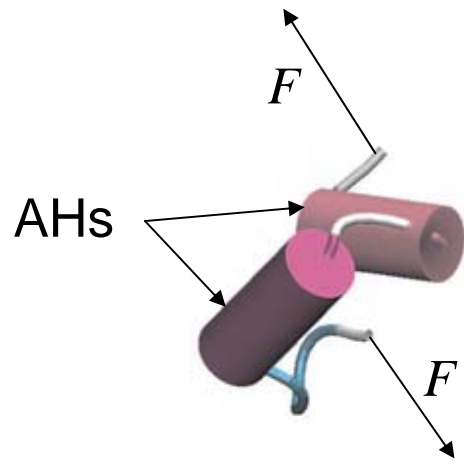
Unfolding of titin molecule



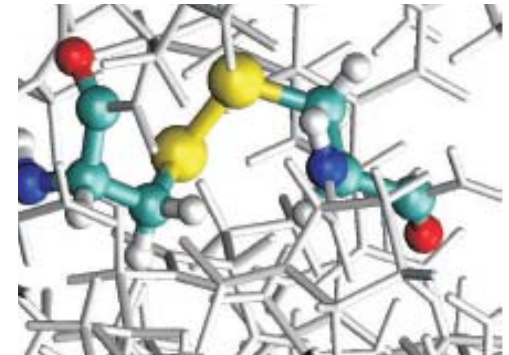
Titin I27 domain: Very resistant to unfolding due to parallel H-bonded strands



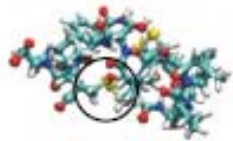
Protein unfolding - ReaxFF



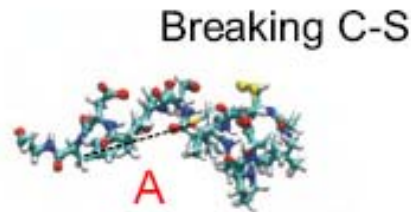
PnIB 1AKG



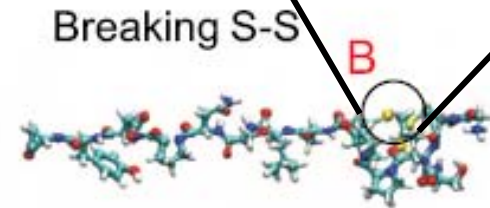
(a)



(b)



(c)



(d)



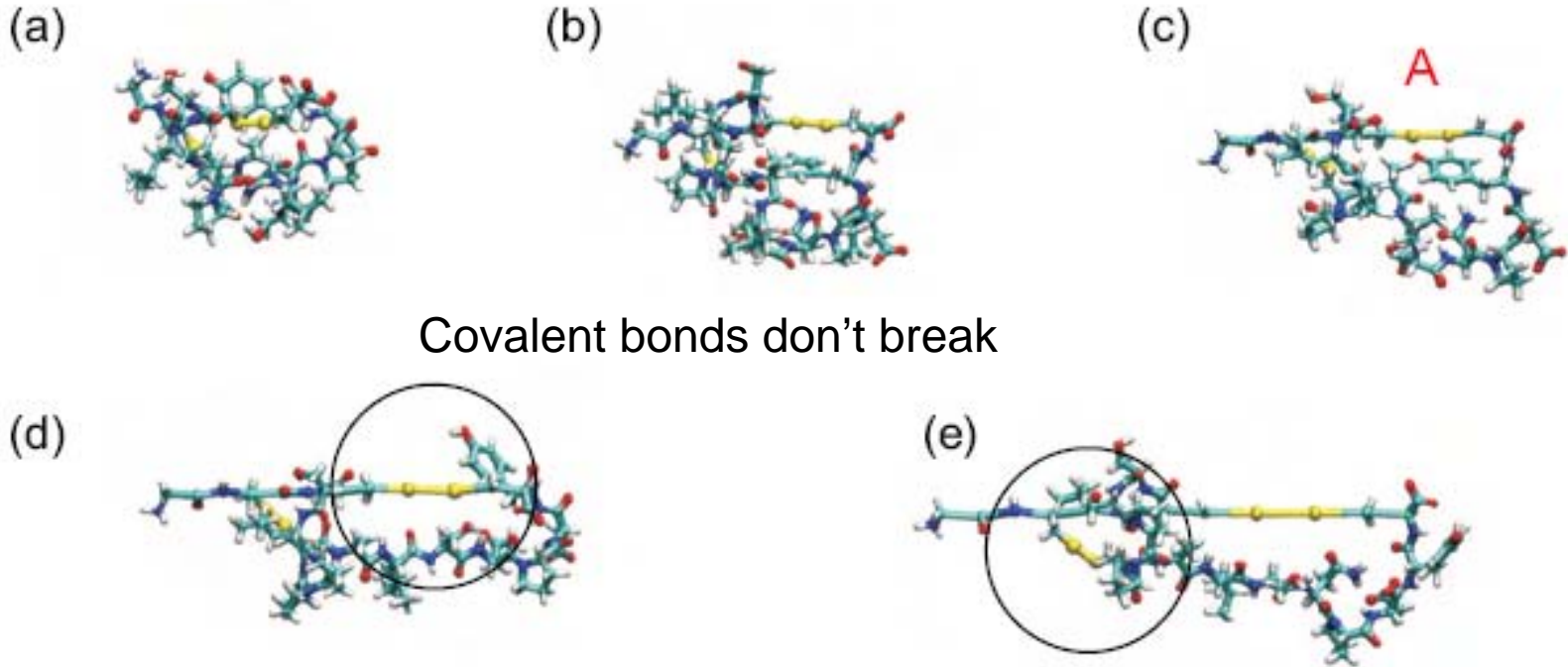
(e)



ReaxFF modeling

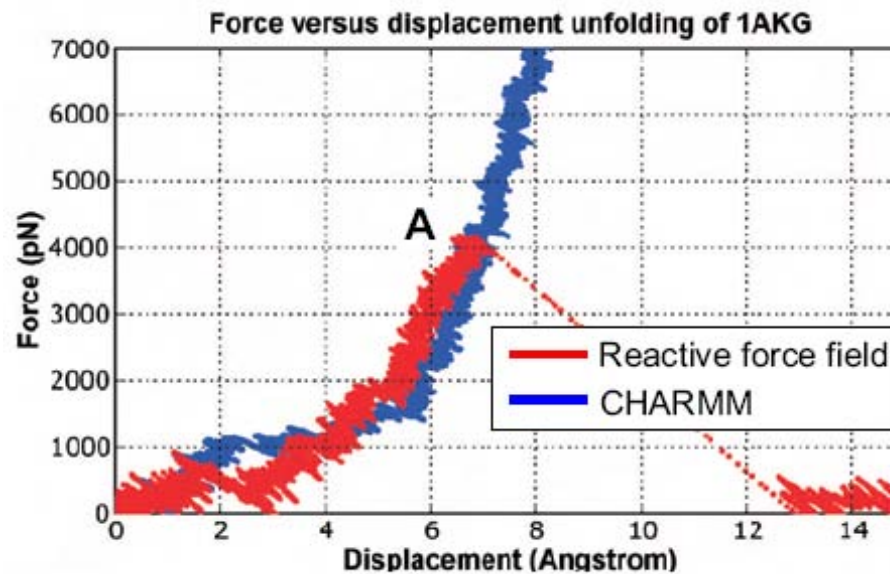
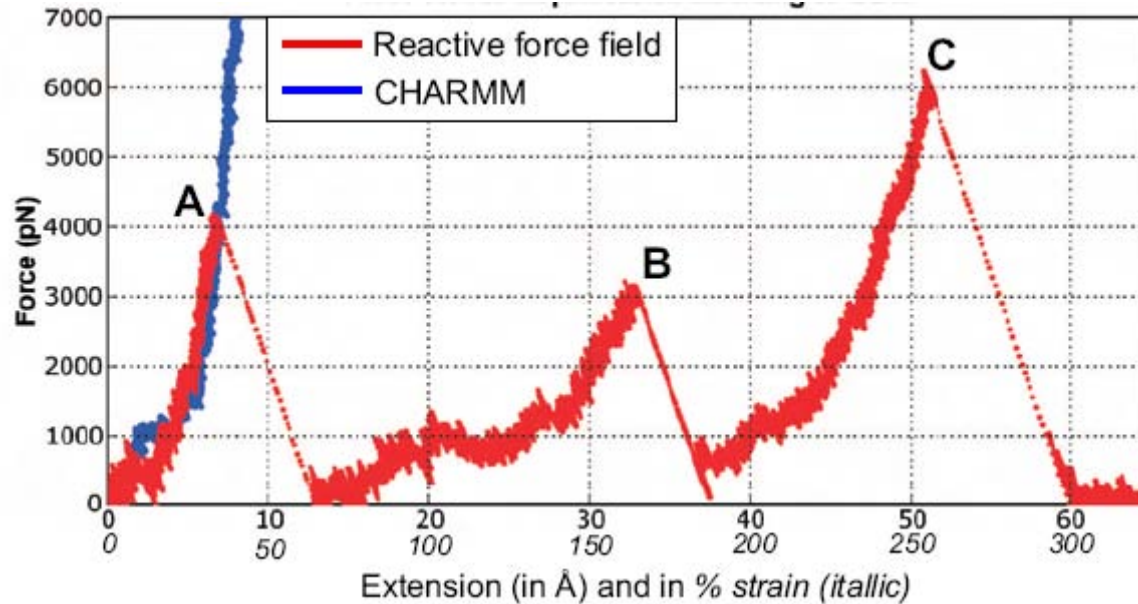
Breaking C-C

Protein unfolding - CHARMM



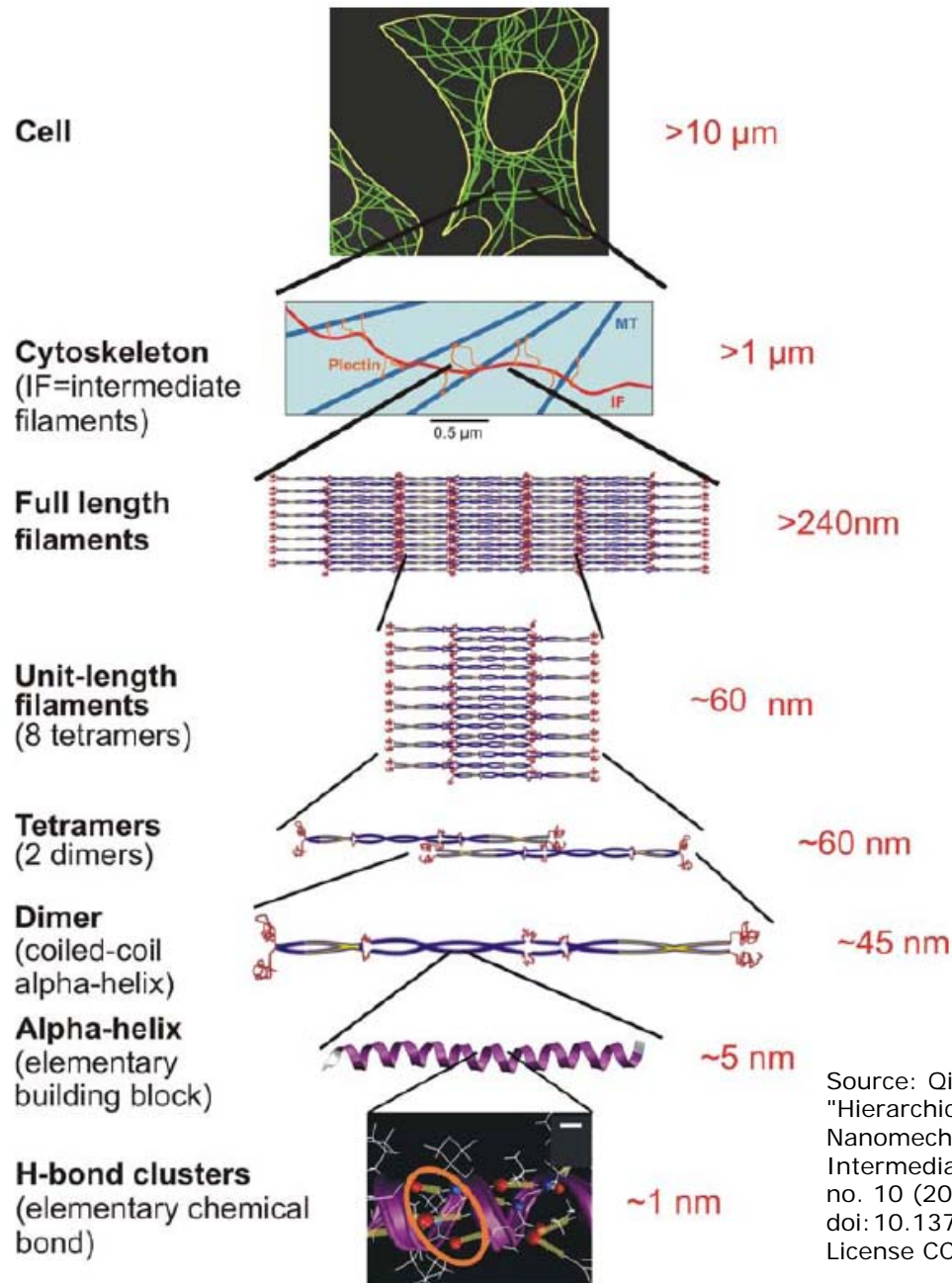
CHARMM modeling

Comparison – CHARMM vs. ReaxFF

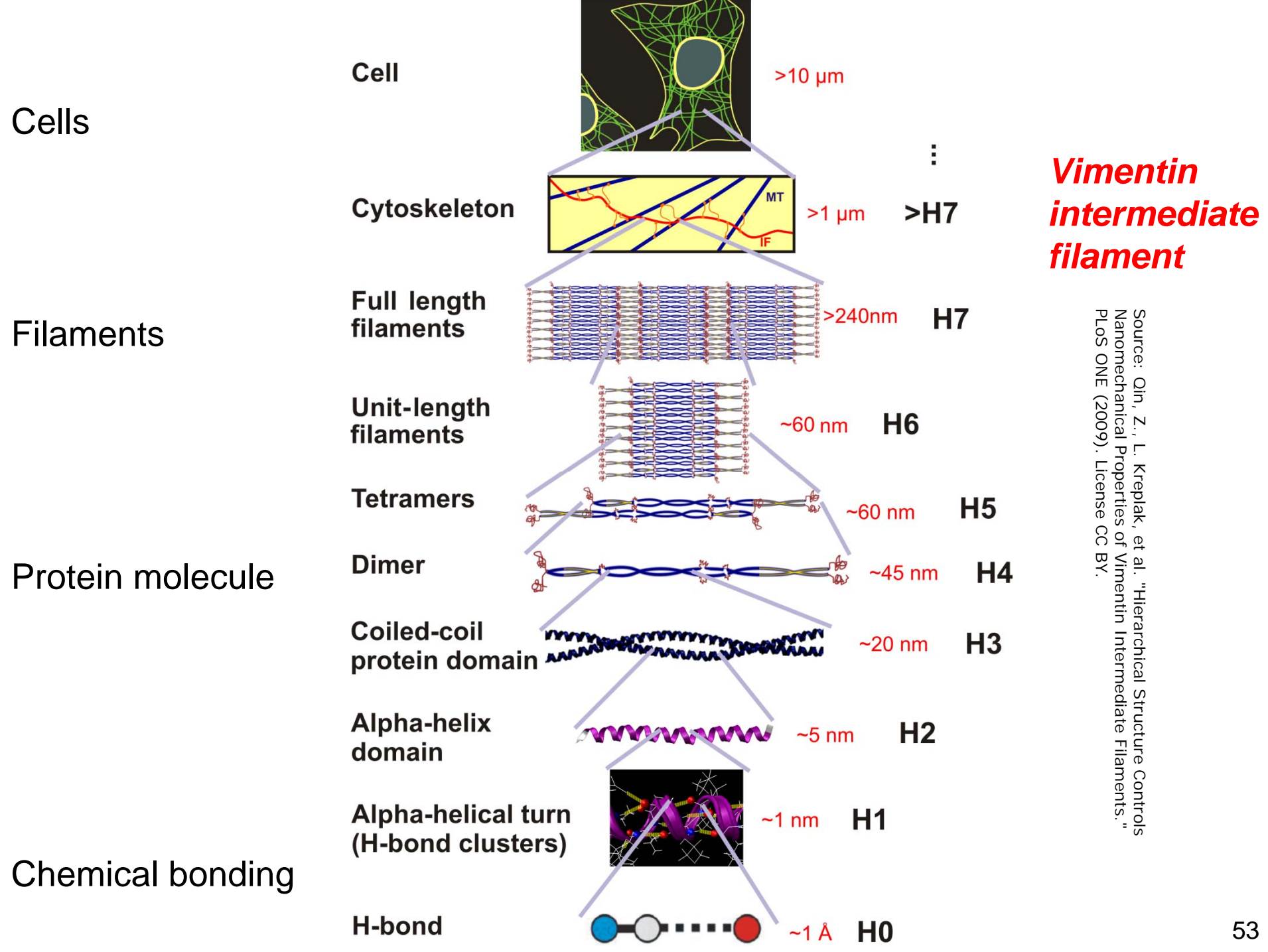


Application to alpha-helical proteins

Vimentin intermediate filaments

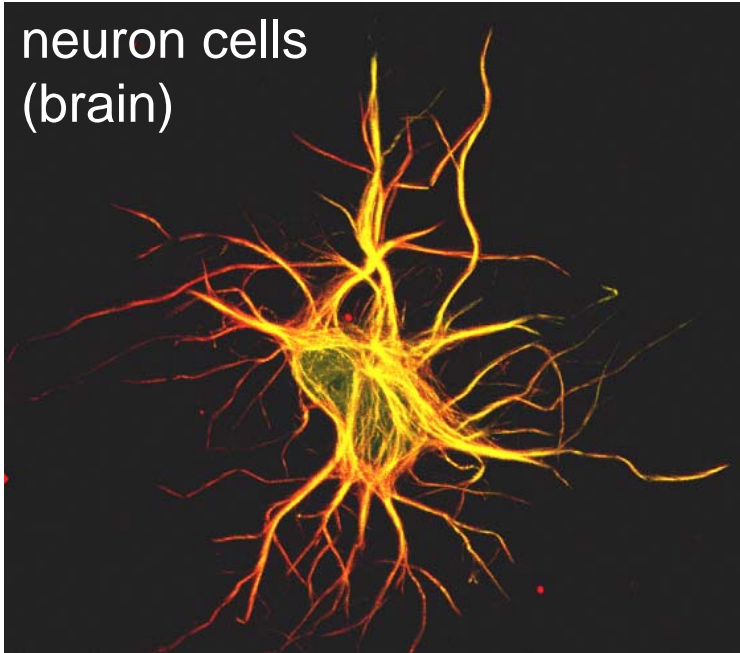


Source: Qin, Z., L. Kreplak, et al. "Hierarchical Structure Controls Nanomechanical Properties of Vimentin Intermediate Filaments." *PLoS ONE* 4, no. 10 (2009). doi:10.1371/journal.pone.0007294. License CC BY.



Intermediate filaments – occurrence

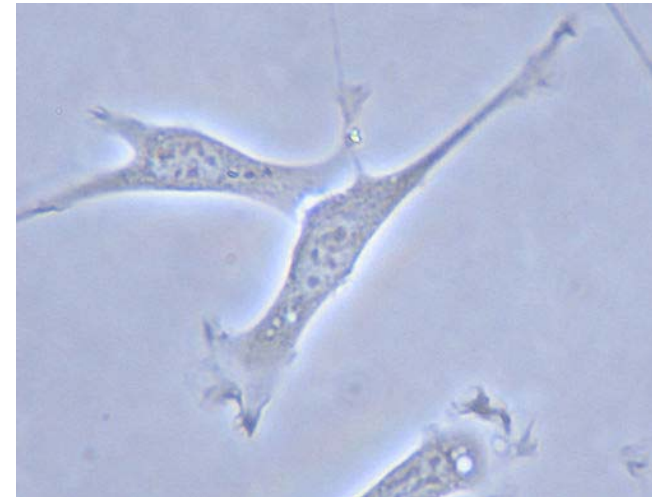
neuron cells
(brain)



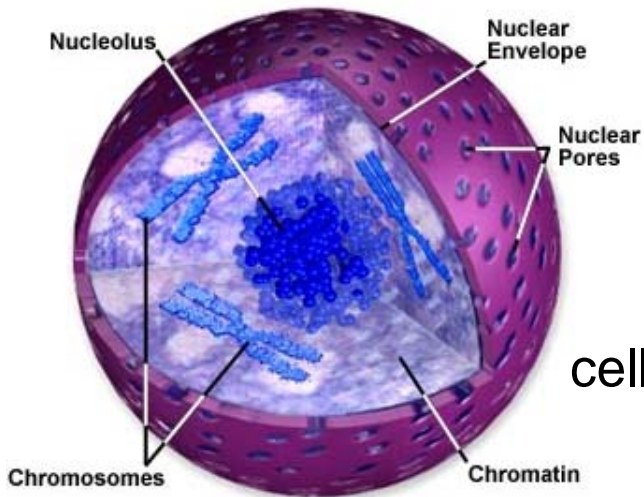
hair, hoof



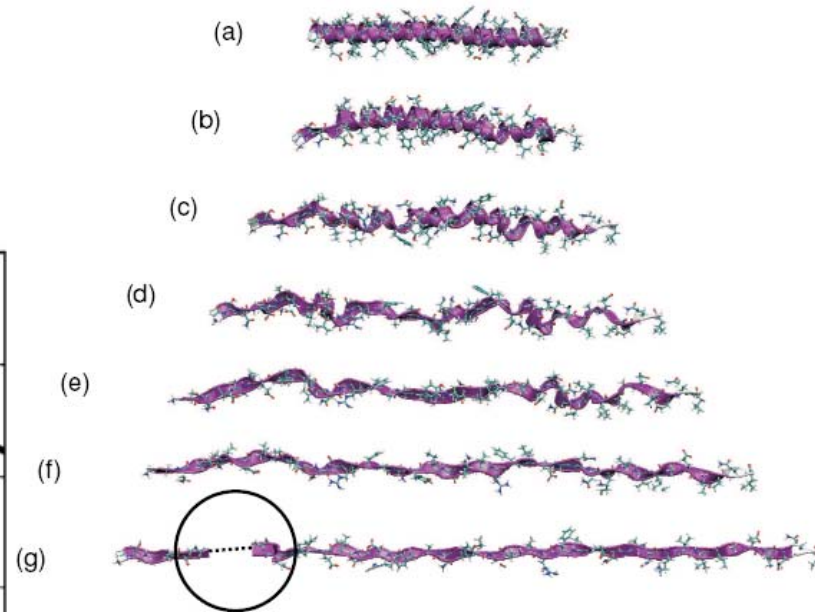
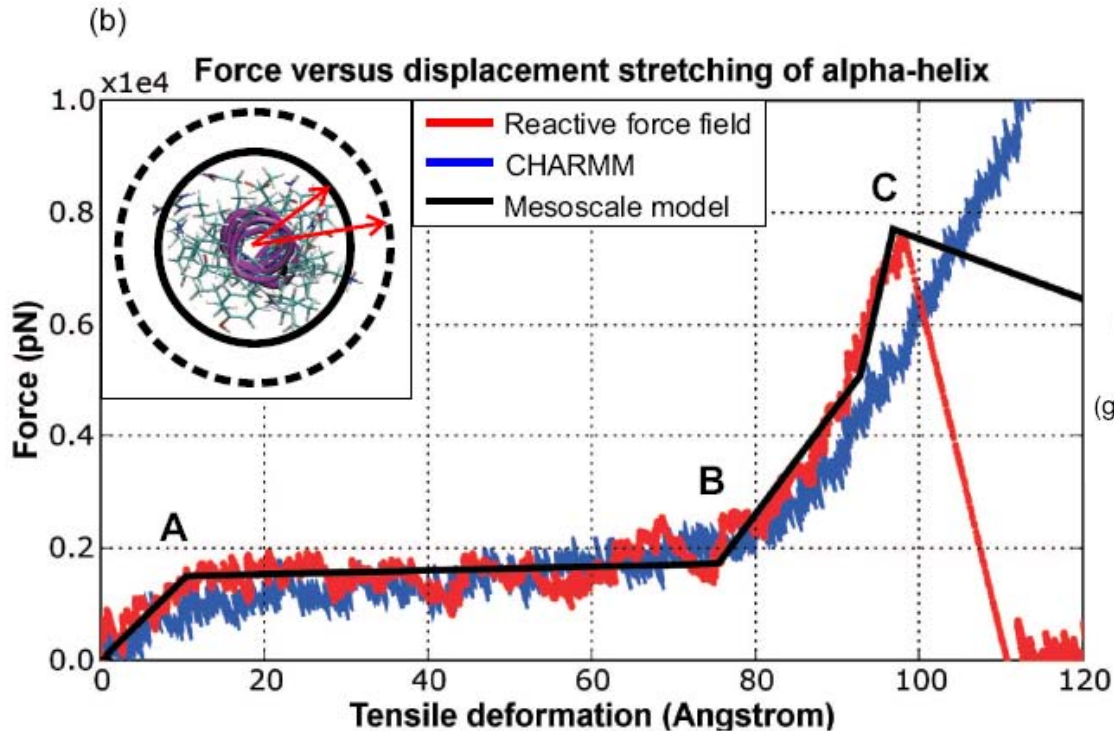
fibroblast cells
(make collagen)



cell nucleus



Alpha-helical protein: stretching



ReaxFF modeling of AH stretching

A: First H-bonds break (turns open)

B: Stretch covalent backbone

C: Backbone breaks

What about varying pulling speeds?

Variation of pulling speed

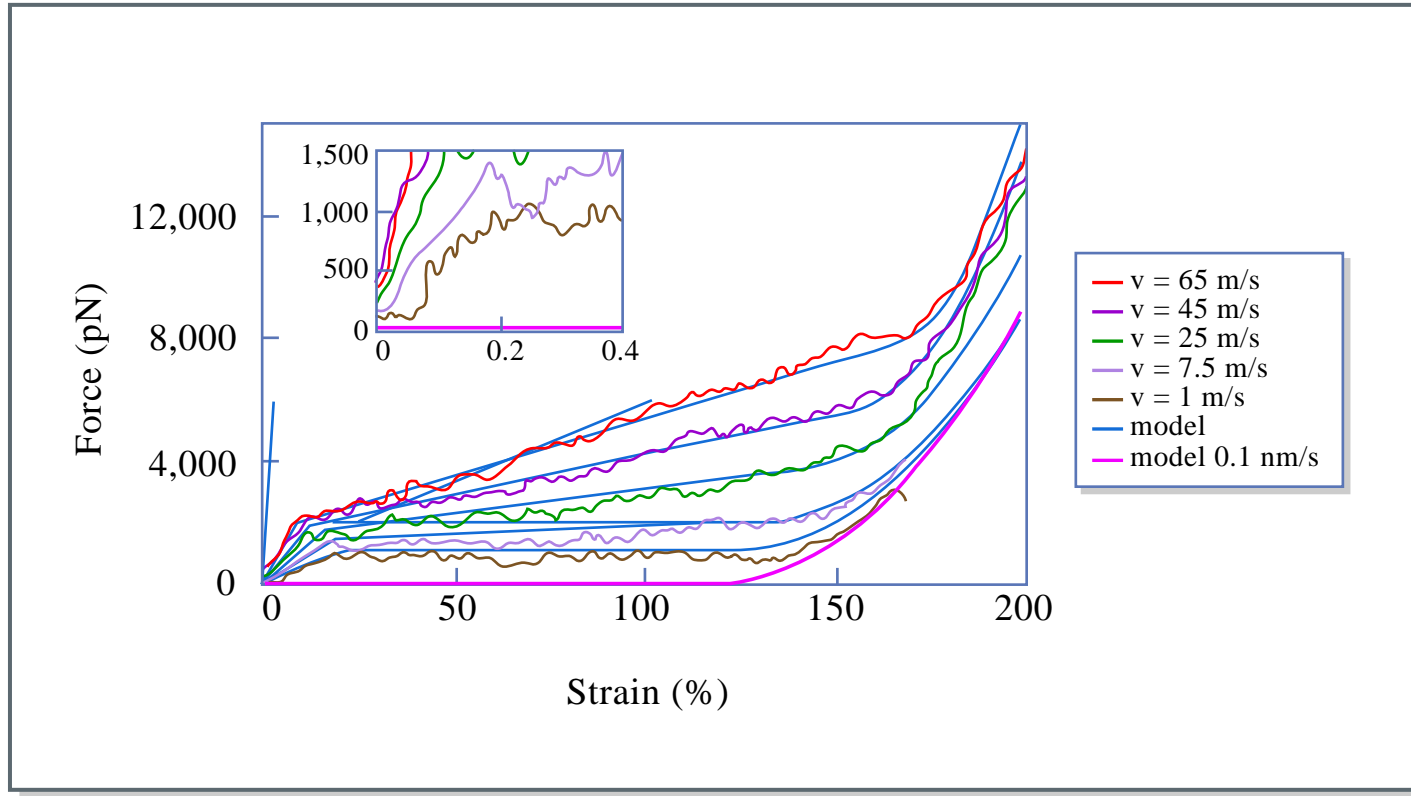
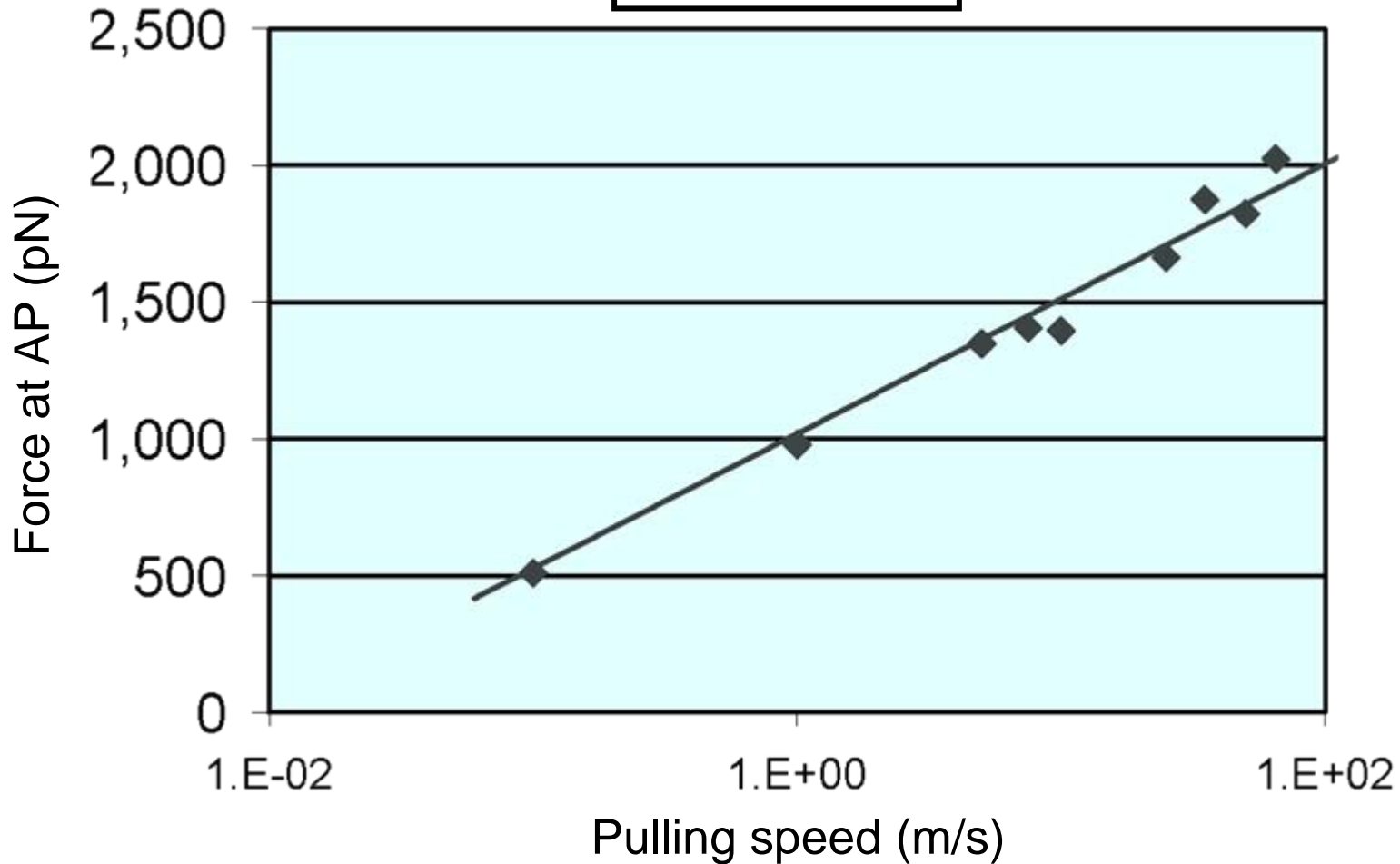


Image by MIT OpenCourseWare. After Ackbarow and Buehler, 2007.

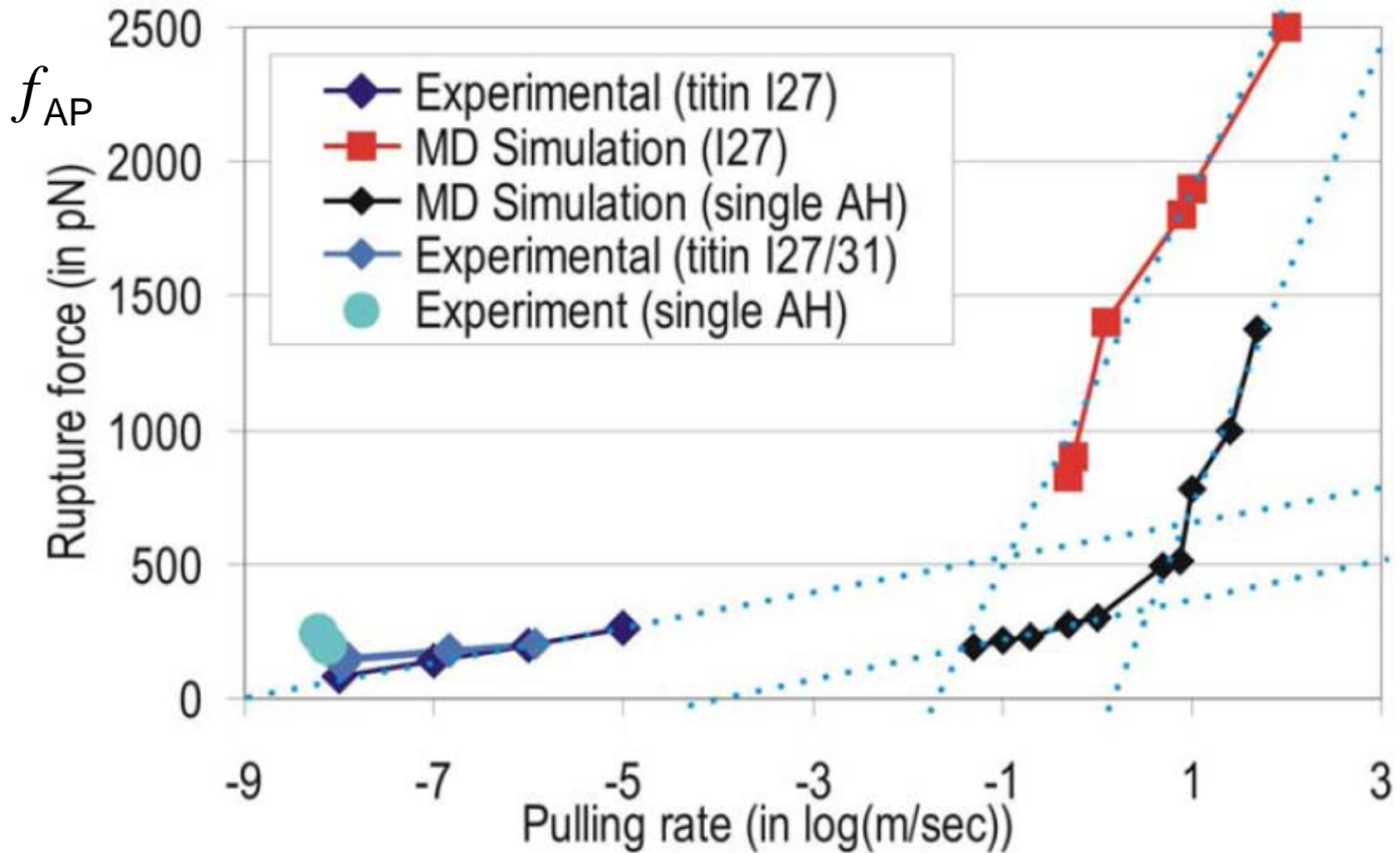
Force at angular point f_{AP} = fracture force

$$f_{AP} \sim \ln v$$



General results...

Rupture force vs. pulling speed



Reprinted by permission from Macmillan Publishers Ltd: Nature Materials.

Source: Buehler, M., and Y. Yung. "Chemomechanical Behaviour of Protein Constituents." *Nature Materials* 8, no. 3 (2009): 175-88. © 2009.

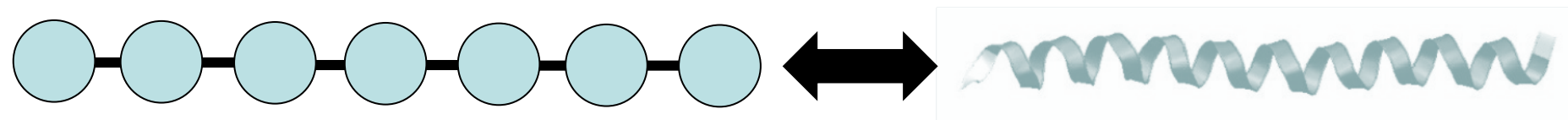
How to make sense of these results?

A few fundamental properties of bonds

- Bonds have a “**bond energy**” (energy barrier to break)
- **Arrhenius relationship** gives probability for energy barrier to be overcome, given a temperature

$$p = \exp\left(-\frac{E_b}{k_B T}\right)$$

- All bonds **vibrate at frequency ω**



Bell model

Probability for bond rupture (Arrhenius relation)

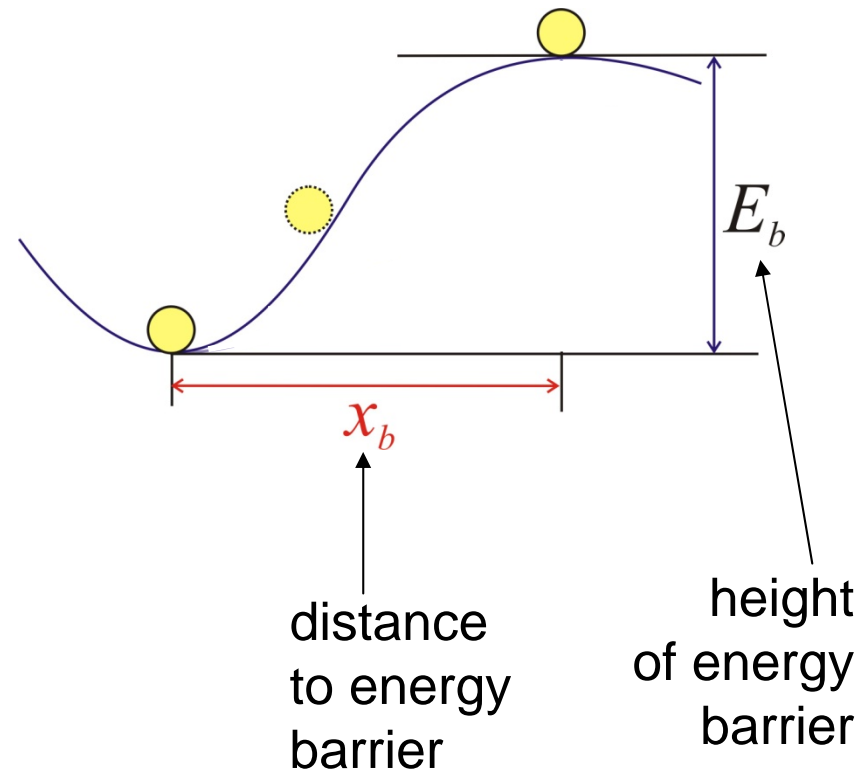
$$p = \exp\left(-\frac{E_b}{k_B T}\right)$$

Boltzmann constant

temperature



“bond”



Bell model

Probability for bond rupture (Arrhenius relation) $f = f_{AP}$

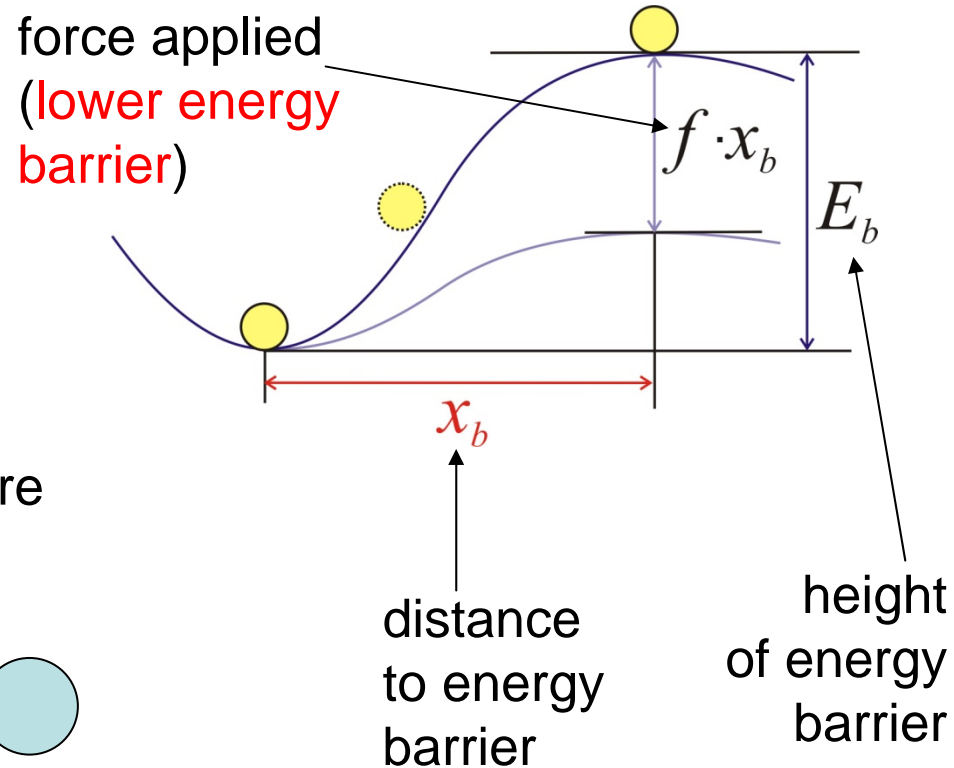
$$p = \exp\left(-\frac{E_b - f \cdot x_b}{k_B T}\right)$$

Boltzmann constant

temperature



“bond”



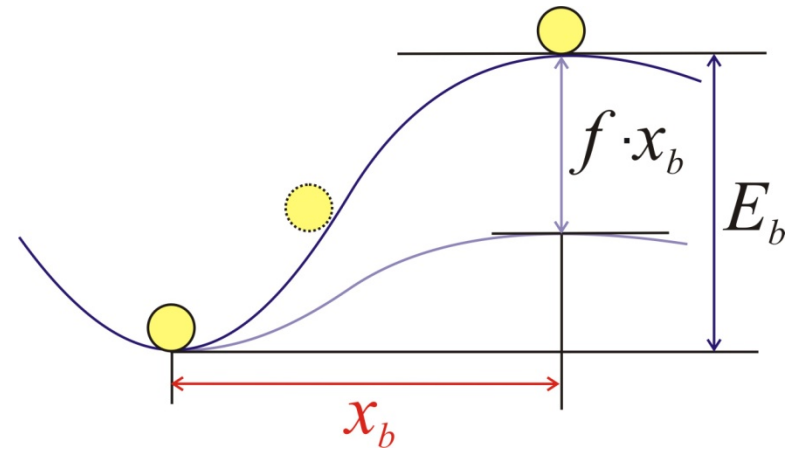
Bell model

Probability for bond rupture (Arrhenius relation)

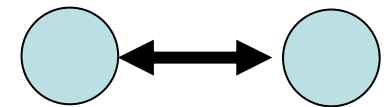
$$p = \exp\left(-\frac{E_b - f \cdot x_b}{k_B T}\right)$$

Off-rate = probability times vibrational frequency

$$\chi = \omega_0 \cdot p$$



$$\omega_0 = 1 \times 10^{13} \text{ 1/sec}$$



bond vibrations

Bell model

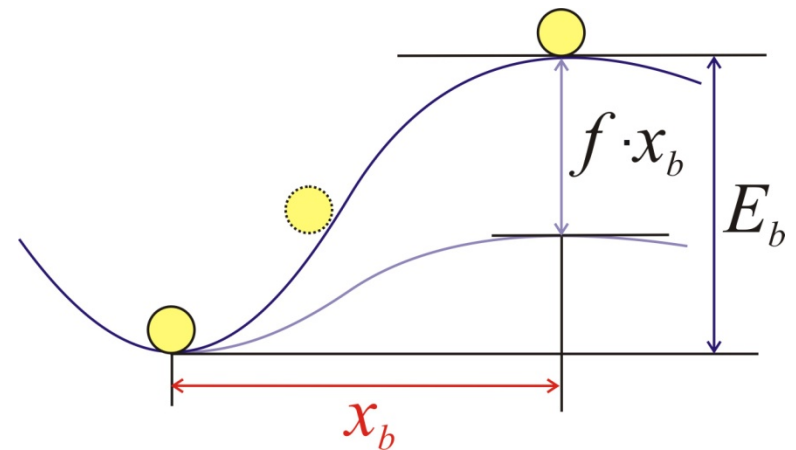
Probability for bond rupture (Arrhenius relation)

$$p = \exp\left(-\frac{E_b - f \cdot x_b}{k_B T}\right)$$

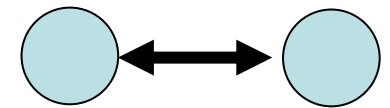
Off-rate = probability times vibrational frequency

$$\chi = \omega_0 \cdot p = \omega_0 \cdot \exp\left(-\frac{(E_b - f \cdot x_b)}{k_b \cdot T}\right)$$

“How often bond breaks per unit time”



$$\omega_0 = 1 \times 10^{13} \text{ 1/sec}$$



bond vibrations

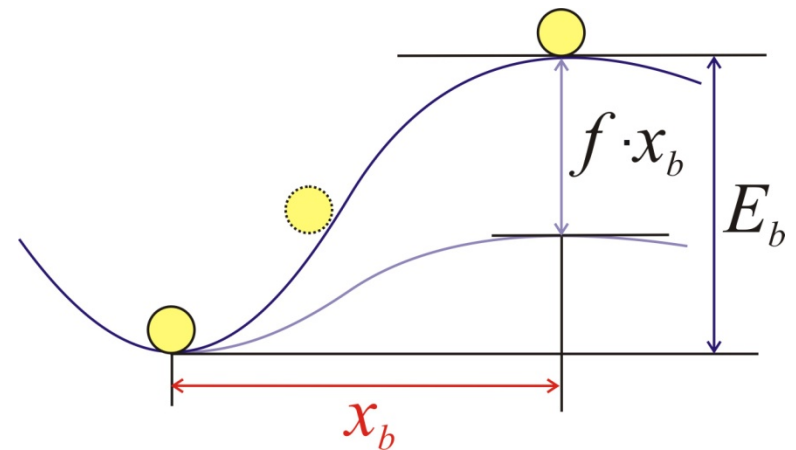
Bell model

Probability for bond rupture (Arrhenius relation)

$$p = \exp\left(-\frac{E_b - f \cdot x_b}{k_B T}\right)$$

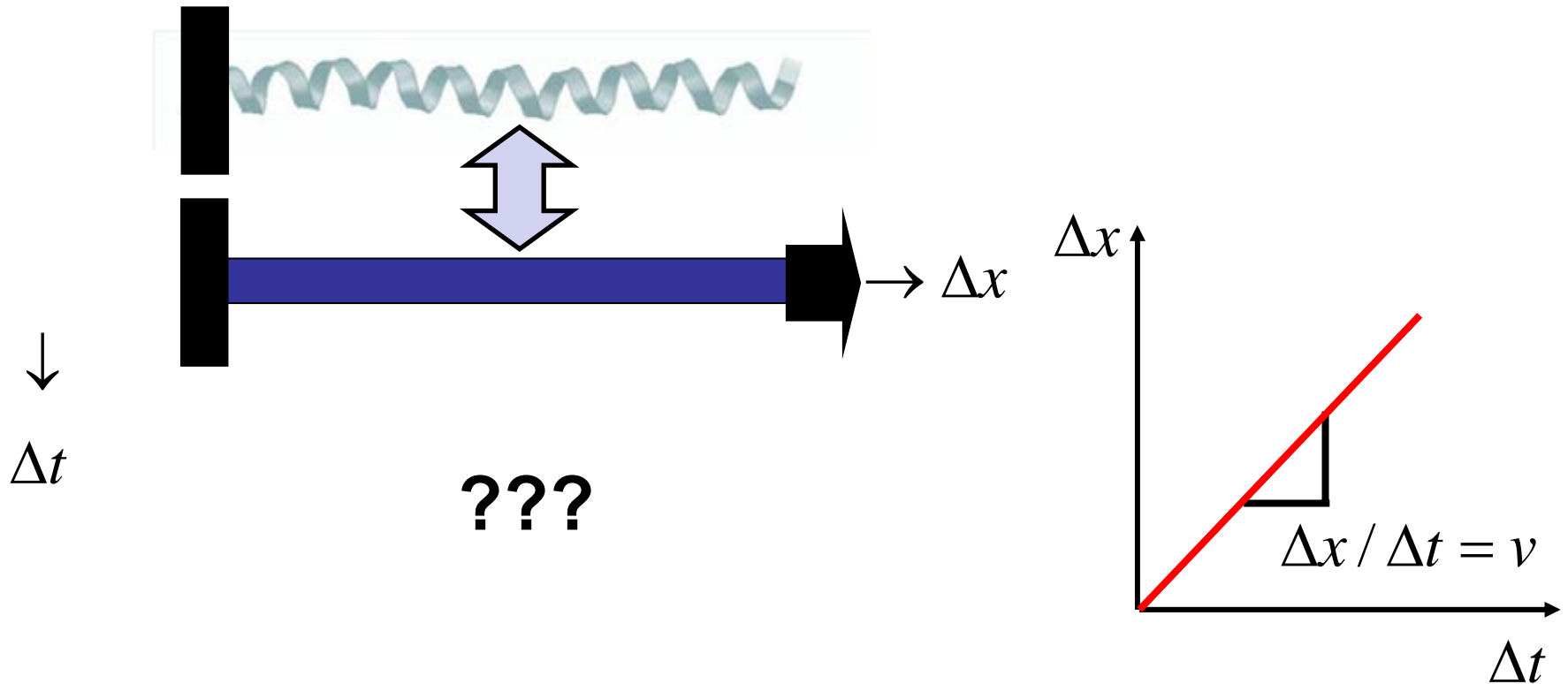
Off-rate = probability times vibrational frequency

$$\chi = \omega_0 \cdot p = \omega_0 \cdot \exp\left(-\frac{(E_b - f \cdot x_b)}{k_b \cdot T}\right) = \frac{1}{\tau} \quad \omega_0 = 1 \times 10^{13} \text{ 1/sec}$$



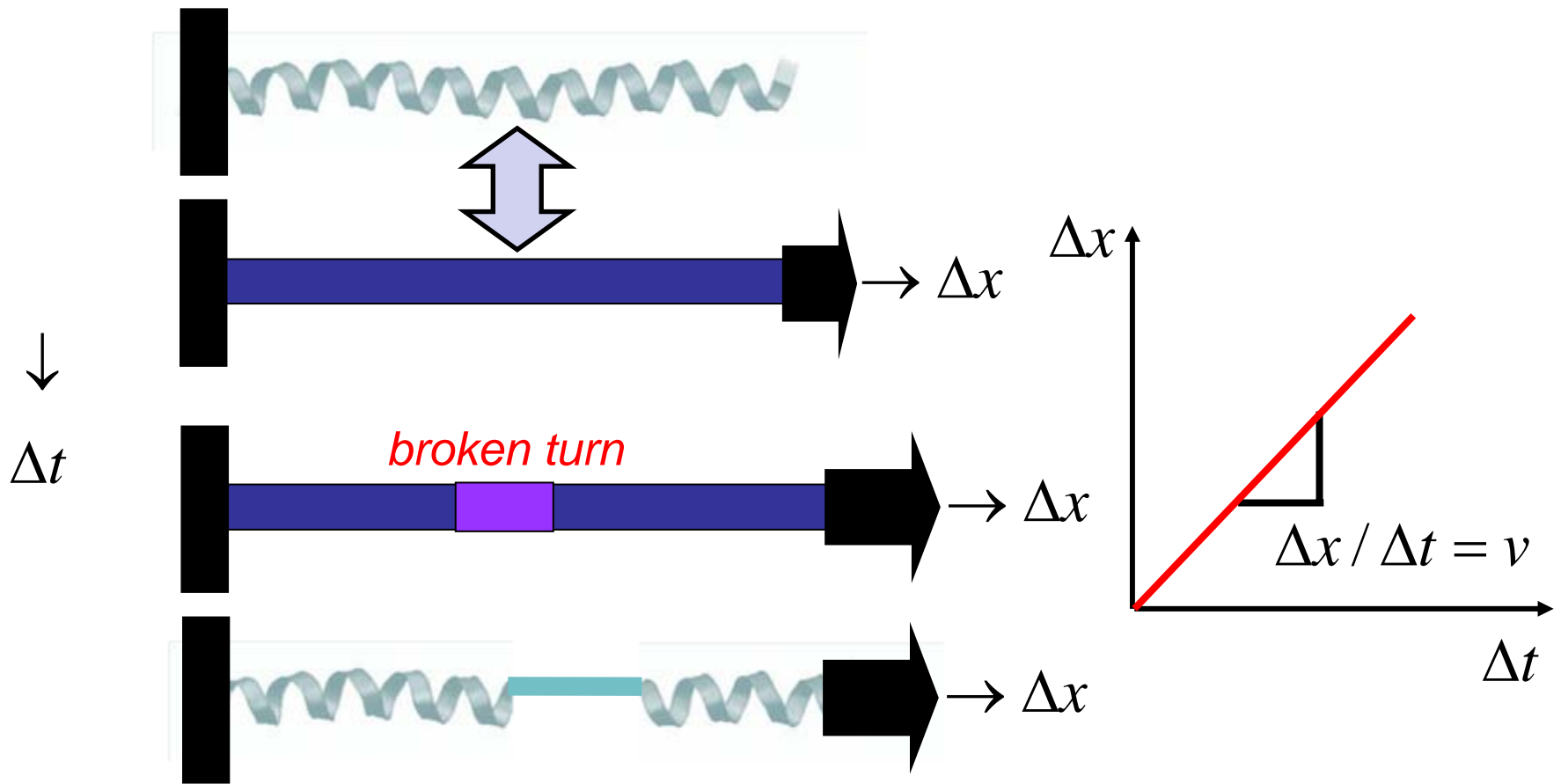
τ = **bond lifetime**
(inverse of off-rate)

Bell model



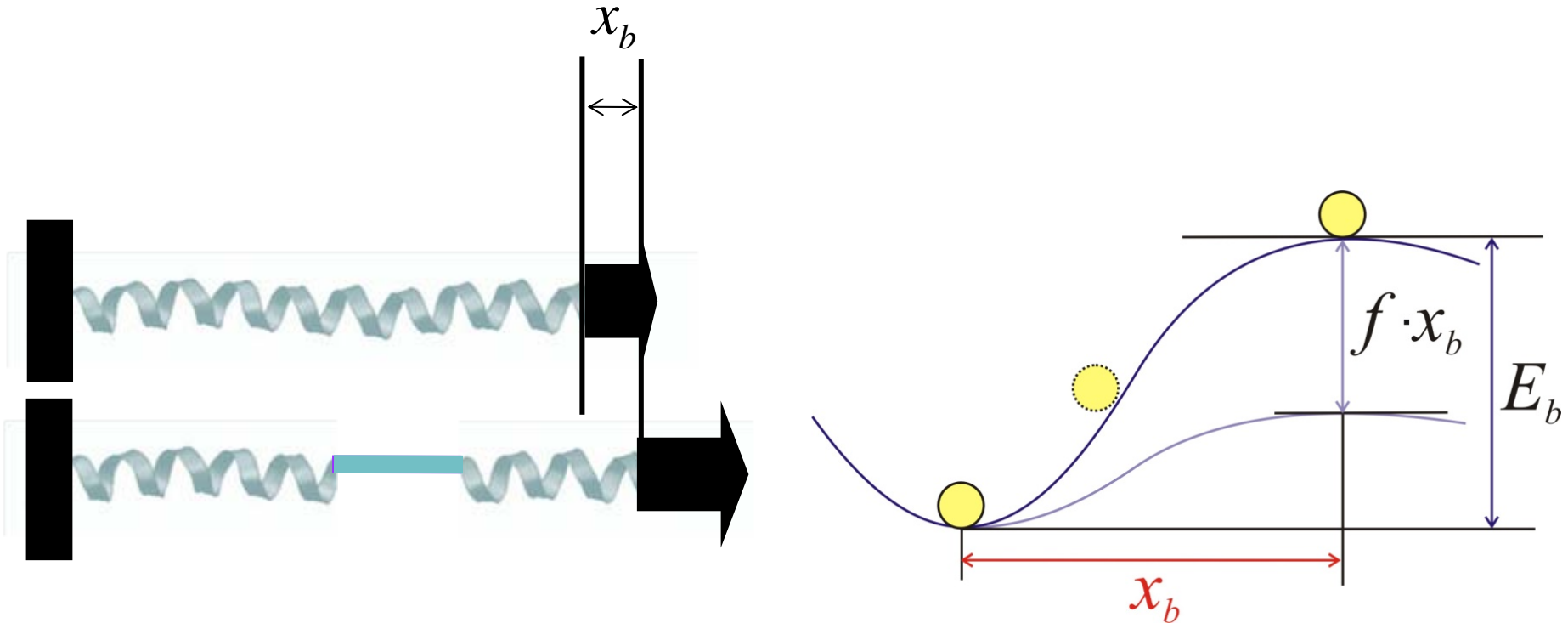
$$\Delta x / \Delta t = v \quad \text{pulling speed (at end of molecule)}$$

Bell model



$$\Delta x / \Delta t = v \quad \text{pulling speed (at end of molecule)}$$

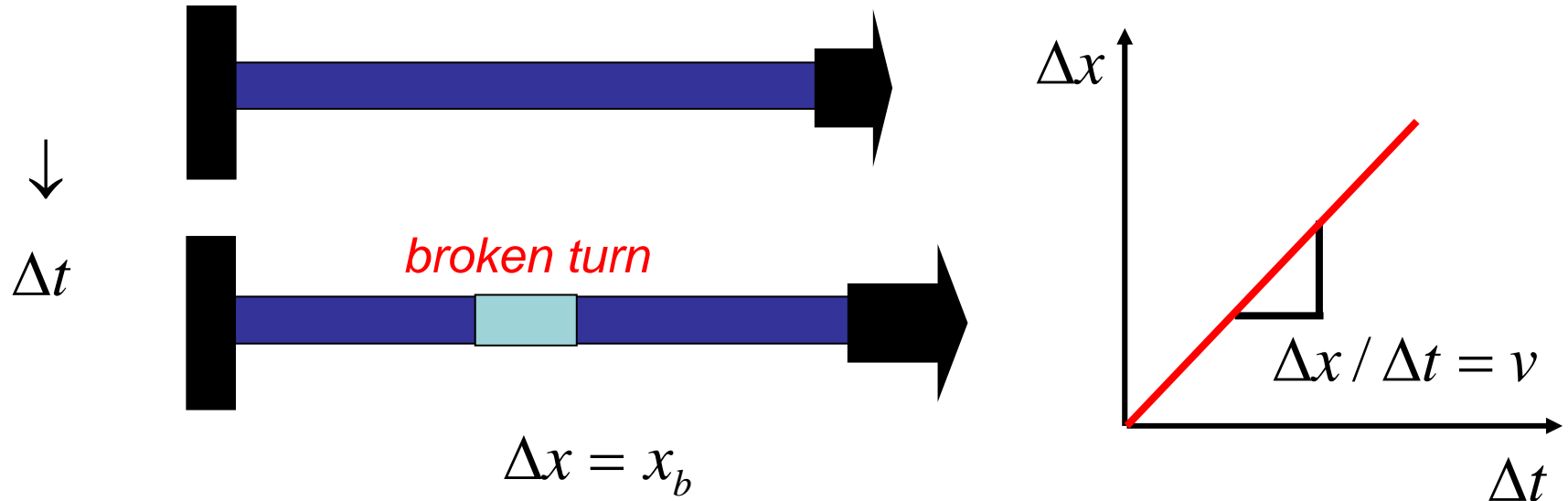
Structure-energy landscape link



$$\Delta x = x_b$$

$$\Delta t = \tau \quad \tau = \left[\omega_0 \cdot \exp\left(-\frac{(E_b - f \cdot x_b)}{k_b \cdot T} \right) \right]^{-1}$$

Bell model



Bond breaking at x_b (lateral applied displacement):

$$\underbrace{\chi \cdot x_b}_{= 1/\tau} = \omega_0 \cdot \exp\left(-\frac{(E_b - f \cdot x_b)}{k_b \cdot T}\right) \cdot x_b = \Delta x / \Delta t = v \quad \uparrow \text{pulling speed}$$

Bell model

$$\omega_0 \cdot \exp\left(-\frac{(E_b - f \cdot x_b)}{k_b \cdot T}\right) \cdot x_b = \nu$$

Solve this expression for f :

Bell model

$$\omega_0 \cdot \exp\left(-\frac{(E_b - f \cdot x_b)}{k_b \cdot T}\right) \cdot x_b = v$$

Solve this expression for f :

$$-\frac{(E_b - f \cdot x_b)}{k_b \cdot T} + \ln(\omega_0 \cdot x_b) = \ln v \quad \leftarrow \ln(..)$$

$$-E_b + f \cdot x_b = k_b \cdot T (\ln v - \ln(\omega_0 \cdot x_b))$$

$$f = \frac{E_b + k_b \cdot T (\ln v - \ln(\omega_0 \cdot x_b))}{x_b} = \frac{k_b \cdot T}{x_b} \ln v + \frac{k_b \cdot T}{x_b} \left(\frac{E_b}{k_b \cdot T} - \ln(\omega_0 \cdot x_b) \right)$$

$$f = \frac{k_b \cdot T}{x_b} \ln v - \frac{k_b \cdot T}{x_b} \left(\ln(\omega_0 \cdot x_b) - \frac{E_b}{k_b \cdot T} \right)$$

$$f = \frac{k_b \cdot T}{x_b} \ln v - \frac{k_b \cdot T}{x_b} \ln \left(\omega_0 \cdot x_b \cdot \exp\left(-\frac{E_b}{k_b \cdot T}\right) \right)$$

Simplification and grouping of variables

*Only system parameters,
[distance/length]*

$$f(v; x_b, E_b) = \frac{k_b \cdot T}{x_b} \cdot \ln v - \frac{k_b \cdot T}{x_b} \cdot \ln \left(\underbrace{\omega_0 \cdot x_b \cdot \exp\left(-\frac{E_b}{k_b \cdot T}\right)}_{\text{grouped}} \right)$$
$$=: v_0 = \omega_0 \cdot x_b \cdot \exp\left(-\frac{E_b}{k_b \cdot T}\right)$$

Bell model

$$\omega_0 \cdot \exp\left(-\frac{(E_b - f \cdot x_b)}{k_b \cdot T}\right) \cdot x_b = v$$

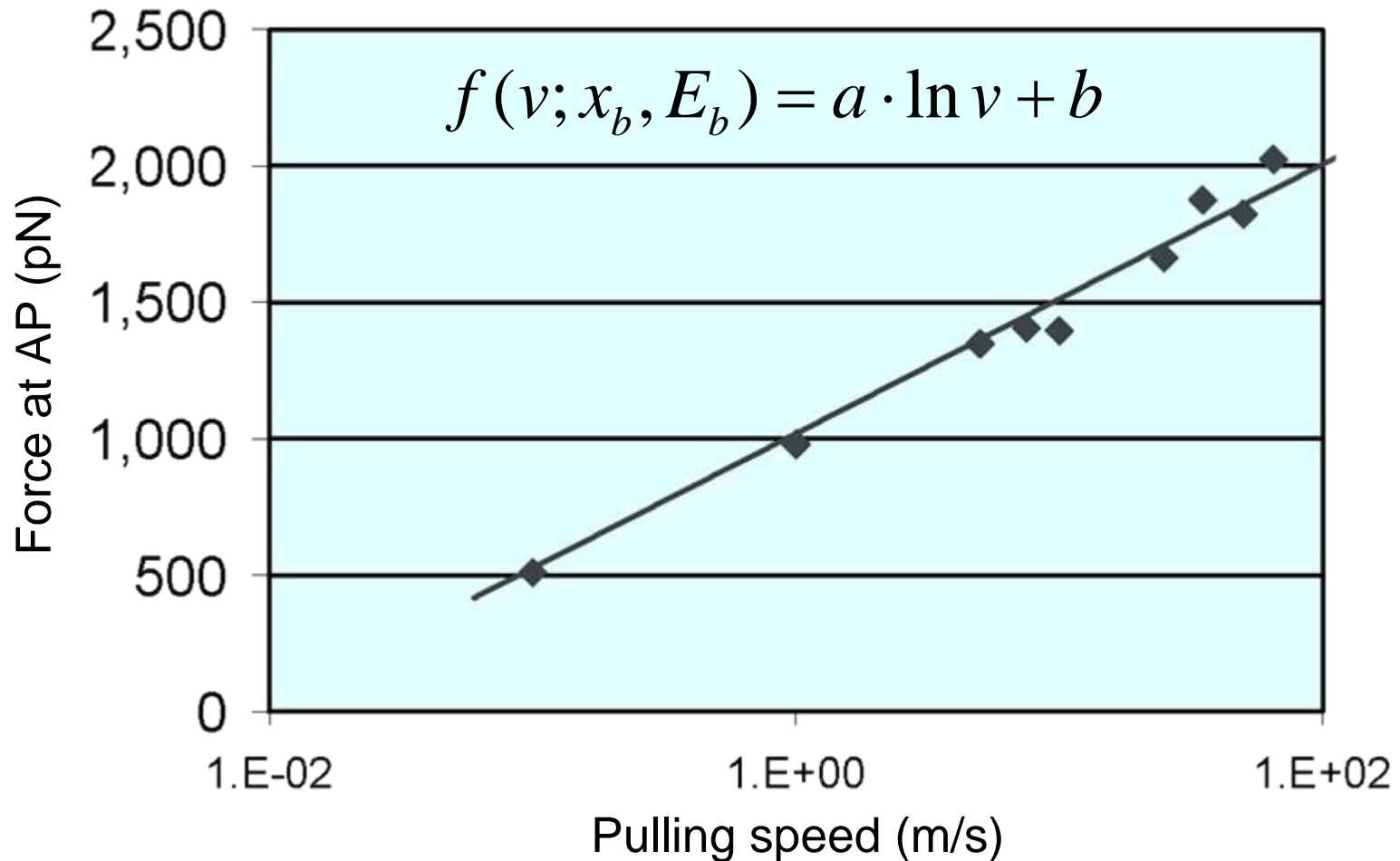
Results in:

$$f(v; x_b, E_b) = \frac{k_b \cdot T}{x_b} \cdot \ln v - \frac{k_b \cdot T}{x_b} \cdot \ln v_0 = a \cdot \ln v + b$$

$$a = \frac{k_B \cdot T}{x_b}$$

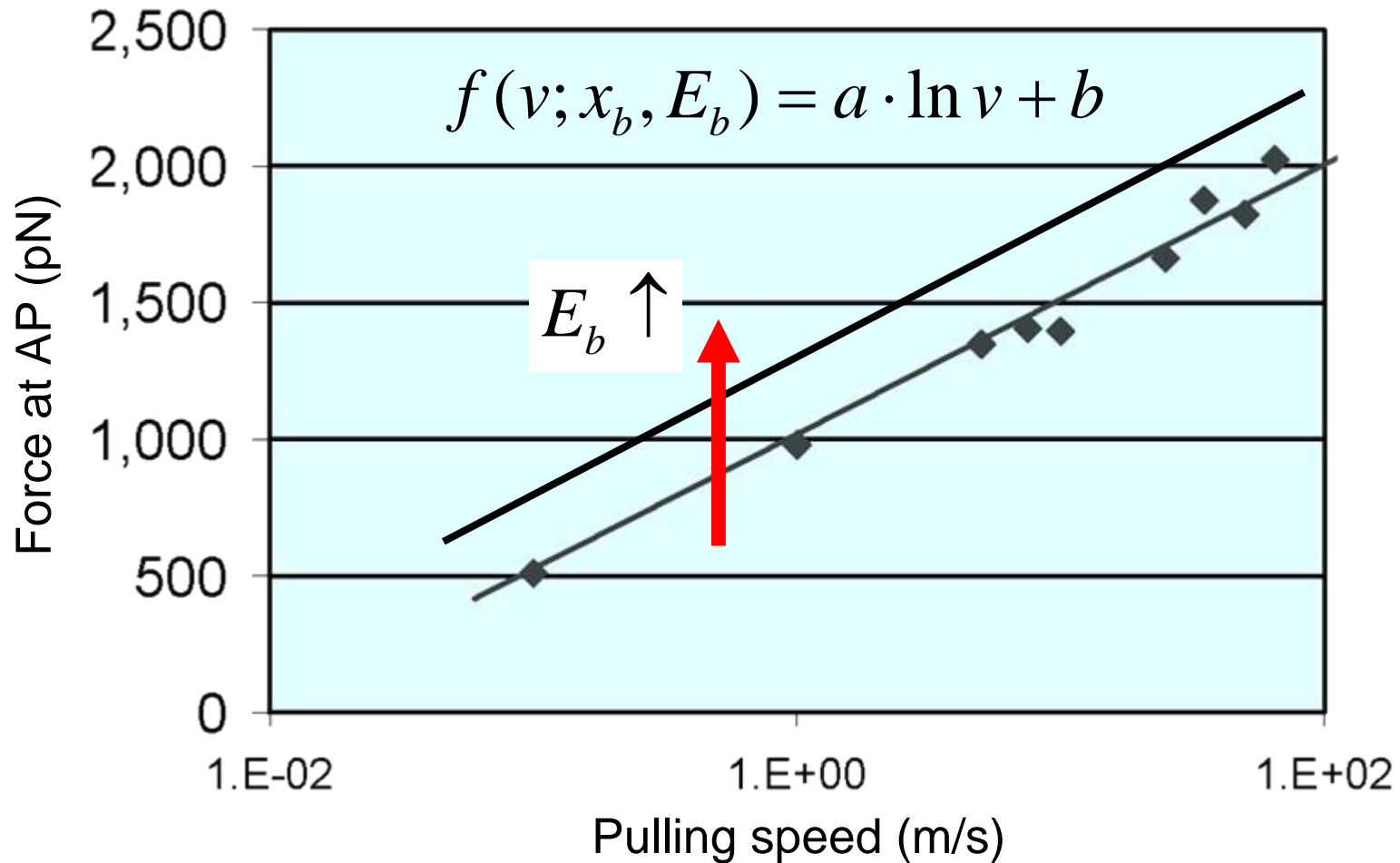
$$b = -\frac{k_B \cdot T}{x_b} \cdot \ln v_0$$

$f \sim \ln v$ behavior of strength



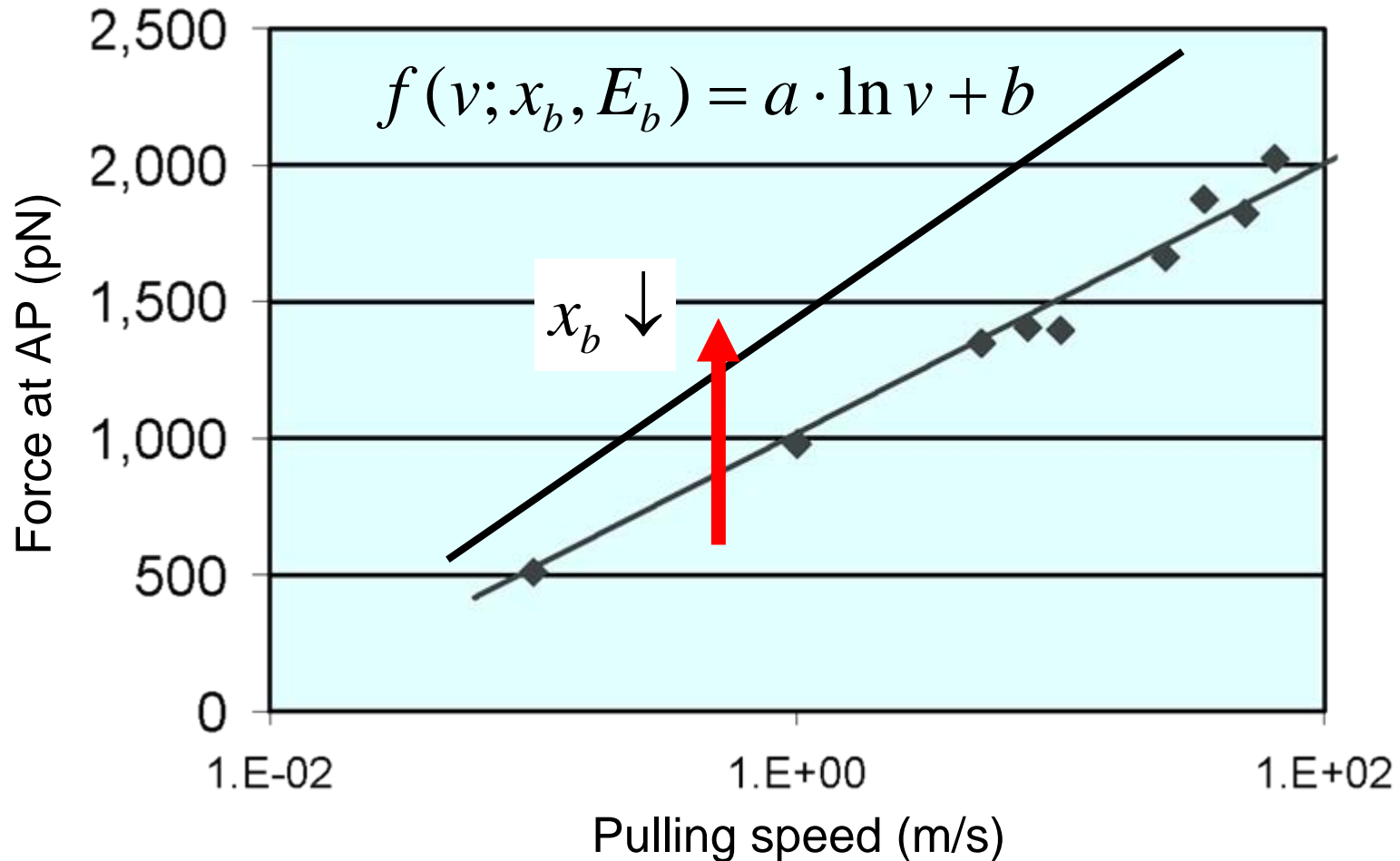
$E_b = 5.6$ kcal/mol and $x_b = 0.17 \text{ \AA}$ (results obtained from fitting to the simulation data)

Scaling with E_b : shifts curve



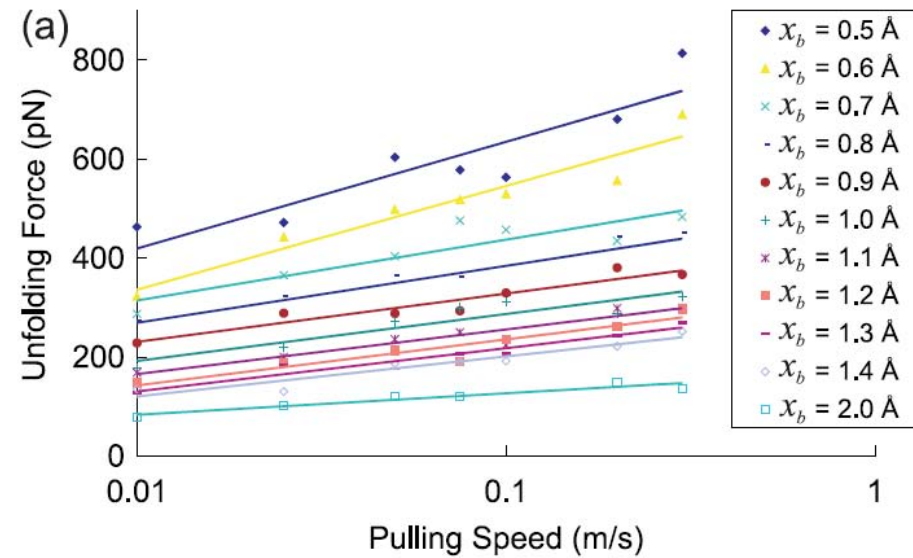
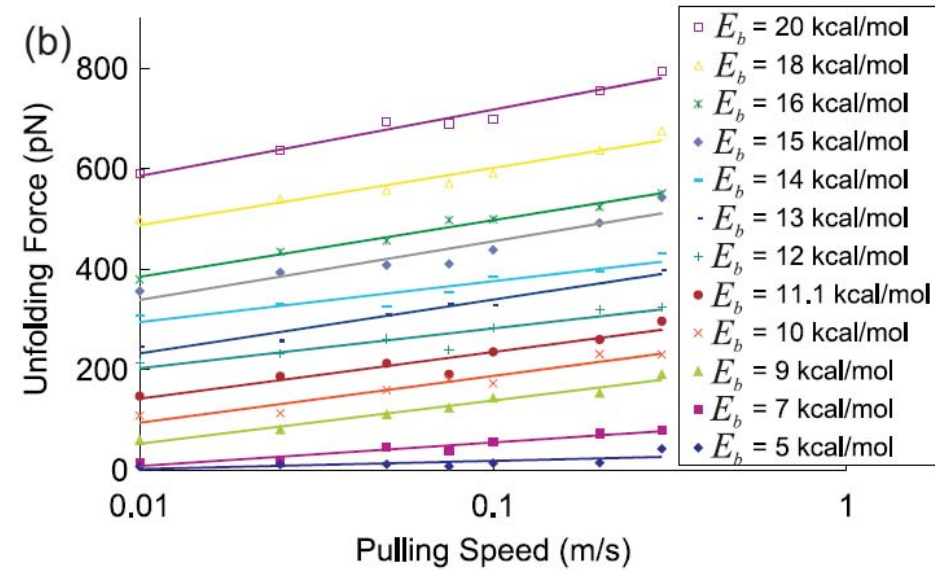
$$a = \frac{k_B \cdot T}{x_b} \quad b = -\frac{k_B \cdot T}{x_b} \cdot \ln v_0 \quad v_0 = \omega_0 \cdot x_b \cdot \exp\left(-\frac{E_b}{k_b \cdot T}\right)$$

Scaling with x_b : changes slope

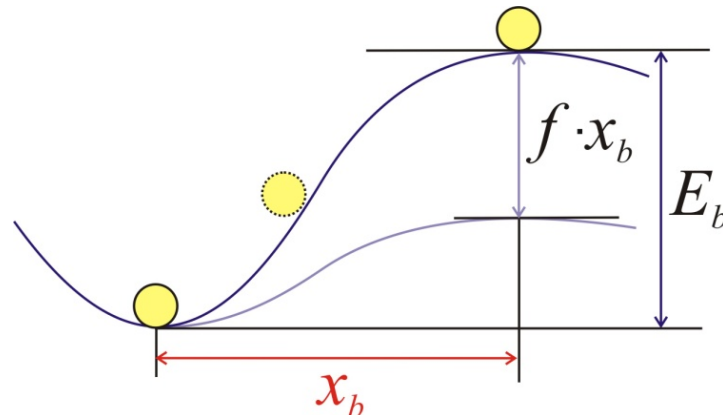


$$a = \frac{k_B \cdot T}{x_b} \quad b = -\frac{k_B \cdot T}{x_b} \cdot \ln v_0 \quad v_0 = \omega_0 \cdot x_b \cdot \exp\left(-\frac{E_b}{k_b \cdot T_{78}}\right)$$

Simulation results



Courtesy of IOP Publishing, Inc. Used with permission. Source: Fig. 3 from Bertaud, J., Hester, J. et al. "Energy Landscape, Structure and Rate Effects on Strength Properties of Alpha-helical Proteins." *J Phys.: Condens. Matter* 22 (2010): 035102. doi:10.1088/0953-8984/22/3/035102.

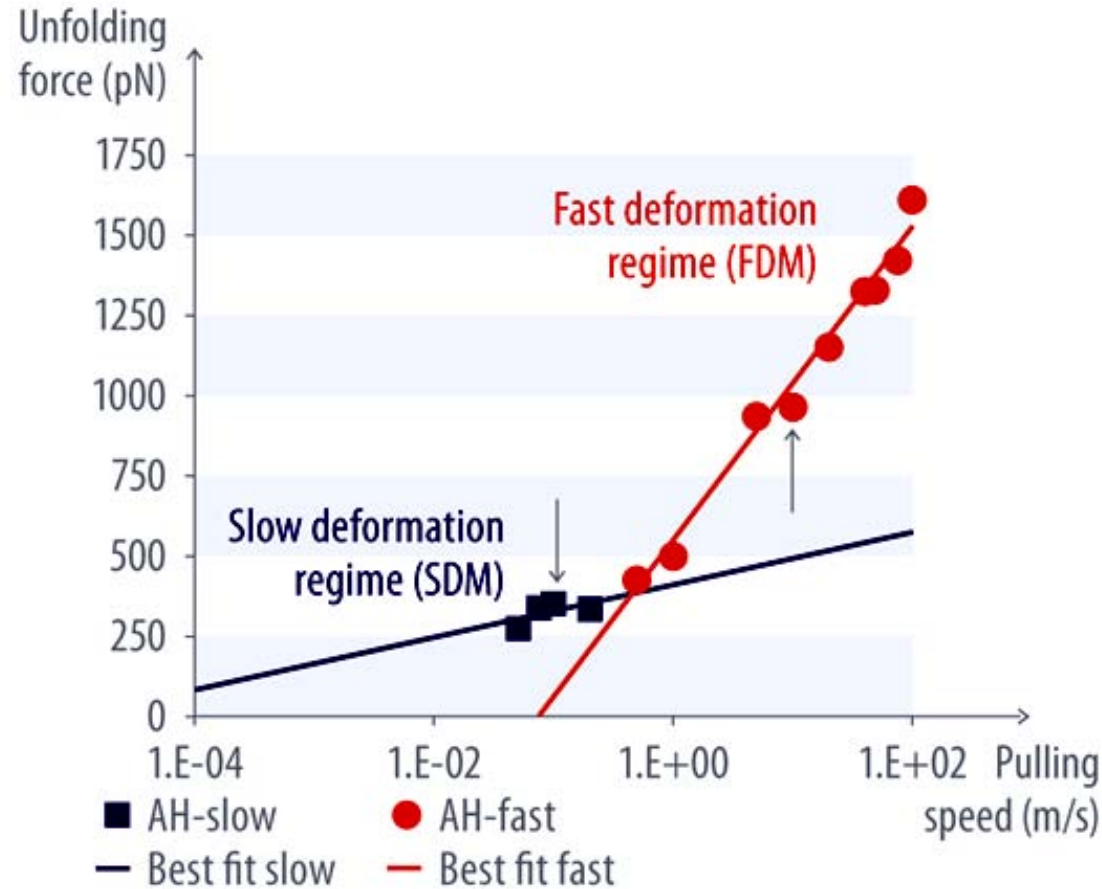


*Mechanisms associated with protein
fracture*

Change in fracture mechanism



Single AH structure



FDM: Sequential HB breaking

SDM: Concurrent HB breaking (3..5 HBs)

Simulation span: 250 ns
Reaches deformation speed O(cm/sec)

Courtesy of National Academy of Sciences, U. S. A. Used with permission. Source: Ackbarow, Theodor, et al. "Hierarchies, Multiple Energy Barriers, and Robustness Govern the Fracture Mechanics of Alpha-helical and Beta-sheet Protein Domains." *PNAS* 104 (October 16, 2007): 16410-5. Copyright 2007 National Academy of Sciences, U.S.A.

Analysis of energy landscape parameters

Table 1. Summary of the differences between the SDM and FDM, for AH1, AH2, and BS

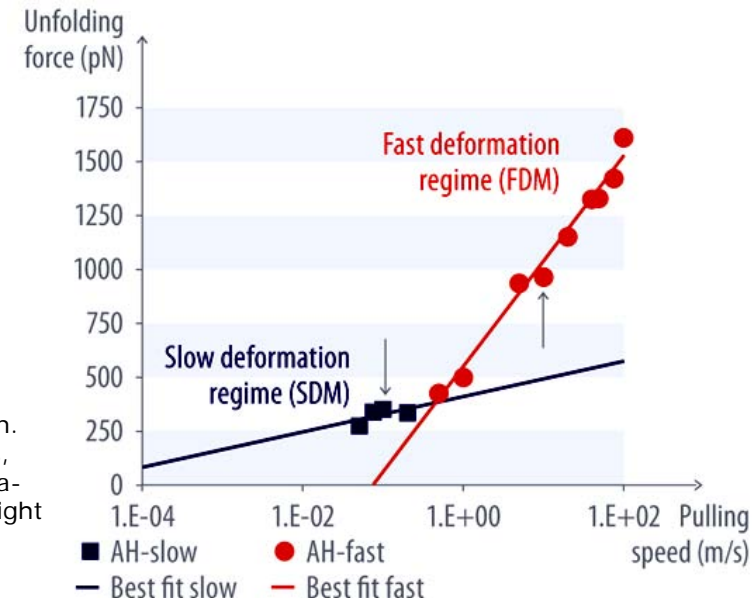
Parameter	AH1 (AH2) domain		BS domain	
	SDM	FDM	SDM	FDM
Pulling speed, m/s	$v < 0.4$ (4)	$v > 0.4$ (4)	$v < 10$	$v > 10$
Unfolding force, pN	$F < 350$ (400)	$F > 350$ (400)	$F < 4,800$	$F > 4,800$
E_b , kcal/mol	11.1 (9.11)	4.87 (3.08)	11.08	1.82
x_b , Å	1.2 (1.19)	0.2 (0.11)	0.138	0.019
HB-breaking mechanism	Simultaneous	Sequential	Simultaneous	Sequential

The values in parentheses in the AH columns represent the results for AH2.

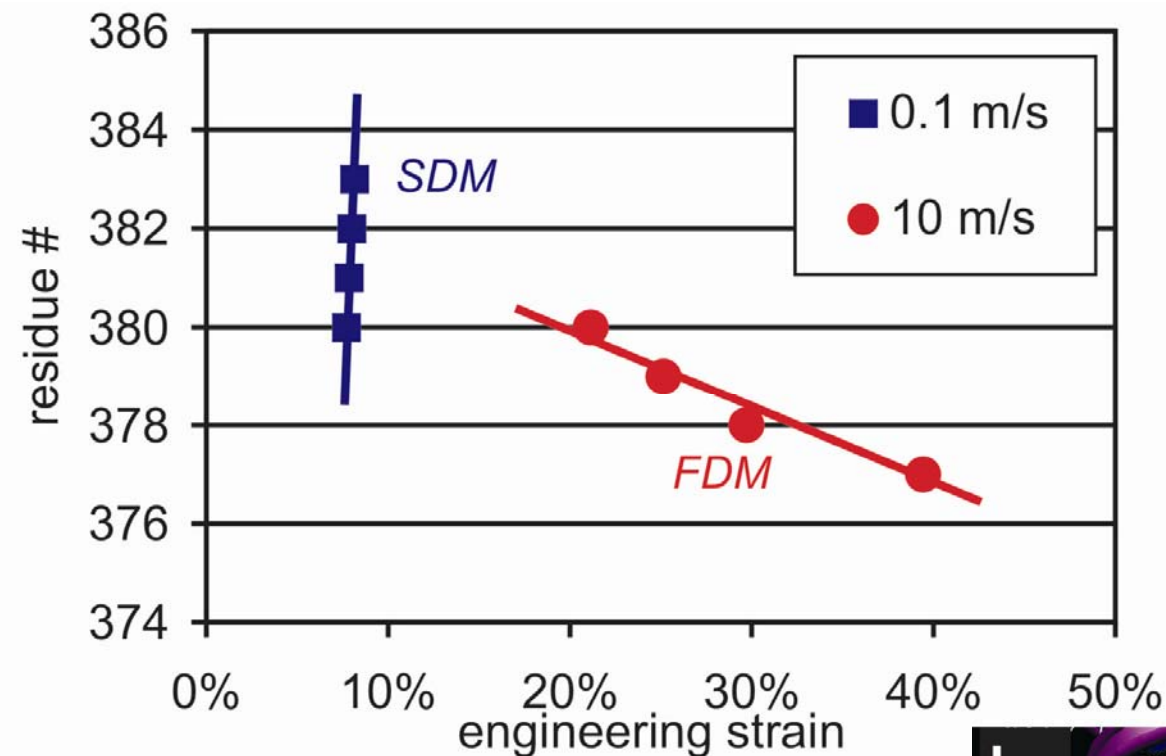
Energy single H-bond: $\approx 3-4$ kcal/mol

What does this mean???

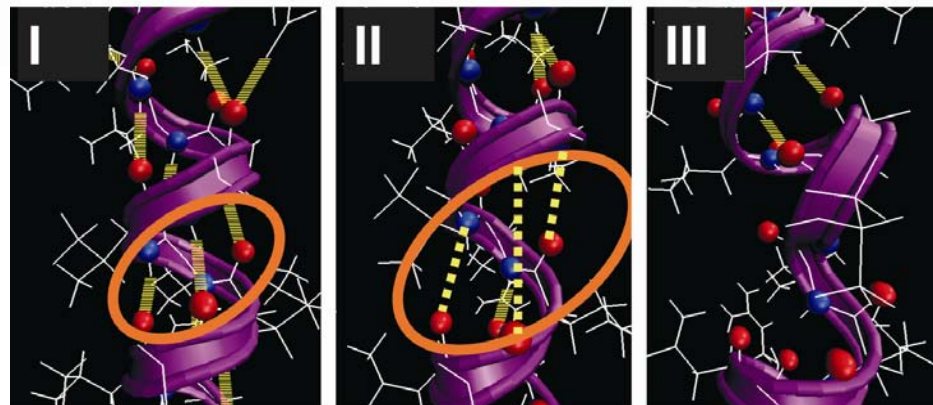
Courtesy of National Academy of Sciences, U. S. A. Used with permission. Source: Ackbarow, Theodor, et al. "Hierarchies, Multiple Energy Barriers, and Robustness Govern the Fracture Mechanics of Alpha-helical and Beta-sheet Protein Domains." *PNAS* 104 (October 16, 2007): 16410-5. Copyright 2007 National Academy of Sciences, U.S.A.



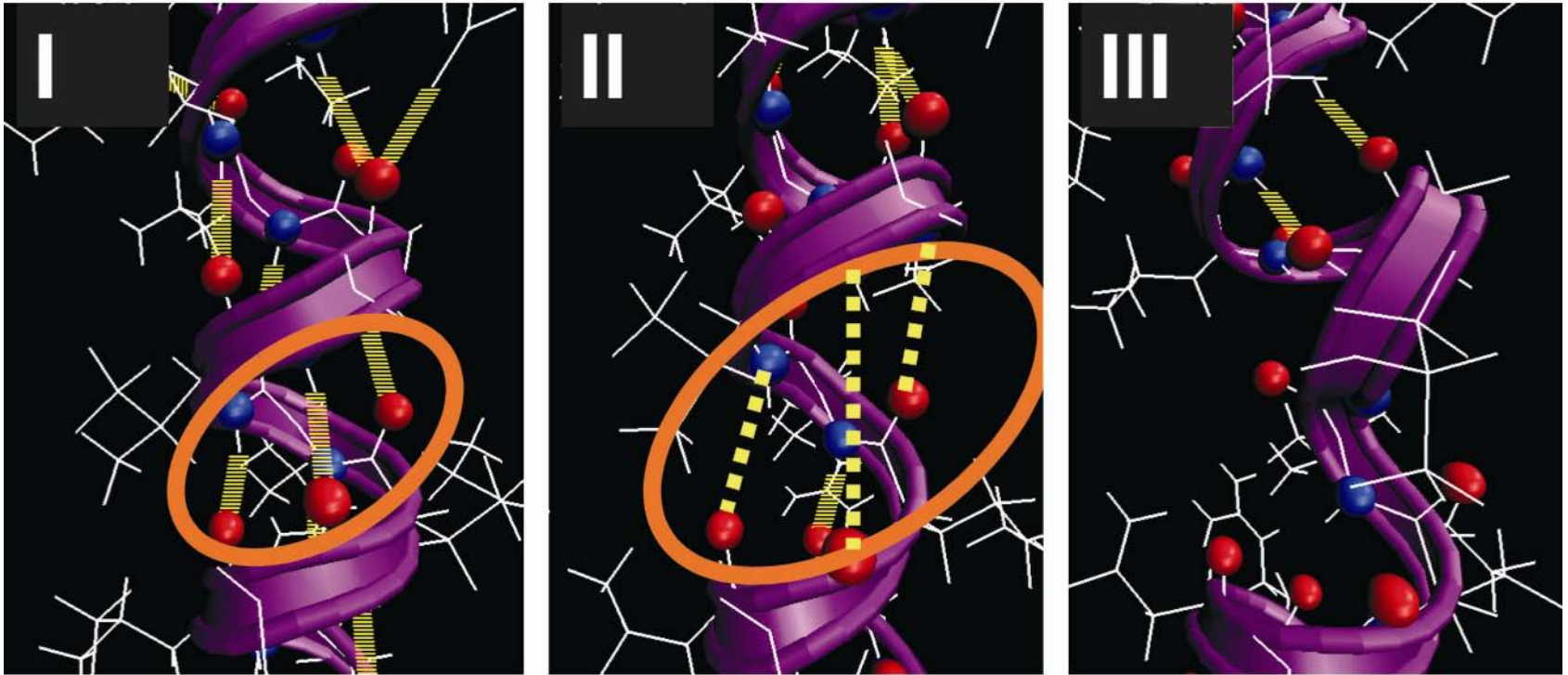
H-bond rupture dynamics: mechanism



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Source: Ackbarow, Theodor, et al. "Hierarchies, Multiple Energy Barriers, and Robustness Govern the Fracture Mechanics of Alpha-helical and Beta-sheet Protein Domains." *PNAS* 104 (October 16, 2007): 16410-5. Copyright 2007 National Academy of Sciences, U.S.A.



H-bond rupture dynamics: mechanism



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Source: Ackbarow, Theodor, et al. "Hierarchies, Multiple Energy Barriers, and Robustness Govern the Fracture Mechanics of Alpha-helical and Beta-sheet Protein Domains." *PNAS* 104 (October 16, 2007): 16410-15.
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I: All HBs are intact

II: Rupture of 3 HBs – simultaneously; **within $\tau \approx 20$ ps**

III: Rest of the AH relaxes – slower deformation...

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3.021J / 1.021J / 10.333J / 18.361J / 22.00J Introduction to Modeling and Simulation
Spring 2012

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