

H^{SO} + H^{Zeeman}
Coupled vs. Uncoupled Basis Sets

Last time:

matrices for $\mathbf{J}_2, \mathbf{J}_+, \mathbf{J}_-, \mathbf{J}_z, \mathbf{J}_x, \mathbf{J}_y$ in $|jm_j\rangle$ basis for $J = 0, \frac{1}{2}, 1$

Pauli spin $\frac{1}{2}$ matrices

arbitrary 2×2 matrix $M = a_0 I + \vec{a}_1 \cdot \vec{\sigma}$ decomposed as scalar plus vector.

When \mathbf{M} is $\rho \rightarrow$ visualization via fictitious vector in fictitious B-field.

When \mathbf{M} is a term in $\mathbf{H} \rightarrow$ idea that arbitrary operator can be decomposed as a sum of the terms that behave like components of $J = 0, J = 1, J = 2 \dots$ This leads to spherical tensor algebra.

types of operators

aJ	e.g. magnetic moment (a is a known constant or a function of r)
\vec{q}	how to evaluate matrix elements (e.g. Stark Effect)
$\mathbf{J}_1 \cdot \mathbf{J}_2$	e.g. Spin-Orbit

Special simplification of Trace (\mathbf{AH})

For example

$$\mathbf{A} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad \mathbf{H} = \begin{pmatrix} H_{11} & H_{12} & H_{13} \\ H_{21} & H_{22} & H_{23} \\ H_{31} & H_{32} & H_{33} \end{pmatrix}$$

$$\mathbf{AH} = \begin{pmatrix} H_{21} & H_{22} & H_{23} \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \begin{array}{l} \text{simpler} \\ \text{extreme simplification!} \end{array}$$

Trace(\mathbf{AH}) = H_{21}

\mathbf{A}_{12} picks out only \mathbf{H}_{21} , \mathbf{A}_{21} picks out only \mathbf{H}_{12} .

Extreme labor saving trick!

TODAY:

1. $H^{SO} + H^{Zeeman}$ as illustrative
2. Dimension of two basis sets, $|JLSM_J\rangle$ and $|LM_LSM_S\rangle$, is the same
3. matrix elements of H^{SO} in both basis sets
4. matrix elements of H^{Zeeman} in both basis sets
5. ladder operators and orthogonality for transformation between basis sets. Necessary to be able to evaluate matrix elements of H^{Zeeman} in “coupled basis”. Why? Because coupled basis set does not explicitly reveal the effects of L_z or S_z .

Nos. 3, 4 and 5 will be repeated in Lecture #26.

Suppose we have 2 kinds of angular momenta, which can be coupled to each other to form a *total* angular momentum.

$$\left. \begin{array}{l} \vec{L} \quad \text{orbital} \\ \vec{S} \quad \text{spin} \end{array} \right\} \text{ operate on different coordinates or in different vector spaces}$$

$$\vec{J} = \vec{L} + \vec{S} \quad \text{total}$$

The components of L, S , and J each follow the standard angular momentum definition commutation rule, but, in addition

$$[\vec{L}, \vec{S}] = 0, \quad [J_i, L_j] = i\hbar \sum_k \epsilon_{ijk} L_k$$

$$[J_i, S_j] = i\hbar \sum_k \epsilon_{ijk} S_k.$$

These commutation rules specify that L and S act like vectors with respect to J but as scalars with respect to each other.

$$\begin{aligned} \vec{J} &\rightarrow |jm_j\rangle \\ \vec{L} &\rightarrow |\ell m_\ell\rangle \\ \vec{S} &\rightarrow |sm_s\rangle \end{aligned}$$

Coupled $|j\ell sm_j\rangle$ vs. uncoupled $|\ell m_\ell\rangle |sm_s\rangle$ representations.

- * matrix elements of certain operators are more convenient in one basis set than the other
- * a unitary transformation between basis sets must exist
- * limiting cases for energy level patterns
(and Zeeman tuning rates and intensities for transitions into eigenstates)
 - ← assignment
 - ← determination of key parameters, structure, and dynamics

$$\begin{aligned}
 & \text{matrix elements of } \ell \text{ and } \mathbf{s} \\
 & \text{will each give a factor of } \hbar \\
 1. \quad & \left[\begin{aligned}
 H^{SO} &= \xi(r) \ell \cdot \mathbf{s} \equiv \frac{\zeta_{nl}}{\hbar} \ell \cdot \mathbf{s} \\
 H^{Zeeman} &= -\gamma B_z (\ell_z + 2s_z) \equiv -(\omega_0) (\ell_z + 2s_z)
 \end{aligned} \right. \\
 & \text{each will give a factor of } \hbar \\
 & \text{anomalous g - value of } e^- \\
 & (\zeta_{nl} \text{ and } \omega_0 \text{ are in units of rad/s})
 \end{aligned}$$

* evaluate matrix elements in both basis sets

* look at energy levels and their Zeeman tuning rate in *high field* $|\gamma B_z| \gg \zeta_{nl}$ limit

* and in *low field* $|\gamma B_z| \ll \zeta_{nl}$ limit

Notation: $\left\{ \begin{array}{l} \text{lower case for } 1e^- \text{ atom angular momenta} \\ \text{upper case for many } -e^- \text{ angular momenta} \end{array} \right.$

two different CSCOs

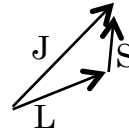
- | | | | | |
|----|--|-----------------------|---|---|
| a) | $H^{\text{elect}}, J^2, J_z, L^2, S^2$ | coupled basis | } | recall tensor product states and "entanglement" |
| | $ nJLSM_J\rangle$ | (can't be factored) | | |
| b) | $H^{\text{elect}}, L^2, L_z, S^2, S_z$ | uncoupled basis | } | |
| | $ nLM_L\rangle SM_S\rangle$ | (explicitly factored) | | |

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2. Coupled and Uncoupled Basis Sets have the same dimension

COUPLED $\vec{J} = \vec{L} + \vec{S}$ $|L - S| \leq J \leq L + S$
 each J has $2J + 1$ M_J 's



every term in this sum has $2L + 1$ and there are $2S + 1$ of them. The second term shows that the $S, S-1, \dots, -S$ terms in sum all cancel.

	<u>Dimension</u>	
}	$J = L + S$	$2(L + S) + 1$
	$L + S - 1$	$2(L + S - 1) + 1$
	$L + S - 2$	$2(L + S - 2) + 1$

	$ L - S $	$2(L - S) + 1$

Every allowed value of J contributes $2L + 1$ to sum. How many allowed values of J are there?
 If $L > S$, there are $2S + 1$ terms in sum.

$$(2S + 1)(2L + 1) + \underbrace{2[S + (S - 1) + \dots + (-S)]}_{= 0} = \underbrace{(2S + 1)(2L + 1)}_{\uparrow}$$

total dimension of basis set for specified L and S

UNCOUPLED $\underbrace{LM_L}_{2L+1} \underbrace{SM_S}_{2S+1}$ total dimension $(2L + 1)(2S + 1)$ again

There is a term by term correspondence between the 2 basis sets \therefore a transformation must exist:

Coupled basis state in terms of uncoupled basis states:

$$|JLSM_J\rangle = \sum_{M_L} a_{M_L} |LM_L\rangle \underbrace{|SM_S = M_J - M_L\rangle}_{\text{constraint}}$$

Trade J, M_J for M_L, M_S , but $M_J = M_L + M_S$.

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Going in the opposite direction: express uncoupled basis state in terms of coupled basis states:

$$\text{OR } |LM_L\rangle |SM_S\rangle = \sum_{J=|L-S|}^{L+S} b_J \left| JLS \underbrace{M_J = M_L + M_S}_{\text{constraint}} \right\rangle$$

3. Matrix elements of $H^{SO} = \frac{\zeta_{nl}}{\hbar} \ell \cdot s$

A. Coupled Representation

$$\vec{J} = \vec{L} + \vec{S} \quad \mathbf{J}^2 = \mathbf{L}^2 + \mathbf{S}^2 + 2\mathbf{L} \cdot \mathbf{S} \quad \begin{array}{l} \text{L and S commute because} \\ \text{they operate in different} \\ \text{vector spaces} \end{array}$$

$$\mathbf{L} \cdot \mathbf{S} = \frac{\mathbf{J}^2 - \mathbf{L}^2 - \mathbf{S}^2}{2} \quad \text{(useful trick!)}$$

$$\langle J'L'S'M_J | \mathbf{L} \cdot \mathbf{S} | JLSM_J \rangle = (\hbar^2/2) [J(J+1) - L(L+1) - S(S+1)] \delta_{J'J} \delta_{L'L} \delta_{S'S} \delta_{M_J'M_J}$$

an entirely diagonal matrix.

B. Uncoupled Representation: work out all of the matrix elements.

$$\mathbf{L} \cdot \mathbf{S} = \mathbf{L}_z \mathbf{S}_z + \frac{1}{2}(\mathbf{L}_+ \mathbf{S}_- + \mathbf{L}_- \mathbf{S}_+): \begin{array}{l} \text{diagonal} \quad \text{off-diagonal} \end{array} \quad \begin{array}{l} \text{because } \mathbf{L}_+ \mathbf{S}_- + \mathbf{L}_- \mathbf{S}_+ = (\mathbf{L}_x + i\mathbf{L}_y)(\mathbf{S}_x - i\mathbf{S}_y) \\ + (\mathbf{L}_x - i\mathbf{L}_y)(\mathbf{S}_x + i\mathbf{S}_y) = 2(\mathbf{L}_x \mathbf{S}_x + \mathbf{L}_y \mathbf{S}_y) \end{array}$$

$$\begin{array}{l} \langle L'M'_L S'M'_S | \mathbf{L} \cdot \mathbf{S} | LM_L SM_S \rangle = \hbar^2 \delta_{L'L} \delta_{S'S} \times \\ \left\{ \begin{array}{l} \boxed{\text{can't change L}} \uparrow \quad \boxed{\text{can't change S}} \uparrow \\ [M_L M_S \delta_{M'_L M_L} \delta_{M'_S M_S}] + \frac{1}{2} [L(L+1) - M'_L M_L]^{1/2} \times \\ [S(S+1) - M'_S M_S]^{1/2} \delta_{M'_L M_L \pm 1} \times \delta_{M'_S M_S \mp 1} \end{array} \right\} \quad \Delta M_L = -\Delta M_S = 0, \pm 1 \end{array}$$

Non-Lecture notes for evaluated matrices

$$S = 1/2,$$

$$L = 0, 1, 2$$

$$\boxed{{}^2S, {}^2P, {}^2D \text{ states}}$$

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NONLECTURE for H^{SO} : COUPLED BASIS

$^{2S+1}L_J$

$^2S_{1/2}$ $H_{COUPLED}^{SO} = \frac{\hbar}{2} \zeta_{ns}(0) = 0$ a 1×1 matrix with matrix element = 0

$^2P_{1/2 \text{ \& } 3/2}$ $H_{COUPLED}^{SO} = \frac{\hbar}{2} \zeta_{np}$

-2	0	0	0	0	0	$J = 1/2$ (2×2)
0	-2	0	0	0	0	
0	0	1	0	0	0	$J = 3/2$ (4×4)
0	0	0	1	0	0	
0	0	0	0	1	0	
0	0	0	0	0	1	

	L	J	$J(J+1)$	$-L(L+1)$	$-S(S+1)$	$=$
$(^2S_{1/2})$	0	1/2	3/4	0	-3/4	0
$(^2P_{1/2})$	1	1/2	3/4	-2	-3/4	-2
$(^2P_{3/2})$	1	3/2	15/4	-2	-3/4	+1
$(^2D_{3/2})$	2	3/2	15/4	-6	-3/4	-3
$(^2D_{5/2})$	2	5/2	35/4	-6	-3/4	+2

$J = 3/2$

$^2D_{\frac{3}{2} \text{ and } \frac{5}{2}}$ $H_{COUPLED}^{SO} = \frac{\hbar}{2} \zeta_{nd}$

-3	0	0	0	0	0	0	0	0	0	(4×4)
0	-3	0	0	0	0	0	0	0	0	
0	0	-3	0	0	0	0	0	0	0	
0	0	0	-3	0	0	0	0	0	0	
0	0	0	0	2	0	0	0	0	0	(6×6)
0	0	0	0	0	2	0	0	0	0	
0	0	0	0	0	0	2	0	0	0	
0	0	0	0	0	0	0	2	0	0	
0	0	0	0	0	0	0	0	2	0	
0	0	0	0	0	0	0	0	0	2	

$J = 5/2$

center of gravity rule: trace of matrix = 0
(obeyed for all *scalar* terms in \mathbf{H})

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^{2S+1}L NONLECTURE for H^{SO} : **UNCOUPLED BASIS**

2S $H_{UNCOUPLED}^{SO} = \hbar\zeta_{ns}(1/2 \cdot 0) = (0)$ (1×1)

2P $H_{UNCOUPLED}^{SO} = \hbar\zeta_{np} \times$

M_J	M_L	M_S							
3/2	1	1/2	1/2	0	0	0	0	0	0
1/2	1	-1/2	0	-1/2	$2^{-1/2}$	0	0	0	0
1/2	0	1/2	0	$2^{-1/2}$	0	0	0	0	0
-1/2	0	-1/2	0	0	0	0	$2^{-1/2}$	0	0
-1/2	-1	1/2	0	0	0	$2^{-1/2}$	-1/2	0	0
-3/2	-1	-1/2	0	0	0	0	0	0	1/2

Each box along main diagonal is for one value of $M_J = M_L + M_S$.

2D $H_{UNCOUPLED}^{SO} = \hbar\zeta_{nd} \times$

M_J	M_L	M_S										
5/2	2	1/2	1	0	0	0	0	0	0	0	0	0
3/2	2	-1/2	0	-1	1	0	0	0	0	0	0	0
3/2	1	1/2	0	1	1/2	0	0	0	0	0	0	0
1/2	1	-1/2	0	0	0	-1/2	$(3/2)^{1/2}$	0	0	0	0	0
1/2	0	1/2	0	0	0	$(3/2)^{1/2}$	0	0	0	0	0	0
-1/2	0	-1/2	0	0	0	0	0	0	$(3/2)^{1/2}$	0	0	0
-1/2	-1	1/2	0	0	0	0	0	$(3/2)^{1/2}$	-1/2	0	0	0
-3/2	-1	-1/2	0	0	0	0	0	0	0	1/2	1	0
-3/2	-2	1/2	0	0	0	0	0	0	0	1	-1	0
-5/2	-2	-1/2	0	0	0	0	0	0	0	0	0	1

End of Non-Lecture

4. Matrix Elements of $\mathbf{H}^{\text{Zeeman}} = -\gamma B_z (\mathbf{L}_z + 2\mathbf{S}_z)$

A. Very easy in uncoupled representation

$$\begin{aligned} H_{\text{uncoupled}}^{\text{Zeeman}} &= -\gamma B_z \langle L'M'_L S'M'_S | L_z + 2S_z | LM_L SM_S \rangle \\ &= -\gamma B_z \hbar (M_L + 2M_S) \delta_{L'L} \delta_{S'S} \delta_{M'_L M_L} \delta_{M'_S M_S} \end{aligned}$$

strictly diagonal

B. Coupled representation

$$\mathbf{L}_z + 2\mathbf{S}_z = \underbrace{\mathbf{J}_z}_{\text{easy}} + \underbrace{\mathbf{S}_z}_{\text{hard}} \text{ — no clue!}$$

can't evaluate matrix elements in coupled representation without a new trick, discussed in item #5

5. If we wish to work in *coupled* representation, because it diagonalizes \mathbf{H}^{SO} , we need to find the transformation between coupled and uncoupled representations.

$$|JLSM_J\rangle = \sum_{M_L} a_{M_L} |LM_L SM_S = M_J - M_L\rangle$$

lengthy procedure: use $J_{\pm} = L_{\pm} + S_{\pm}$ and orthogonality

Always start with an extreme M_L, M_S basis state, where we are assured of a trivial 1 to 1 correspondence between basis sets:

$$\begin{aligned} M_L = L, \quad M_S = S, \quad M_J = M_L + M_S = L + S, \quad J = L + S \\ |J = L + S \quad LSM_J = L + S\rangle = |LM_L = L \quad SM_S = S\rangle \\ \text{coupled} \qquad \qquad \qquad \text{uncoupled} \end{aligned}$$

Now the fun begins ...

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Apply \mathbf{J}_- to both sides of the equation:

$$\mathbf{J}_- \left| \overbrace{L+S}^J \overbrace{LS}^{\quad} \overbrace{L+S}^{M_J} \right\rangle = (\mathbf{L}_- + \mathbf{S}_-) |LM_L = L \quad SM_S = S\rangle$$

$$\begin{bmatrix} (L+S)(L+S+1) \\ -(L+S)(L+S-1) \end{bmatrix}^{1/2} |L+S \quad LS \quad L+S-1\rangle = [L(L+1) - L(L-1)]^{1/2} |LL-1SS\rangle$$

$$+ [S(S+1) - S(S-1)]^{1/2} |LLSS-1\rangle$$

Thus we have derived an equality between one coupled basis state and a specific linear combination of two uncoupled basis states.

There is only one other orthogonal linear combination that belongs to the same value of $M_L + M_S = M_J$: it must belong to the $\underbrace{|L+S-1 \quad LS \quad L+S-1\rangle}_{\text{lowered } J}$ basis state.

NONLECTURE

Work this out for 2P using $\mathbf{J}^- = \mathbf{L}^- + \mathbf{S}^-$

$$|JLSM_J\rangle = |3/2 \quad 1 \quad 1/2 \quad 3/2\rangle = |LM_L SM_S\rangle = |1 \quad 1 \quad 1/2 \quad 1/2\rangle$$

$$|JLSM_J - 1\rangle = \frac{2^{1/2} |1 \quad 0 \quad 1/2 \quad 1/2\rangle + |1 \quad 1 \quad 1/2 \quad -1/2\rangle}{3^{1/2}}$$

now use orthogonality:

$$|J-1LSM_J - 1\rangle = |1/2 \quad 1 \quad 1/2 \quad 1/2\rangle = \frac{-|1 \quad 0 \quad 1/2 \quad 1/2\rangle + 2^{1/2} |1 \quad 1 \quad 1/2 \quad -1/2\rangle}{3^{1/2}}$$

Continue laddering down to get all four $J = 3/2$ and all two $J = 1/2$ basis states.

$$|3/2 \quad 1 \quad 1/2 \quad -1/2\rangle = \left(\frac{2}{3}\right)^{1/2} |1 \quad 0 \quad 1/2 \quad -1/2\rangle + \left(\frac{1}{3}\right)^{1/2} |1 \quad -1 \quad 1/2 \quad 1/2\rangle$$

$$|3/2 \quad 1 \quad 1/2 \quad -3/2\rangle = |1 \quad -1 \quad 1/2 \quad -1/2\rangle$$

$$|1/2 \quad 1 \quad 1/2 \quad 1/2\rangle = -\left(\frac{1}{3}\right)^{1/2} |1 \quad 0 \quad 1/2 \quad -1/2\rangle + \left(\frac{2}{3}\right)^{1/2} |1 \quad -1 \quad 1/2 \quad 1/2\rangle$$

You work out the transformation for 2D !

Next step will be to evaluate $\mathbf{H}^{\text{SO}} + \mathbf{H}^{\text{Zeeman}}$ in both coupled and uncoupled basis sets and look for limiting behavior.

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