

Lecture 21: Variance Reduction Methods and Sensitivity Analysis

Today's Topics

1. Bootstrapping
2. Variance reduction methods
3. Importance sampling
4. Sensitivity analysis

1. Bootstrapping

- How do we get estimates of the standard errors in our estimators that don't have known distributions? e.g., in our estimate for the variance.

2. Variance Reduction Methods

- used to increase the accuracy of the Monte Carlo estimates that can be obtained for a given number of iterations
- "tricks" to make our MCS more "statistically efficient"
 - more accuracy for a given number of samples, or fewer samples to achieve a given level of accuracy
- variance reduction methods: importance sampling, antithetic sampling, control variates, stratified sampling

3. Importance Sampling

- a general technique for estimating properties of one distribution while only having samples generated from another (different) distribution

3.1 Importance sampling general idea

→ A technique for estimating properties of one distribution while only having samples generated from another (different) distribution

Consider random variable X , pdf $f_X(x)$

$$\mu_X \equiv E_X[X] = \int x f_X(x) dx$$

↑ denotes expectation
under f_X

Choose a random variable $Z \geq 0$

$$\text{s.t. } E_X[Z] = 1 = \int z \underbrace{f_X(x)}_{f_Z(x)} dx$$

3.1 Importance sampling general idea

Then $\mu_x = E_x[X] = \int x f_x(x) dx$

$$= \int \frac{x}{z} z f_x(x) dx$$
$$= \int \frac{x}{z} f_z(x) dx = E_z \left[\frac{x}{z} \right] \quad \text{---}$$

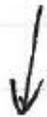
3.1 Importance sampling general idea

We have

$$E_x [X] = E_z \left[\frac{X}{z} \right]$$

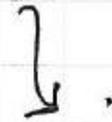


sample x under $f_x(x)$



estimator variance is

$$\frac{\text{var}_x [X]}{N}$$



sample $\frac{x}{z}$ under $f_z(x)$



estimator variance is

$$\frac{\text{var}_z \left[\frac{X}{z} \right]}{N}$$

3.1 Importance sampling general idea

We have

$$E_X [X] = E_Z \left[\frac{X}{Z} \right]$$

sample x under $f_X(x)$

sample $\frac{x}{z}$ under $f_Z(x)$

estimator variance is
$$\frac{\text{Var}_X [X]}{N}$$

estimator variance is
$$\frac{\text{Var}_Z \left[\frac{X}{Z} \right]}{N}$$

- Some values of X in our MCS have more impact on the parameter being estimated (here μ_X) than others
- If "important" values are emphasized by sampling more frequently, then estimator variance can be reduced
- Key is to choose an appropriate "biasing distribution"
→ good choice means we can decrease N for same accuracy

3.2 Importance sampling for probability estimation

We saw $P\{A\}$ is estimated via MCS with $\hat{p}(A)$.

Consider A is the event $y > y_{\text{limit}}$ (eg. prob. of failure)

Define indicator function $I(A_i) = \begin{cases} 1, & y_i > y_{\text{limit}} \\ 0, & y_i \leq y_{\text{limit}} \end{cases}$
↑ sample i

$$\text{then } \hat{p}(A) = \frac{1}{N} \sum_{i=1}^N I(A_i)$$

$$\text{and } E[\hat{p}(A)] = P\{A\} \quad (\text{unbiased})$$

$$\text{var}[\hat{p}(A)] = \frac{P\{A\}(1 - P\{A\})}{N}$$

3.2 Importance sampling for probability estimation

Introduce pdf $w(x)$ (alternative pdf
→ called "biasing density" for x)

→ choose $w(x)$ so that event A occurs more frequently

$$\begin{aligned} \text{Then } P\{A\} &= E_x[I(A)] = \int I(A) f(x) dx \\ &= \int I(A) \frac{f(x)}{w(x)} w(x) dx \end{aligned}$$

$$= E_w \left[I(A) \frac{f(x)}{w(x)} \right]$$

↑
draw
from pdf
 $w(x)$

↑ weight by
 $\frac{f(x)}{w(x)}$ to counter

3.2 Importance sampling for probability estimation

Then our MC IS estimator for $P\{A\}$ is

$$\hat{p}_{IS}(A) = \frac{1}{N} \sum_{i=1}^N \mathbb{I}(A_i) \frac{f(x_i)}{w(x_i)} \quad \text{where the } x_i \text{ are drawn from } w(x)$$

Summary: • define $w(x)$

- draw samples ~~from~~ of x from $w(x)$
(idea \rightarrow more samples in region of interest)
- estimate $P\{A\}$, but we need to weight the samples by $\frac{f(x_i)}{w(x_i)}$ to account for the fact that we drew from $w(x)$ not $f(x)$

Then: $E[\hat{p}_{IS}(A)] = P\{A\}$ (unbiased)

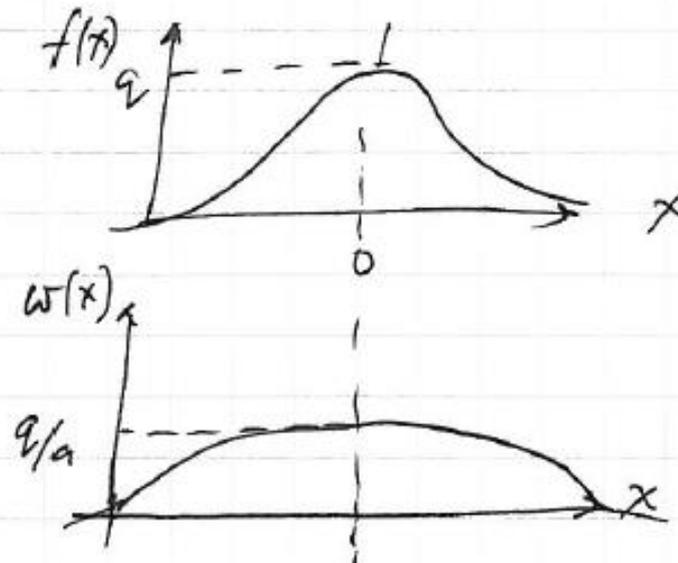
$$\text{var}_w[\hat{p}_{IS}(A)] = \frac{1}{N} \left\{ E\left[\mathbb{I}(A) \frac{f(x)}{w(x)} \right] - (P\{A\})^2 \right\}$$

3.3 How to pick the biasing distribution

Simple approach: scaling to shift probability mass into the event region

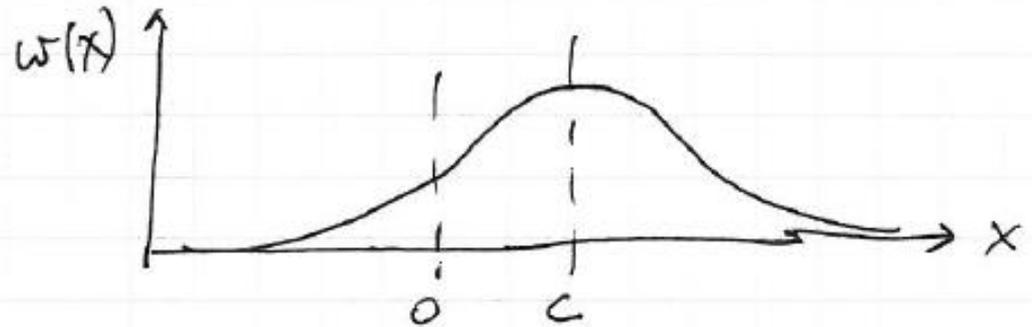
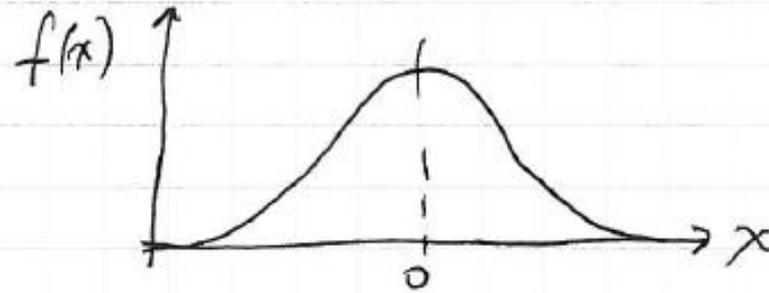
$$w(x) = \frac{1}{a} f\left(\frac{x}{a}\right)$$

$$a > 1$$



3.3 How to pick the biasing distribution

translation: $w(x) = f(x-c)$, $c > 0$ (for $P(X > X_{crit})$)



4. Sensitivity Analysis

- How do we use our MCS results to understand which uncertain inputs are contributing the most to output variability?
 - Important to understand where we should focus our uncertainty reduction efforts (improving manufacturing tolerances, improving models, installing sensors, etc.)
 - factor prioritization
 - Important to understand where there may be uncertainties but they are not important
 - factor fixing

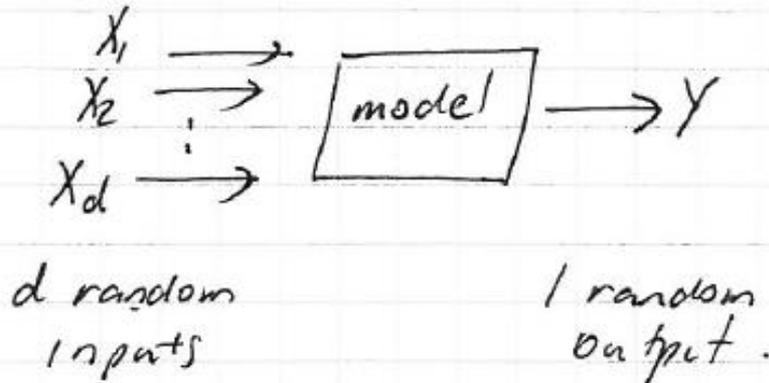
4a. Vary-all-but-one (VABO) MCS

1. Run a MCS with all inputs varying
2. Fix input k to a deterministic value. Rerun the MCS with all inputs except k varying.
3. Compare statistics of the output (e.g., variance of Run #1 to variance of Run #2).

Questions:

- at what value should we fix factor k ?
- would the results be different if we fixed factor k to a different deterministic value?
- what about possible interactions among the inputs?

4b. Global Sensitivity Analysis

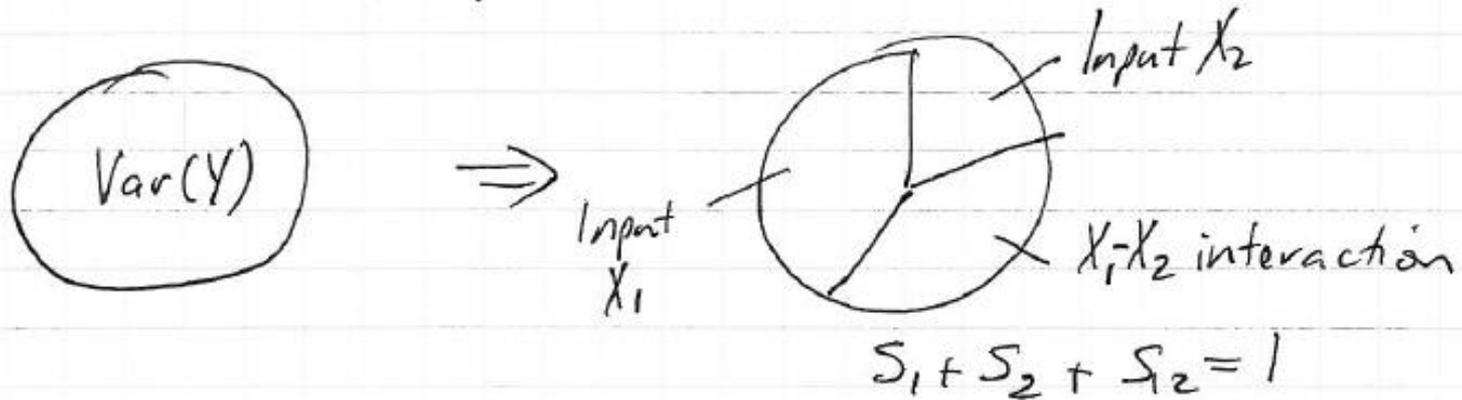


Main effect sensitivity index for input i :
$$S_i = \frac{\text{var}(Y) - E[\text{var}(Y/X_i)]}{\text{var}(Y)}$$

- expected, ^{relative} reduction in output variance if the true value of X_i is learned (expectation over what that true value might be)
- measure of the effect of varying X_i alone, averaged over variations in other inputs

4b. Global Sensitivity Analysis

Also can compute higher-order interaction indices
 S_{ij}, S_{ijk}, \dots etc.



Generally
$$\sum_{i=1}^d S_i + \sum_{i < j} S_{ij} + \dots + S_{12\dots d} = 1$$

Total effect sensitivity index for input i :
$$S_{Ti} = \frac{\text{var}(Y) - E[\text{var}(Y|X_{-i})]}{\text{var}(Y)}$$

→ measures contribution to $\text{var}(Y)$ of X_i
including its main effect and all the interaction effects

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